# **Modicon M340** BMX NOC 0401 Ethernet Communication Module User Manual

05/2015



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When devices are used for applications with technical safety requirements, the relevant instructions must be followed.

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## **Safety Information**

### **Important Information**

#### NOTICE

Read these instructions carefully, and look at the equipment to become familiar with the device before trying to install, operate, or maintain it. The following special messages may appear throughout this documentation or on the equipment to warn of potential hazards or to call attention to information that clarifies or simplifies a procedure.



The addition of this symbol to a "Danger" or "Warning" safety label indicates that an electrical hazard exists which will result in personal injury if the instructions are not followed.



This is the safety alert symbol. It is used to alert you to potential personal injury hazards. Obey all safety messages that follow this symbol to avoid possible injury or death.

## ▲ DANGER

**DANGER** indicates a hazardous situation which, if not avoided, **will result in** death or serious injury.

## A WARNING

**WARNING** indicates a hazardous situation which, if not avoided, **could result in** death or serious injury.

## 

**CAUTION** indicates a hazardous situation which, if not avoided, **could result** in minor or moderate injury.

## NOTICE

NOTICE is used to address practices not related to physical injury.

#### PLEASE NOTE

Electrical equipment should be installed, operated, serviced, and maintained only by qualified personnel. No responsibility is assumed by Schneider Electric for any consequences arising out of the use of this material.

A qualified person is one who has skills and knowledge related to the construction and operation of electrical equipment and its installation, and has received safety training to recognize and avoid the hazards involved.

## **About the Book**

### At a Glance

#### **Document Scope**

This manual describes the use of the Modicon M340 BMX NOC 0401 Ethernet communication module. This manual describes the creation of a complete configuration. The features and functions of the module are described in the course of constructing this configuration.

The specific configuration settings contained in this manual are intended to be used for instructional purposes only. The settings required for your specific configuration ill differ from the examples presented in this manual.

#### **Validity Note**

The module described in this document can requires Unity Pro version 5.0 or later.

#### **Related Documents**

For additional information, refer to the online help files for the Unity Pro software, and to the following technical publications:

Title of Documentation	Reference Number
Advantys STB EtherNet/IP Network Interface Applications Guide	31008204 (English), 31008205
	(French), 31008206 (German),
	31008207 (Spanish), 31008208
	(Italian)

You can download these technical publications and other technical information from our website at www.schneider-electric.com.

## Chapter 1 Installation

#### **Overview**

The Ethernet communication module serves as the interface between a M340 PLC and other Ethernet network devices by means of either the EtherNet/IP or the Modbus TCP communication protocol. This chapter shows you how to install the module by:

- inserting it into a PLC backplane
- connecting it to an Ethernet network
- installing the Unity Pro Ethernet Configuration Tool software

#### What Is in This Chapter?

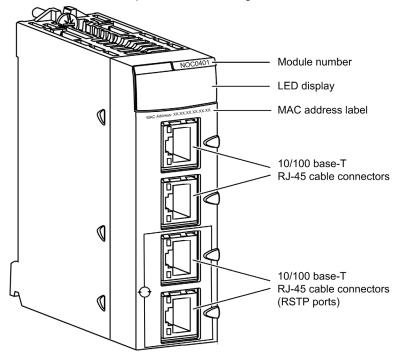
This chapter contains the following topics:

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## Physical Description of the BMX NOC 0401 Module

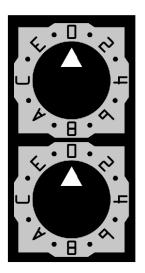
### Front

The front of the module presents the following features:



#### **Rotary Switches**

The back of the BMX NOC 0401 presents two rotary switches, which you can use to specify how the module will obtain its IP address.

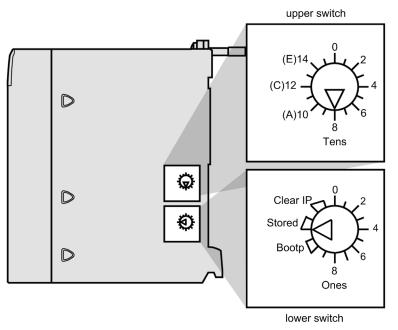


The settings of these two rotary switches work together to specify the source of the module's IP address, as follows:

Setting	Description		
Upper switch	Upper switch:		
09	Tens value (0, 10, 2090) for the device name setting. It is added to the ones value on the lower switch to identify the module to a DHCP server.		
AF	Tens value (100, 200, 300150) for the device name setting. It is added to the ones value on the lower switch to identify the module to a DHCP server.		
Lower switch:			
09	Ones value (0, 1, 29) for the device name setting. It is added to the tens value on the upper switch to identify the module to a DHCP server.		
A + B	BootP <sup>1</sup> :The module obtains its IP address from a BootP server.		
C + D	Stored <sup>1</sup> : The module uses the IP address configured in the application.		
E + F	Clear IP <sup>1</sup> : The module applies its default IP address.		
1. The lower switch alone determines module behavior. The upper switch is ignored.			

#### **Switch Labels**

The right side of the module displays two labels explaining the choice of rotary switch settings, as depicted below.



#### LEDs

The BMX NOC 0401 communication module presents the following LED indicators:

- RUN (running)
- ERR (detected error)
- MS (module status)
- NS (network status)
- ETH STS (Ethernet status)

In addition, each Ethernet port presents the following two LED indicators:

- LNK (link)
- ACT (activity)

For a description of these LEDs, and how to use them to diagnose the communication module, refer to the topic LED Indicators for the Ethernet Communication Module (see page 324).

### **Module Specifications**

#### **Specifications**

BMX NOC 0401 specifications include:

Ports		
Communication Ports	Four auto-sensing 10/100Base-T shielded twisted pair (RJ-45 connector) ports.	
Electrical		
Bus Current Required	@3.3V: 550 mA	
Power Dissipation	1.9 W	
Fuse	None	
Operating Conditions		
Temperature	060° C	
Humidity	095% Rh non-condensing @ 60° C	
Altitude	2000 m (6561.68 ft)	
Storage Conditions		
Temperature	-40+85° C	
Humidity	095% Rh non-condensing @ 60° C	
Altitude	3000 m (9842.52 ft) transport	

#### Software Compatibility

The Ethernet communication module is compatible with Unity Pro programming software version 5.0 and later.

#### Standards

The Ethernet communication module complies with the following standards:

- UL 508
- CSA 22.2-142
- CSA 22.2-213
- CE
- EMI EN55011
- EN61131-2
- IEC61131-2
- IEEE 802.3 2002
- ODVA

#### **Communication Modules per Station**

The maximum number of communication modules — including but not limited to BMX NOC 0401 Ethernet communication modules — you can install in a single station is determined by the CPU serving that station

CPU	Maximum Number of Communication Modules per Station
BMX P34 1000	2
BMX P34 2000	3
BMX P34 2010	3
BMX P34 20102	3
BMX P34 2020	3
BMX P34 2030	3
BMX P34 20302	3

**NOTE:** If you use the embedded Ethernet port with the BMX P34 2···· copro, the maximum number of communication modules per station is 2.

### **Communication Specifications**

#### Introduction

The following specifications describe both the I/O communication and the explicit messaging capacities of the BMX NOC 0401.

#### I/O Communication Specifications

The Ethernet communication module presents the following I/O communication features:

Communication type	Feature	Capacity
EtherNet/IP (CIP Implicit Messaging)	Scanner	
	Maximum number of devices	128 devices (125 devices as scanner + 3 devices as adapter) shared with Modbus TCP
	Maximum message size	512 bytes
	Adapter	
	Maximum number of instances	3 adapter instances
	Maximum number of connections	2 connections per instance
	Maximum message size	511 bytes including header
	Inputs	505 bytes excluding header
	Outputs	509 bytes excluding header
Modbus TCP	Maximum number of registers	
(Modbus Scanner)	Read	125 registers
	Write	120 registers
	Maximum number of devices	128 devices shared with EtherNet/IP
	Maximum message size	
	Read	250 bytes (125 words) excluding header
	Write	240 bytes (120 words) excluding header

### **Explicit Messaging Specifications**

The Ethernet communication module presents the following explicit messaging features:

Communication type	Feature	Capacity	
EtherNet/IP	Client		
(CIP Explicit Messaging)	Maximum number of simultaneous connections	16 connections	
	Maximum number of concurrent requests	16 requests, shared with Modbus TCP	
	Server		
	Maximum number of simultaneous connections	32 connections	
	Maximum messaging size	1023 bytes	
Modbus TCP	Client		
(Modbus Scanner)	Maximum number of simultaneous connections	16 connections	
	Maximum number of concurrent requests	16 requests, shared with EtherNet/IP	
	Server		
	Maximum number of simultaneous requests	128 requests	
	Maximum number of simultaneous connections	32 connections	
	Maximum message size		
	Read	250 bytes (125 words) excluding header	
	Write	240 bytes (120 words) excluding header	

### Mounting the BMX NOC 0401 Module

#### **Tools Required**

One medium sized (size 2) Phillips-head screw driver.

#### Mounting the Module

The module can be mounted in any of the racks of the Modicon M340 system. It can be installed in any available slot (except in the offset X Bus racks). To mount the communication module:

Step	Action	Illustration
1	Position the locating pins (situated at the bottom part of the rear of the module) in the corresponding slots.	
2	Swivel the module upwards toward the top of the rack, so that the back of the module sits flush with the rack. <b>NOTE:</b> Before positioning the pins, remove the pins protective cover.	
3	Tighten the screw to hold the module in place on the rack. <b>NOTE:</b> The tightening torque is 1.5 N.m (13.3 lb-in).	

#### Wiring

## **WARNING**

#### HAZARD OF ELECTRICAL SHOCK OR BURN

Connect the ground wire to the protective ground (PE) terminal before you establish any further connections. When you remove connections, disconnect the ground wire last. The Ethernet cable shield must be connected to PE ground at the Ethernet switch.

Failure to follow these instructions can result in death, serious injury, or equipment damage.

The Ethernet communication module communicates over an industrial Ethernet network through any one of four RJ45 connectors located on the front of the module.

- Use the top two ports (ports 1 and 2) to connect to end devices.
- Use the bottom two ports (ports 3 and 4)—which support the RSTP redundancy protocol—to connect to the local area networks, for example, a ring.

### Installing Unity Pro Ethernet Configuration Tool Software

#### **Overview**

Accessing Unity Pro Configuration Tool Software depends on the version of Unity Pro that you are using:

- Unity Pro version 6.0 and higher: The module configuration software is already included in the Unity Pro installation.
- Unity Pro version 5.0: You need to install the Unity Pro Ethernet Configuration Tool software, which you can obtain from the following website: http://www.global-download.schneiderelectric.com/8525773E00058BDC/all/DA00A87B8BB30386852577940058D66C

#### Installing Unity Pro Ethernet Configuration Tool Software for Unity Pro Version 5.0

To install this software, navigate to navigate to the root of the installation files and run the file **Setup.exe**.

The setup process displays the following setup screens:

Step	Screen	Description
1	Welcome	Click Next to continue.
2	ReadMe and Release Notes Display	Indicate whether to display the ReadMe file. Click <b>Next</b> to continue.
3	ReadMe	(Optional) Displays the ReadMe file, if selected above. Click <b>Next</b> to continue.
4	License Agreement	Displays the software license. Select I accept, then click Next to continue.
5	Customer Information	<ul> <li>Enter the following data:</li> <li>your first and last names</li> <li>company name</li> <li>identify for whom the software is installed: <ul> <li>anyone who uses this computer</li> <li>only for yourself</li> </ul> </li> </ul>
6	Destination Folder	Click <b>Next</b> to continue. Identify where the application will be installed. Either: • Accept the default path • Click <b>Change</b> and specify a new path
		Click Next to continue.
7	Ready to Install	Click Next to continue.
8	Status	Progress bar indicates the status of the installation. When complete, click <b>Next</b> to continue.
9	Install Complete	Click Finish.

The installation process described above copies the following objects to your PC:

- the Unity Pro Ethernet Configuration Tool
- a Generic EtherNet/IP DTM
- a Generic Modbus TCP DTM

NOTE: A DTM is a small software driver that defines and enables a device.

#### **Updating Hardware Catalog**

For installations of Unity Pro version 5.0 and higher, the next step is to update the **Hardware Catalog**. Updating the **Hardware Catalog** adds your new Ethernet communication module to the list of available modules and devices that you can add to your Unity Pro application.

Refer to the topic Updating the Unity Pro Hardware Catalog (see page 129) for step-by-step instructions.

## **UnInstalling the Ethernet Configuration Tool**

#### Introduction

Use the **Add or Remove Programs** utility provided by the Windows<sup>™</sup> operating system to uninstall the Unity Pro Ethernet Configuration Tool.

To completely uninstall the Ethernet Configuration Tool, remove each of the following three DTMs, one at a time:

Generic EtherNet/IP DTM



Generic Modbus TCP DTM

Unity Pro Ethernet Configuration Tool

#### **Un-Installing Ethernet Configuration Tool DTMs**

To remove the three Ethernet Configuration Tool DTMs:

Step	Action
1	Open the Windows Control Panel: Start
2	In the Control Panel, double click on Add or Remove Programs.
3	In the Add or Remove Programs window, select the Change or Remove Programs page.
4	Select the first of the three DTMs to remove (for example, the <b>Generic EtherNet/IP DTM</b> ), then click <b>Remove</b> .
5	Repeat step 4 for each of the remaining 2 DTMs: <b>Generic Modbus DTM</b> and <b>Unity Pro Ethernet Configuration Tool</b> .

Installation

## **Chapter 2** Configuring the Ethernet Communication Module

#### **Overview**

This chapter shows you how to use Unity Pro programming software to select and configure the Ethernet communication module.

**NOTE:** The instructions presented in this chapter include specific choices made for a sample project. Your Unity Pro project may include different choices that are appropriate for your specific configuration.

#### What Is in This Chapter?

This chapter contains the following sections:

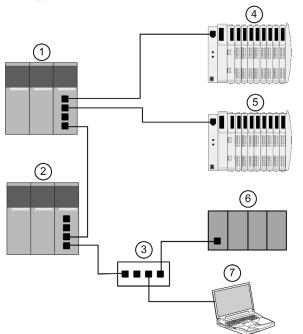
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## Section 2.1 Ethernet Network Configuration Example

### The Ethernet Network Example

#### **The Ethernet Network**

This manual describes the creation of a complete Ethernet network configuration for the following topology:



- 1 Primary PLC incorporating the BMX NOC 0401 Ethernet communication module
- 2 A secondary PLC that "listens" to the scan of the primary PLC local slave by the third-party scanner
- 3 Ethernet managed switch
- 4 Advantys STB island, with an STB NIC 2212 EtherNet/IP network interface module plus 8 I/O modules
- 5 Advantys STB island, with an STB NIP 2212 Modbus TCP network interface module plus 8 I/O modules
- 6 Third-party PLC that scans a local slave in the primary PLC (1)
- 7 PC equipped with both Unity Pro configuration software (upgraded with the Ethernet Configuration Tool that ships with the BMX NOC 0401 Ethernet communication module) and Advantys configuration software, used to configure communication settings for Ethernet communication module in the primary PLC (1) and the remote network interface modules on the STB I/O islands (4 and 5)

#### Multiple Roles of the PLC and Ethernet Communication Module

The PLC, and in particular the BMX NOC 0401 Ethernet communication module, can be configured to simultaneously perform multiple roles with respect to other network devices. In this sample network, you will learn how to configure the communication module to operate as:

- a scanner of devices that use the EtherNet/IP (4) and the Modbus TCP (5) protocols
- an adapter—also known as a local slave—that produces output data that both the remote thirdparty PLC (6) and secondary PLC (2) can read as input data
- a DHCP server that provides IP address settings to other devices on the Ethernet network
- an FDR server that provides operational settings to devices on the Ethernet network that also receive their IP address from the DHCP server, above

## Section 2.2 Creating a Project in Unity Pro

#### **Overview**

This section shows you how to add modules—including the BMX NOC 0401 Ethernet communication module—to your project, using Unity Pro.

#### What Is in This Section?

This section contains the following topics:

Торіс	Page
Creating a Project in Unity Pro	
Configuring the Size and Location of Inputs and Outputs	

### **Creating a Project in Unity Pro**

#### Introduction

This topic shows you how to create a new Unity Pro project, and add to the new project the following components:

- a CPU
- a power supply
- a BMX NOC 0401 Ethernet communication module

NOTE: The following example uses Unity Pro version 7.0, or higher.

#### **Creating and Saving a New Unity Pro Project**

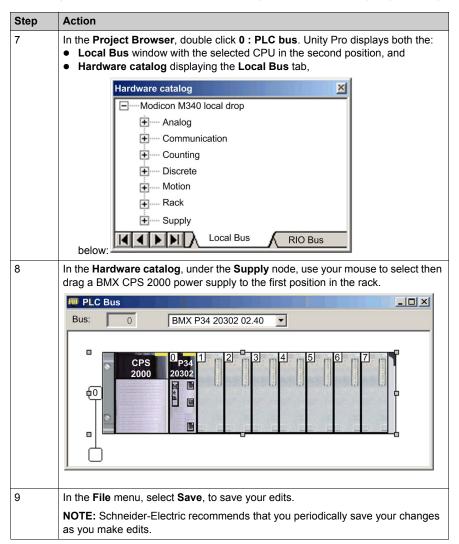
Use Unity Pro to create a new project. The following steps describe the creation of a project for the sample network:

Action			
Open Unity Pro.			
-			controller
In the New Project w	indow, expa	nd the Modicon M340 node to select	a CPU.
New Project			×
Show all versions			ОК
PLC	Min OS Ver	Description	Cancel
Modicon M340			
BMX CRA 31200	01.00	Ethernet Remote IO head for M340 platform	Help
BMX CRA 31210	01.00	Ethernet Remote IO head for M340 platform	
	02.00		
Quantum			
	Open Unity Pro. In the Unity Pro main The New Project win types. In the New Project w New Project Show all versions PLC Modicon M340 BMX CRA 31200	Open Unity Pro.         In the Unity Pro main menu, select         The New Project window opens of types.         In the New Project window, expanding         New Project         Show all versions         PLC       Min OS Ver         Modicon M340         BMX CRA 31200       01.00         BMX CRA 31210       01.00         BMX P34 1000       02.40         BMX P34 2010       02.00         BMX P34 2010       02.00         BMX P34 2030       02.00         BMX P34 2030       02.00         BMX P34 2030       02.40         BMX P34 2030       02.40	Open Unity Pro.         In the Unity Pro main menu, select File →New         The New Project window opens displaying a list of Schneider-Electric types.         In the New Project window, expand the Modicon M340 node to select         New Project         Show all versions         PLC       Min OS Ver         Modicon M340         BMX CRA 31200       01.00         Ethernet Remote IO head for M340 platform         BMX CRA 31210       01.00         Ethernet Remote IO head for M340 platform         BMX CRA 31210       02.00         CPU 340-20 Modbus         BMX P34 1000       02.40         CPU 340-20 Modbus         BMX P34 2010       02.00         BMX P34 2010       02.00         BMX P34 2020       02.40         CPU 340-20 Modbus CANopen         BMX P34 2020       02.40         CPU 340-20 Ethernet CANopen         BMX P34 2030       02.00         BMX P34 2030       02.00         BMX P34 2030       02.00         CPU 340-20 Ethernet CANopen         BMX P34 00100       02.30         BMX P34 00100       02.30         BMX PA 0100       02.30         BMX PA 0100       02.30

Step	Action	
4	Click <b>OK</b> . Unity Pro displays the <b>Project Browser</b> , below.	
	Project Browser	
5	To save the project, select File →Save. The Save As dialog opens.	
6	In the <b>Save As</b> dialog, type in a <b>File name</b> —which will be the name of your Unity Pro project—then click <b>Save</b> . Unity Pro saves your project to the specified path location.	
	<ul> <li>NOTE: You can change the default location Unity Pro uses to store project file Before saving your project:</li> <li>1 Select Tools →Options. The Options Management window opens.</li> <li>2 In the left pane, navigate to Options →General →Paths.</li> <li>3 In the right pane, type in a new path location for the Project path. You can a edit the: <ul> <li>Import/Export file path</li> <li>XVM path</li> <li>Project settings templates path</li> </ul> </li> </ul>	
	4 Click <b>OK</b> close the window and save your path edits.	

#### Adding a Power Supply to the New Unity Pro Project

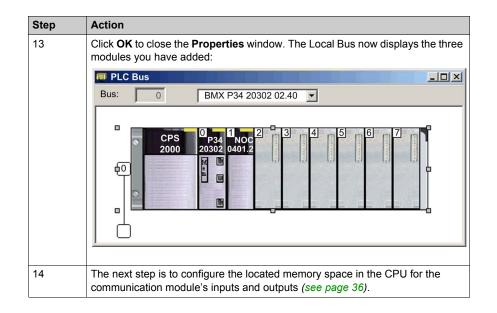
When you added the CPU to the project, above, Unity Pro may also have added a power supply to the project. If not, the next step is to manually add a power supply to your Unity Pro project:



### Adding an Ethernet Communication Module to the New Unity Pro Project

Next, add an Ethernet communication module to your project:

Step	Action	
10	Returning to the <b>Hardware catalog</b> , under the <b>Communication</b> node, use your mouse to select then drag a <b>BMX NOC 0401.2</b> Ethernet communication module to an open slot in the rack—in this example, slot 2.	
	<ul> <li>NOTE: You can select the BMX NOC 0401.2 only after:</li> <li>selecting the BMX P34 20302 CPU for the project, and</li> <li>upgrading the BMX NOC 0401 module firmware to version 2.0 or higher</li> </ul>	
	When you drop the communication module into the rack, Unity Pro opens the communication module <b>Properties</b> window.	
11	In the <b>General</b> page of the module properties window, type in an alias name for the communication module: <b>NOC01</b> :	
	Properties of	
	General       Device Information       DTM Information       Protocol Information         DTM name management       Alias name:       NOC01         Tag name:	
	OK Cancel Help	
	When you change the alias name, Unity Pro changes the base input and output type and variable names to match the edited alias name. <b>NOTE:</b> Schneider Electric recommends that you assign a unique alias name to each communication module. This practice helps you distinguish between modules of the same type.	
12	In the File menu, select Save, to save your edits.	



### Configuring the Size and Location of Inputs and Outputs

#### Overview

Use the **Configuration** page of the Ethernet communication module's **Properties** window to configure:

- the size and starting position of inputs
- the size and starting position of outputs

The following steps present one example of how to configure the size and location of inputs and outputs. Your own project configuration may differ.

#### Setting Input and Output Memory Addresses and Naming the Module

The **Properties** window opens when you double-click the left mouse button on the image of the BMX NOC 0401 communication module in either the **Local Bus** window, or the **Project Browser**.

When you select the **Configuration** page, it displays the network, or Alias, name. This is the name assigned to the network channel when the communication module was added to the project.

Use the **Configuration** page to edit the communication module inputs and outputs, as follows:

0.1 : BMX NOC 0401			
Ethernet 4 Port 10/100 RJ45			
Configuration			
Project Network name:	M_NOC0401		
MW Index: 0 Max size: 16	Outputs %MW Index: 16 Max size: 16		
EIP connectivity network			

To input the above settings, take the following steps:

Step	Action	
1	In the module's <b>Properties</b> window, select the <b>Configuration</b> page.	
2	Type in the size and starting position of the inputs and outputs, as follows:	
	<ul> <li>In the Inputs area:</li> <li>In the %MW index field, type in a starting address for inputs, in this example: 0.</li> <li>In the Max size field, type in the maximum number of 16-bit words dedicated to inputs, in this example: 16.</li> </ul>	
	<ul> <li>In the Outputs area:</li> <li>In the %MW index field, type in a starting address for outputs, in this example: 16.</li> <li>In the Max size field, type in the maximum number of 16-bit words dedicated to outputs—in this example: 16.</li> </ul>	
	<ul> <li>Notes:</li> <li>Locate the inputs and outputs at the beginning of a 4-byte (or 2 word) range. Because address numbering in the M340 platform is zero-based, verify that %MW index input and output settings are configured to start at an even number.</li> <li>Allocate separate non-overlapping space to inputs and outputs.</li> <li>Unity Pro automatically reserves space for two arrays of 32 bytes, as follows:</li> <li>for connection health bits (see page 204), located at the beginning of the space configured for inputs</li> <li>for connection control bits (see page 208), located at the beginning of the space configured for outputs</li> <li>Confirm that the %MW space assigned for both inputs and outputs is available in the CPU.</li> </ul>	
	For more information, refer to the Unity Pro help file topic <i>Processor Configuration Screen</i> .	
3	In Unity Pro select <b>Edit</b> → <b>Validate</b> (or click the <b>Validate I</b> button) to save the address and size settings for inputs and outputs.	
	<b>NOTE:</b> After you validate module settings for the first time, the module name cannot be edited. If you subsequently decide to change the module name, delete the existing module from the configuration, then add and rename a replacement module.	

#### **Completing the Ethernet Network Configuration**

After configuring settings for inputs and outputs, the next step is to configure the communication module settings beginning with its **Channel Properties** and then configure remote Ethernet network devices (*see page 123*).

**NOTE:** After you input configuration settings for the communication module and remote devices, return to the **Configuration** page of the Ethernet communication module's **Properties** window and click the **Update application** button. This creates derived data type (DDT) variables (see page 198) that display the following information and commands for your Unity Pro project:

- connection health bits, that display the status of each connection
- connection control bits, you can use to toggle each connection on and off
- the value of input and output items
- module and device configuration settings
- free memory space that has been reserved, but not yet allocated

# Section 2.3 The Unity Pro FDT/DTM Interface

#### **Overview**

The section describes the use of DTMs within Unity Pro.

## What Is in This Section?

This section contains the following topics:

Торіс	
DTM Browser	40
DTM Browser Menu Commands	43
Field Bus Discovery Service	49
Device Editor	53
Configuring Properties in the Device Editor	
Uploading and Downloading DTM-Based Applications	

# **DTM Browser**

#### **Overview**

The **DTM Browser** displays a hierarchical list of DTMs—in the form of nodes on a connectivity tree—that have been added to your Unity Pro project. Each DTM node represents an actual module or device in your Ethernet network.

DTM Browser	×
Host PC	
😑 👢 < 192.168.1.4 > NOC01	
EtherNet IP:192.168.1.6>NIC2212_01	
Modbus:192.168.1.7>NIP2212_01	

## **Node Types**

There are 3 types of DTM nodes:

- Communication DTMs:
  - Any COM DTM can be plugged directly under the root node (Host PC) at the 1st level
  - A COM DTM can support Gateway DTMs or Device DTMs as children if their protocols are compatible
- Gateway DTMs:
  - A Gateway DTM can support other Gateway DTMs or Device DTMs as children if their protocols are compatible.
- Device DTMs:
  - A Device DTM does not support any child DTMs

## Node Names

Each DTM has a default name when inserted into the browser. The default name consists of the following elements:

<Channel: Address> Device Name

Where:

Element	Description	
channel	This is the name of the channel communication media, to which the device is plugged in. This name is read from the DTM and is set by the device vendor. Example: EtherNet/IP, Modbus	
address	<ul> <li>The bus address of the device, which can be:</li> <li>The connection point on its parent gateway network</li> <li>The slot number in the modular device parent internal bus</li> <li>Example: the device IP address</li> </ul>	
device name	The default name is determined by the vendor in the device DTM, but can be edited by the user.	

#### **Node Status**

The DTM Browser displays the status of each DTM node in the connectivity tree, as follows:.

Status	Description	
Built / Not-built	A blue check mark v superimposed on a device icon indicates that node, or one of its sub-nodes, is not built. This means that some property of the node has changed, and the information stored in the physical device is no longer consistent with the local project.	
Connected / A connected DTM is denoted in <b>bold</b> text. An unconnected DTM a in plain text.		
	<ul> <li>NOTE:</li> <li>Connecting a DTM to its physical device automatically connects higher level parent nodes up to the root node.</li> <li>Disconnecting a DTM from its physical device automatically disconnects its lower level child nodes.</li> </ul>	
	<b>NOTE:</b> Connecting or disconnecting a DTM to or from its device does not also connect or disconnect Unity Pro to or from the PLC. DTMs can be connected/disconnected while Unity Pro is either offline or online.	
Installed / Not- installed	A red $\mathbf{X}$ superimposed on a device icon indicates the DTM for that device is not installed on the PC.	

## Handling Invalid Nodes

As indicated above, a red X superimposed on a node indicates the DTM for that node is not installed on the PC. To resolve this situation, click the right mouse button on the node to open a pop-up menu with the following two commands:

Command	Description		
Delete	Removes the selected node (and its sub-nodes) from the DTM Browser.		
Properties	Opens the following dialog, which you can use to identify the name of the missing DTM:		
	Properties of NOC01		
	General Device information DTM information Protocol information		
	Name : EIP Master DTM		
	Vendor : Schneider Electric		
	Version : 2.0.7.0		
	FDT version : 1.2.0.0		
	Date : 2012-01-20		
	Component : EIPMasterDTM.DTMCore		
	OK Cancel Apply Help		

# **DTM Browser Menu Commands**

#### **Overview**

The **DTM Browser** includes a pop-up, contextual (right-click) menu that displays commands for the currently selected DTM. The list of available commands consists of:

- universal commands, as determined by the selected node level:
  - host PC node (level 1)
  - communication module node (level 2)
  - remote device node (level 3)
- device-specific commands, as determined by the device DTM

### **Host PC Node Commands**

The Host PC node contextual menu includes the following commands:

Name	Description	
Add <sup>1</sup>	Opens the <b>Add</b> dialog — containing a subset of the <b>Hardware Catalog</b> , allowing the selection of a communication module DTM.	
Check DTM devices <sup>1</sup>	Checks the current project for invalid DTMs or DTMs that are not installed in the PC. If the results of the check include invalid or not-installed DTMs, they are displayed in the <b>User errors</b> tab in the	
	information window and a red $\mathbf{X}$ is superimposed over their icons in the <b>DTM Browser</b> .	
DTM services	Displays the communication DTMs selection, as well as the device topology, their respective IP addresses, and connection state. In this dialog, for each device you can connect, disconnect, load from devices, or store to devices. You can also choose to stop communication or continue activity when detected errors occur.	
DTM hardware catalog		
Expand all <sup>2</sup> Displays every DTM in the project.		
Collapse all <sup>2</sup>	Displays only the communication DTMs in the project.	
<ol> <li>This command also appears in the Unity Pro Edit menu.</li> <li>This command also appears in the Unity Pro View menu.</li> </ol>		

## Communication Module and Remote Device Node Commands

Name	Description	
Open <sup>1</sup>	This opens the <b>Device Editor</b> for the selected communication module.	
	<b>NOTE:</b> Double-clicking the left mouse button on the DTM in the <b>DTM Browser</b> also opens this window.	
Add <sup>1</sup>	This opens the <b>Add</b> dialog, displaying a subset of the <b>Hardware Catalog</b> , allowing the selection of a DTM.	
	<b>NOTE:</b> Unity Pro filters the content of the <b>Add</b> dialog, so that it displays only DTMs that are compatible with the selected DTM selected.	
Delete <sup>1</sup>	If the selected DTM allows this function, this deletes the selected DTM and its sub-node DTMs from the DTM connectivity tree. Deletion from the DTM connectivity tree does not affect the DTM's link to the I/O scanning table.	
Field Bus Discovery	This scans the connected physical devices to create the corresponding field bus topology. Refer to the Field Bus Discovery Service topic.	
Connect <sup>1</sup>	This connects the DTM (see page 47) to its physical device on the network. This connection does not depend on the PLC online/offline status of the Unity Pro project application.	
	<b>NOTE:</b> Connecting a gateway or device DTM implicitly connects its parent DTM.	
Disconnect <sup>1</sup>	This disconnects the DTM (see page 47) from its physical device. This disconnection depends on the PLC online/offline status of the Unity Pro project application.	
	<b>NOTE:</b> Disconnecting a gateway or device DTM implicitly disconnects its parent DTM.	
Load data from device <sup>1</sup>	This loads data from the physical device on the network to the DTM.	
Store data to device <sup>1</sup>	This loads data from the DTM to the physical device on the network.	
Сору	This command is disabled.	
Paste	This command is disabled.	
Device menu	This command opens a sub-menu that contains device-specific commands, as determined by the device vendor. For details, refer to the Communication Module Commands topic (see page 45).	
<ol> <li>This command also appears in the Unity Pro Edit menu.</li> <li>This command also appears in the Unity Pro View menu.</li> </ol>		

Name	Description	
Device menu 2	This command opens a sub-menu that contains device-specific commands, as determined by the device vendor. For details, refer to the Communication Module Commands topic <i>(see page 45)</i> .	
Properties <sup>1</sup>	Opens the Ethernet communication module <b>Properties</b> window.	
Print device <sup>1</sup>	If this optional function is supported by a DTM, this function displays the device documentation — including configuration settings — in the PC's default Internet browser, which can then be printed.	
	<ul> <li>NOTE: Device information can be printed:</li> <li>for only one device DTM at a time, when that DTM is not open for editing in the Device Editor.</li> <li>only when the DTM is disconnected from the physical device.</li> </ul>	
Zoom out <sup>2</sup>	This returns to the display of the entire DTM connectivity tree.	
Expand all <sup>2</sup>	This displays DTMs below the selected DTM.	
Collapse all <sup>2</sup>	This displays only the selected DTM.	
<ol> <li>This command also appears in the Unity Pro Edit menu.</li> <li>This command also appears in the Unity Pro View menu.</li> </ol>		

## **Communication Module Commands**

When you select **Device menu** in the main contextual menu for the communication module, a submenu with the following commands is displayed:

Name	Description
Offline Parameter	This command is disabled.
Online Parameter	This command is disabled.
Compare	This compares 2 devices, either online or offline.
Configuration	This opens the <b>Device Editor</b> for the selected communication module, when the module and its DTM are disconnected.
Observe	This command is disabled.
Diagnosis	This opens the <b>Diagnosis Window</b> for the selected communication module, when the module and its DTM are connected.

Name		Description
Additional functions	Add EDS to library	Opens the <b>EDS File Wizard</b> , which you can use to add a device EDS file to the Unity Pro EDS device library. Unity Pro displays the contents of EDS files as DTMs for use in the <b>DTM Browser</b> and <b>Device Editor</b> .
	Remove EDS from library	Opens the <b>EDS Deletion from Device Library</b> window, which you can use to delete an EDS file from the device library.
	Online Action	<ul> <li>Opens the Online Action window. Depending upon the protocol(s) a remote device supports, you can use the Online Action window to:</li> <li>Ping a remote EtherNet/IP or Modbus TCP device</li> <li>view and write to EtherNet/IP properties in a remote EtherNet/IP device</li> <li>view and write to port configuration properties in a remote EtherNet/IP device</li> </ul>
	EtherNet/IP Explicit Message	Opens the EtherNet/IP Explicit Message (see page 318) window, which you can use to send explicit messages to EtherNet/IP remote devices.
	Modbus TCP Explicit Message	Opens the Modbus TCP Explicit Message (see page 321) window, which you can use to send explicit messages to Modbus TCP remote devices.
	About	
	Advanced Mode	Displays or hides expert-level properties that help define Ethernet connections. See the Enabling Advanced Mode topic ( <i>see page 48</i> ) for instruction on how to use this feature.

When you select **Device menu 2** in the main contextual menu for the communication module, a sub-menu with the following commands is displayed:

Name	Description
Configuration	This opens the <b>Device Editor</b> for the selected communication module, when the module and its DTM are disconnected.
Diagnosis	This opens the <b>Diagnosis Window</b> for the selected communication module, when the module and its DTM are connected.
Add EDS to library	Opens the <b>EDS File Wizard</b> , which you can use to add a device EDS file to the Unity Pro EDS device library. Unity Pro displays the contents of EDS files as DTMs for use in the <b>DTM Browser</b> and <b>Device Editor</b> .
Remove EDS from library	Opens the <b>EDS Deletion from Device Library</b> window, which you can use to delete an EDS file from the device library.

Name	Description
Online Action	<ul> <li>Opens the Online Action window. Depending upon the protocol(s) a remote device supports, you can use the Online Action window to:</li> <li>Ping a remote EtherNet/IP or Modbus TCP device</li> <li>view and write to EtherNet/IP properties in a remote EtherNet/IP device</li> <li>view and write to port configuration properties in a remote EtherNet/IP device</li> </ul>
EtherNet/IP Explicit Message	Opens the EtherNet/IP Explicit Message (see page 318) window, which you can use to send explicit messages to EtherNet/IP remote devices.
Modbus TCP Explicit Message	Opens the Modbus TCP Explicit Message (see page 321) window, which you can use to send explicit messages to Modbus TCP remote devices.
Advanced Mode	Displays or hides expert-level properties that help define Ethernet connections. See the Enabling Advanced Mode topic <i>(see page 48)</i> for instruction on how to use this feature.

### Connecting and Disconnecting a Device or Module DTM

A device or module DTM can be either connected to, or disconnected from, the physical device or module.

When a device and its DTM are	You can use the Ethernet configuration tool to
Connected	Monitor and diagnose the real-time operation of the device or module
Disconnected	Configure a communication module or remote device by editing its properties

#### NOTE: Distinguish between:

- connecting and disconnecting a DTM and the associated physical device using commands in the DTM Browser
  - and —
- placing Unity Pro in online or offline operating mode using commands in the Unity Pro PLC menu

You can connect a DTM to, or disconnect a DTM from a device or module using the contextual pop-up menu in the **DTM Browser**. The **DTM Browser** indicates the relationship between the DTM and the remote module or device: a connected DTM is displayed in **bold** text; a disconnected DTM is displayed in normal text.

To connect a DTM to, or disconnect a DTM from its respective module or device, follow these steps:

Step	Action
1	In the <b>DTM Browser</b> select the DTM that you want to connect to, or disconnect from, the physical communication module or remote device.
	<ul> <li>NOTE: If the module or device name appears in:</li> <li>bold text, it is connected and only the Disconnect command is enabled.</li> <li>normal text, it is disconnected and only the Connect command is enabled.</li> </ul>
2	Click the right-mouse button. Result: A pop-up menu opens.
3	Select one of the following commands: • Connect • Disconnect
	<b>NOTE:</b> The <b>Connect</b> and <b>Disconnect</b> commands are also available in the Unity Pro <b>Edit</b> menu.

#### **Enabling Advanced Mode**

Use the contextual menu in the **DTM Browser** to toggle Unity Pro in or out of **Advanced Mode**, thereby displaying or hiding expert-level properties that help define Ethernet connections. These

properties are identified by the 🥝 icon.

**NOTE:** To maintain system performance, confirm that **Advanced Mode** properties are configured only by persons with a solid understanding of communication protocols.

To toggle Advanced Mode on and off:

Step	Action
1	Close both the <b>Diagnosis Window</b> and every instance of the <b>Device Editor</b> before attempting to toggle <b>Advanced Mode</b> on or off.
	<b>NOTE:</b> If the <b>Device Editor</b> or the <b>Diagnosis Window</b> is open, the <b>Advanced Mode</b> status — on or off — cannot be changed.
2	In the <b>DTM Browser</b> , right-click the communication module. <b>Result</b> : A pop-up menu opens.
3	To toggle ON advanced mode, select <b>Device Menu</b> → <b>Advanced Mode</b> .
4	To toggle OFF advanced mode, repeat steps 1 through 3, above.

# **Field Bus Discovery Service**

#### Introduction

Use the field bus discovery service to detect and add to your Unity Pro application, network devices that are situated on a local network. The field bus discovery service is available only when the Ethernet communication module DTM is connected to its physical device.

Only the first level devices below the communication DTM are detected.

#### **Performing Field Bus Discovery**

The results of the scanning process is compared to the registered DTMs in the DTM catalog of the computer. If a match is found in the DTM catalog for a scanned device, the results are accompanied with a matching type that gives the accuracy of the match.

These are the available matching types:

- Exact match: Every identification attribute matches. The correct device type was found.
- Generic match: At least the Vendor and device Type ID attributes match. The support level of the DTM is "Generic Support."
- Uncertain match: At least the Vendor and device Type ID attributes match. The support level of the DTM is not "Generic Support."

Use the field bus discovery service:

Step	Action				
1	In the <b>DTM Browser</b> , select an appropriate DTM.				
	<b>NOTE:</b> The field bus discovery service limits its search to the range of IP addresses that is pre- configured for the selected channel in the <b>Channel Properties</b> page (see page 60).				
2	Right-click the DTM and scroll to Field bus discovery to open the dialog box:				
	Field bus discovery       NOC01       Channel       EtherNet/IP       Modbus TCP       Select a channel and a protocol for scanning.       OK				
3	<ul> <li>Under these conditions, select a channel and a protocol:</li> <li>The DTM has more than one channel.</li> <li>The channel supports more than one protocol.</li> </ul>				
4	Click on <b>OK</b> . The service starts to detect devices on the selected channel.				

Step	Action					
5	If at least one matched device has been found, the <b>Field Bus Discovery</b> dialog displays a list of <b>Scanned Devices</b> .					
6	Use the controls of the <b>Field Bus Discovery</b> dialog to select the devices to add to your Unity Pro application.					
7	After you have selected the devices you want to add in the Field Bus Discovery dialog, click OK.					
8	If the field bus discovery process finds at least one device with an IP address that is already used in the project, you are asked if you want to continue and replace the existing project device(s): • Yes: Proceed to the next step. • No: Cancel automatic field bus discovery.					
9	The device properties dialog (below) opens, displaying the default name for the first discovered device to be added:					
	Properties of device					
	General       Device Information       DTM Information       Protocol Information         DTM name management       Alias name:       STBNIC2212_from_EDS         Tag name:					
	OK Cancel Help					
	In the <b>General</b> page of the device properties dialog, type in the <b>Alias name</b> for the device to be added, then click <b>OK</b> . The dialog closes, then re-opens if there is another device to be added to the application.					
10	Repeat the above step for each additional discovered device.					
11	<ul> <li>After you finish adding devices to the application, configure each device for operation as part of the application:</li> <li>Disconnect the Ethernet communication module from its DTM. In the DTM Browser, select the Ethernet communication module, then select Edit →Disconnect.</li> <li>Configure the new device properties in the DTMs for both the Ethernet communication module, and the newly added remote device.</li> </ul>					

## Field Bus Discovery Dialog

If at least one matched device has been found, the Field Bus Discovery dialog box is displayed listing the scanned and matched devices. Select the matched devices to be created in the Unity Pro project (which then shows up in the **Selected Devices** list:

Name		Address		TypeId	Vendor	Version	Serial		
1734-AENT Ethernet IP		192.168		12-108	1	2.1	4378503		
STB NIC 2212In19 Out	6	192.168	.1.6	12-2213	243	2.10	1024987	86	
Matched Devices:									
Name	Match	Туре	Vende	or	Ver	sion Da	te		
STB NIC 2212In19 Out			Schne	eider Electr			09-12-08		
-									
								+	
Selected Devices:								-	
Name	Addre	ss N	latch	Typeld	Vendor		Version	Date	
STB NIC 2212In19 Ou	t6 192.16	8.1.6 E	xact	device	Schneid	er Electric	2.10	2009-	12-08

This dialog presents these lists:

List	Description
Scanned Devices	The devices (matched and unmatched) found during the scan.
Matched Devices	The matched DTMs found in the workstation DTM catalog for the device that you selected in the <b>Scanned Devices</b> list. Each time a scanned device is selected in the <b>Scanned Devices</b> list, the contents of the <b>Matched Devices</b> list is updated to display the matched device DTMs found for the selected scanned device. The matching process can yield one or more matched devices for a given scanned device.
Selected Devices	This list displays the device DTMs that have been selected in the <b>Matched Devices</b> list, which will be added to the Unity Pro project.

Color	Meaning
Green	The device has been selected.
Yellow	The device has been matched.
Red	The device has <b>not</b> been matched.
Black	<ul> <li>Information about the address of the scanned device:</li> <li>In the Scanned Devices list, the device has an address identical to one of the DTMs in the Unity Pro project</li> <li>In the Matched Devices list, the device will be assigned an address identical to one of the DTMs in the Unity Pro project</li> </ul>
• has a m	icon can consist of two colors. For example, a search can discover a device that: atching DTM, and P address identical to a device already added to the Unity Pro application

In this case, the icon next to the discovered device would be:

- half yellow and half black before it is selected, and
- half green and half black after it is selected

This dialog has five buttons:

Button	Use this button to
Add All	Automatically add the most closely matched (according to the matching types listed above) device DTM for each found device in the <b>Matched Devices</b> list to the <b>Selected Devices</b> list.
Add One	Add the matched device DTM selected in the Matched Devices list.
Remove	Remove one or more devices from the <b>Selected Devices</b> list.
ОК	Insert the device DTMs in the <b>Selected Devices</b> list into the Unity Pro project. If there are one or more devices in the <b>Selected Devices</b> list that have the same address in the Unity Pro project, a message box opens asking if you want to continue. If you click <b>OK</b> , devices in the Unity Pro project that have identical addresses as the selected devices are <b>deleted</b> and <b>replaced</b> by the DTMs selected in the <b>Selected Devices</b> list.
Cancel	Cancel the field bus discovery scan and do nothing. Information in the three lists is discarded.

# **Device Editor**

#### Description

Use the **Device Editor** to view and configure Ethernet communication modules and remote devices. The collection of properties you can view or configure depends on:

- the node type selected in the DTM Browser:
  - communication module
  - remote device
- whether Unity Pro is operating in Advanced Mode

### **Displaying Properties of the Ethernet Communication Module**

After you open the BMX NOC 0401 Ethernet communication module in the **DTM Browser**, the left pane (1, below) of the **Device Editor** displays a tree control containing configurable property groups for the communication module. Click on a node in the tree control to display one or more pages of module properties for the selected group in the right pane (2, below).

		<u>_0×</u>
M_NOC0401 Communication NOC01		Schneider Electric
Channel Properties	Source Address:	
TCP/IP EtherNet/IP	Source IP Address: 2	192.168.1.99
Services     Address Server     SNMP	Sub-Network Mask:	255.255.255.0
Access Control QoS	EtherNet/IP Network Detection:	
EtherNet/IP Local Slaves	Begin detection range address:	192.168.1.1
<ul> <li>Local Slave 1</li> <li>Items</li> <li>Local Slave 2</li> </ul>	End detection range address:	192.168.1.254
Items ⊡ Local Slave 3	Modbus Network Detection:	
	Begin detection range address:	192.168.1.1
<ul> <li>► NIC2212_01</li> <li>⇒ Read Input / Write Output Data</li> <li>↓ Items</li> <li>Logging</li> </ul>	End detection range address:	192.168.1.254
Help	ОК	Cancel Apply
ADDisconnected ☐ Data Set		

## **Property Types**

The **Device Editor** displays an icon next to many device properties. The following three icons are displayed:

This icon	Indicates the property is
a F	Read-only. The property value cannot be edited in this page.
	Read-write. The property value can be edited in this page.
9	An expert-level communication protocol property that is displayed only when <b>Advanced Mode</b> is enabled.

### **Displaying Property Definitions**

Many property configuration pages provide an on-screen definition of the property you are editing. To display a property definition in the **Description** section of the page, select that property in the property list. The following screen displays a description of the **Gateway IP Address** property.

Configuration:	Static
Group/Parameter	Value
IP Address	
Scanner IP Address	192.168.1.4
📃 🔚 🕨 Sub-Network Mask	255.255.255.0
📃 🕨 🕨 Gateway IP Address	0.0.0.0
Description: IP address of a machine likely to perform r (internal or external).	outing to another network
ОК	Cancel Apply

**NOTE:** The page displayed above can be accessed by opening an Ethernet communication module in the **Device Editor**, and then selecting **Channel Properties**  $\rightarrow$ **TCP/IP** in the navigation tree.

# **Configuring Properties in the Device Editor**

## **Configuring Properties**

The Device Editor can be opened from the DTM Browser.

To open the **DTM Browser** select **Tools** →**DTM Browser** in the Unity Pro main menu.

To use the **Device Editor**:

Step	Description	
1	Confirm that the DTM you want to use is not connected to the actual communication module or device. It necessary, disconnect the DTM from the module or device (see page 47).	f
2	<ul> <li>In the DTM Browser, select the Ethernet network node you want to configure, which can be either:</li> <li>an Ethernet communication module <ul> <li>or —</li> <li>a remote device</li> </ul> </li> </ul>	
3	<ul> <li>With a node selected in the DTM Browser, do one of the following:</li> <li>In the Unity Pro main menu, select Edit →Open. — or —</li> <li>In the DTM Browser click the right mouse button and, in the pop-up menu, select Open.</li> <li>The Device Editor appears. It displays the configurable properties for the selected module or device:</li> </ul>	
	Q_NOC78000 - fdtConfiguration	
	Q_NOC78000 Communication Q_NOC78000 Scheider	
	Source Address:         Switch         TCP/IP         Services         Address Server         SNMP         RSTP         Service Port         Security         EtherNet/IP Local Slaves         Local Slave 1         Items         Local Slave 2         Items         EtherNet/IC Local Slave 3         Items         Device List	
	Help OK Cancel Apply	

Step	Description	
4	pane. The list of	gation tree and select a node in the left window pane to display its properties in the right configurable properties varies, depending on the node type — communication module or – selected in the <b>DTM Browser</b> .
5		parameter, Unity Pro displays an icon — next to the field you are editing and in the — indicating the parameter value is being edited. Unity Pro displays one of the following
	This icon	Indicates the importance of the parameter being edited is
	!	High: Editing this parameter may limit or deny access to the module or device.
	1	Low: Editing this parameter will not limit or deny access to the module or device.
6	<ul> <li>Apply to sav — or —</li> <li>OK to save y</li> <li>NOTE: Your edition</li> </ul>	editing a page, click: e your edits and keep the page open. our edits and close the page. ts will not take effect until they are successfully downloaded from your PC to the CPU and the communication modules and network devices.

# Uploading and Downloading DTM-Based Applications

#### Introduction

You can use Unity Pro to download an application file from your PC to the PLC, and to upload an application file from the PLC to your PC.

To perform a successful upload, confirm that the application file includes specific upload-related information as part of the application.

#### **Downloading DTM-Based Applications**

Unity Pro applications that include DTM files require more memory than traditional Unity Pro applications. The following products employ DTMs for network configuration:

- 140 NOC 771 01 Ethernet Communication Module for Quantum
- TSX ETC 101 Ethernet Communication Module for Premium
- BMX NOC 0401 Ethernet Communication Module for M340

In some cases, the configurations created for these modules—and the data associated with them—will require more memory than is available in the CPU.

If the amount of memory required by an application exceeds the amount of memory that is available in the CPU, Unity Pro displays a message during the build process, before the application is downloaded to the PLC.

When this situation occurs, exclude the additional upload-related information from the application to complete the build and enable the application download. To do this, make the following configuration change in Unity Pro:

Step	Action		
1	In the main menu, select Tools	→Project Settings T	he Project Settings window opens.
2	In the left pane of the Project Se	ettings window, select G	eneral PLC embedded data.
3	In the right pane, de-select Uplo	ad information:	
	Project Settings		<u>? × </u>
	Project Settings	Property label	Property value
	<ul> <li>General</li> <li>Management of build messages</li> </ul>	Data dictionary	
	- Build settings	Upload information	
	<ul> <li>Project autosaving on download</li> <li>Di Q angle alded data</li> </ul>	Comments	
	PLC embedded data	Animation tables	nt Automatic
	- Variables	Optimize data on-line change	
	Program     Operator Screens	Optimize data on-line change	
		l	
	Import 😫 Export 🗱 Reset All	OK Apply	Cancel Help
		Sector (1.1.1.1.1.1.1.1.1.1.1.1.1.1.1.1.1.1.1.	te undet nu de la translatione
4	Click OK to save your changes	and close the Project S	ettings window.

After the **Upload information** setting is disabled, you can build the application and download it to the PLC.

**NOTE:** An application in which the **Upload information** setting has been disabled cannot later be uploaded from the PLC to the PC.

#### Uploading DTM-Based Applications

DTM-based applications that were successfully downloaded to Unity Pro—with the project's **Upload information** setting enabled—can later be uploaded from the PLC to the PC if the target PC has the following files installed on it:

- a version of Unity Pro that is equal to or higher than the version used to create the application
- the master DTMs for the modules included in the configuration
   NOTE: The Ethernet Configuration Tool installation CD contains the Master DTMs for the Ethernet communication modules, referenced above.
- the device DTMs for the DTM-based devices attached to the network (confirm that the DTMs are of the same or higher revision as each device DTM used in the configuration)
- the device EDS files for any EtherNet/IP device used in the configuration (confirm that the EDS files are of the same or higher revision as each device EDS file used in the configuration)

After the above components have been installed on the target PC, you can upload a DTM-based Unity Pro application from a PLC.

**NOTE:** Confirm that each of the above DTM components is installed on the target PC *before* attempting the upload.

# Section 2.4 Channel Properties

#### **Overview**

This section describes how to configure channel properties for the Ethernet network.

## What Is in This Section?

This section contains the following topics:

Торіс	Page
Channel Properties Page	60
Channel Properties - Switch Settings	62
Channel Properties - QoS Queue	64
Channel Properties — TCP/IP Page	67
Channel Properties - EtherNet/IP Page	72

# **Channel Properties Page**

#### Description

Use the Channel Properties page to:

- select the IP address to use for:
  - connecting module or device DTMs to physical devices, and
  - sending explicit messages to Modbus TCP and EtherNet/IP devices
- view your PC's IP address settings

The Channel Properties page looks like this:

Source Address:	
Source IP Address:	192.168.1.99
Sub-Network Mask:	255.255.255.0
EtherNet/IP Network Detection:	
Begin detection range address:	192.168.1.1
End detection range address:	192.168.1.254
Modbus Network Detection:	
Begin detection range address:	192.168.1.1
End detection range address:	192.168.1.254
ОК	Cancel Apply

To display this page, select the **Channel Properties** node in the navigation tree located on the left side of the **Device Editor**.

**NOTE:** Refer to the topic Configuring Properties in the Device Editor (see page 55) for instructions on how to edit properties.

## **Properties**

This page presents the following properties:

Name	Description
Source Address area:	
Source IP Address:	A list of IP addresses assigned to network interface cards installed on your PC.
Sub-Network Mask:	The subnet mask associated with the selected Source IP Address.
EtherNet/IP Network De	tection area:
Begin detection range address	The starting IP address of the address range for automatic field bus discovery of EtherNet/IP devices.
End detection range address	The ending IP address of the address range for automatic field bus discovery of EtherNet/IP devices.
Modbus TCP Network D	etection area:
Begin detection range address	The starting IP address of the address range for automatic field bus discovery of Modbus TCP devices.
End detection range address	The ending IP address of the address range for automatic field bus discovery of Modbus TCP devices.

# **Channel Properties - Switch Settings**

#### Description

Use the Switch tab of the Switch page to:

- enable or disable each of the four Ethernet ports on the BMX NOC 0401 communication module
- view and edit the **Baud Rate** for each port, which includes both the:
  - transmission speed, and
  - duplex mode

**NOTE:** The Ethernet communication module supports only the **Ethernet II** frame type.

The **Switch** page looks like this:

Sv	witch Qc	oS Queue		
	Port	Enabled	Bai	ud Rate
	1	Yes	Auto 10	)/100Mbits/s
	2	Yes	Auto 10	)/100Mbits/s
	3	Yes	Auto 10	)/100Mbits/s
	4	Yes	Auto 10	)/100Mbits/s
	ОК	Ca	ncel	Apply

To display this page, select the **Channel Properties**  $\rightarrow$ **Switch** node in the navigation tree located on the left side of the **Device Editor**, then click on the **Switch** tab.

**NOTE:** Refer to the topic Configuring Properties in the Device Editor (see page 55) for instructions on how to edit properties.

# **Properties**

This page presents the following properties:

Name	Description
Port	(read-only) The Ethernet port number: 14.
Enabled	The active status of the port: • Yes = enabled • No = disabled
Baud Rate	The transmission speed and duplex mode for the network. Values include: • Auto 10/100 Mb (default) • 100 Mb Half • 100 Mb Full • 10 Mb Full
	<b>NOTE:</b> Schneider Electric recommends the default setting—Auto 10/100 Mb. This setting causes the connected devices to perform auto-negotiation and thereby determine the fastest common transmission rate and duplex mode.

# **Channel Properties - QoS Queue**

#### Description

The BMX NOC 0401 Ethernet communication module can be configured to sort packets it receives by placing them into one of 4 separate queues—based upon their priority (very high, high, low, very low)—and handle each packet in the order of its priority.

The module also can be configured to add a *differentiated service code point* (DSCP) value to each packet it originates, indicating the relative priority of the packet.

The process of packet queuing and DSCP tagging together enable the module to perform Ethernet packet traffic management.

Use the **QoS Queue** tab of the **Channel Properties** —**Switch** page to assign *differentiated service code point* (DSCP) values and queueing priorities to Ethernet packets based on their message type.

#### NOTE:

- The settings input in this page are synchronized with the values input in the Services →QoS page (see page 90). Edits to a common property in either page will change that value in the other page.
- The **Explicit Message** group settings are editable only when Unity Pro is operating in **Advanced Mode**.
- Confirm that every switch in your network adopts the same DSCP tagging scheme, thereby providing consistent packet traffic management throughout your network.

		DSCP Value	
	Type of Traffic		Queue Mapping
	PTP Event	59	Very High
1	PTP General	47	High
therN	Net IP Control		
	Type of Traffic	DSCP Value	Queue Mapping
	Urgent	55	High
	Scheduled	47	High
	High	43	High
	Low Explicit	31 27	Low Low
lodbu			
lodbu	Explicit		
lodbu	Explicit us TCP Control	27	Low
1odbu	Explicit us TCP Control Type of Traffic	27 DSCP Value	Low Queue Mapping
	Explicit US TCP Control Type of Traffic Modbus I/O Modbus Explicit	27 DSCP Value 47 27	Low Queue Mapping High Low
	Explicit us TCP Control Type of Traffic Modbus I/O Modbus Explicit	27 DSCP Value 47	Low Queue Mapping High

The QoS Queue page, displaying the default settings, looks like this:

To display this page, select the **Channel Properties**  $\rightarrow$ **Switch** node in the navigation tree located on the left side of the **Device Editor**, then click on the **QoS Queue** tab.

**NOTE:** Refer to the topic Configuring Properties in the Device Editor (see page 55) for instructions on how to edit properties.

# QoS Queue Mapping Settings

DSCP settings have a range of 0...63. The range of **Queue Mapping** settings are set forth below:

Group	Traffic Type	Available Group Queue Settings
Precision Time Control	Point-to-point event	<ul><li>Very High</li><li>High</li></ul>
	Point-to-point general	<ul><li>High</li><li>Low</li><li>Very Low</li></ul>
IEtherNet IP Control <sup>1</sup>	Urgent	• High
	Scheduled	● Low ● Very Low
	High	
	Low	-
	Explicit <sup>2</sup>	_
Modbus TCP Control <sup>1</sup>	Modbus I/O	• High
	Modbus Explicit	<ul><li>Low</li><li>Very Low</li></ul>
Network Time Protocol	NTP Control	<ul> <li>Very High</li> <li>High</li> <li>Low</li> <li>Very Low</li> </ul>
<ol> <li>Edits to these properties</li> <li>Editable only in Advance</li> </ol>	· · · · · · · · · · · · · · · · · · ·	he Services →QoS page (see page 90).

# Channel Properties — TCP/IP Page

#### Description

Use the TCP/IP page to:

- select a Configuration mode, which specifies how the communication module obtains its IP addressing settings, and
- edit the IP addressing settings that will be used if the Configuration mode is set to Static

**NOTE:** The settings made in this page can either match or conflict with the manual settings made using the 2 rotary switches on the back of the module. See the Resolving Conflicting Hardware and Software IP Address Settings topic for an explanation of when IP addressing conflicts exist and how the module resolves them.

The TCP/IP page looks like this:

Configuration:	Static
Group/Parameter	Value
IP Address	192.168.1.4
Sub-Network Mask	255.255.255.0
Gateway IP Address	0.0.0.0
Description: IP address of a machine likely to perform (internal or external).	n routing to another network
ОК	Cancel Apply

To display this page, select the **Channel Properties**  $\rightarrow$ **TCP/IP** node in the navigation tree located on the left side of the **Device Editor**.

**NOTE:** Refer to the topic Configuring Properties in the Device Editor (see page 55) for instructions on how to edit properties.

## Properties

The IP addressing properties you can configure in this page depends upon the selected configuration mode:

Property	Description	Configuration Mode Options
Scanner IP Address	The 32-bit identifier — consisting of both a network address and a host address — assigned to a device connected to a TCP/IP Internet network using the Internet Protocol (IP).	<ul><li>Static</li><li>Flash memory</li><li>BOOTP</li><li>DHCP</li></ul>
Sub-Network Mask	The 32-bit value used to hide (or mask) the network portion of the IP address and thereby reveal the host address of a device on a network using the IP protocol.	Static
Gateway Address	The address of a device, if any, that serves as a gateway to the communication module.	Static
Name	The device name. <b>NOTE:</b> The default device name, based on the rotary switch settings is BMX_0401_xxy. where: • xx is the value of the upper switch setting (tens) • y is the value of the lower switch setting (ones)	DHCP

## Selecting a Configuration Mode

Use the **Configuration** list to specify a configuration mode. The configuration mode setting determines how the communication module obtains its IP address at startup. Choices are:

Configuration Mode	Description
Static	The module uses the scanner IP address, gateway IP address, and sub-network mask configured in this page.
Flash Memory	The module uses the IP address configured via the TCP/IP object and stored flash memory. An IP address configured by this process survives both a warm and a cold re-start.
BOOTP	The module uses an IP address assigned by a BOOTP server.
DHCP <sup>1</sup>	The module uses an IP address assigned by a DHCP server.

## **Default Address Configurations**

The communication module uses a default address configuration when it is not configured or when a duplicate IP address is detected. The default address is based on the MAC address of the module and makes it possible for several Schneider Electric devices to use their default network configuration on the same network.

The module uses the following default address configurations:

- Default IP Address
   This default address starts with 10.10 and uses the last two bytes of the MAC address. As an example, a device with the MAC address of 00:00:54:10:8A:05 has a default IP address of 10.10.138.5 (0x8A=138, 0x05=5).
- Default Sub-Network Mask The default address is 255.0.0.0 (a class A mask).
- Default Gateway Address
   The default gateway address is identical to the default IP address.

## **Duplicate Address Checking**

Before going online, the module sends out at least 4 ARP (address resolution protocol) messages with a proposed IP address:

- if an answer is returned:
  - another network device is already using the proposed IP address
  - the module will not use the proposed IP address, but will instead use the default IP address
- if an answer is not returned:
  - the module is assigned the proposed IP address (along with the associated network parameters.)

**NOTE:** When powering up an entire network, some switches may be slow to complete the power up process. This can cause some ARP messages to be dropped. To help avoid this situation, Schneider Electric recommends that, when powering up an entire network, confirm that every network switch completes its power up cycle before powering up the PLCs.

## **Resolving Conflicting Hardware and Software IP Address Settings**

The following table summarizes the status of the Ethernet channel depending on the **Configuration Mode** set in the application, and the positions of the 2 rotary switches on the back of the module:

Application:	Rotary Switch Position			
Configuration Mode	DHCP <sup>1</sup>	BOOTP	STORED	CLEAR IP
<no configuration=""></no>	<b>No Conflict:</b> Get IP address from DHCP server using device name from rotary switches. Start basic services only.	No Conflict: Get IP address from BOOTP server. Start basic services only.	No Conflict: Get IP address from: • flash memory — or — • BOOTP server — or — • use default IP address Start basic services only.	No Conflict: Use default IP address. Start basic services only.
Static or Flash memory	<b>Conflict:</b> Get IP address from DHCP server using device name from rotary switches. Start basic services only.	<b>Conflict:</b> Get IP address from BOOTP server. Start basic services only.	<b>No Conflict:</b> Get IP address from the application. Start services configured in the application.	
DHCP or BOOTP with no configured device name	<b>No Conflict:</b> Get IP address from DHCP server using device name from rotary switches. Start services configured in the application.	No Conflict: Get IP address from BOOTP server. Start services configured in the application.	No Conflict: Get IP address from BOOTP server. Start services configured in the application.	
DHCP with a configured device name	<b>Conflict</b> (if device name on switches differs from name in application) or <b>No Conflict:</b> if names are equal. Get IP address from DHCP server using device name from rotary switches. If conflict, start basic services only; If no conflict, start services configured in the application.	<b>Conflict:</b> Get IP address from BOOTP server. Start basic services only.	<b>No Conflict:</b> Get IP address from DHCP server using device name from application. Start services configured in the application.	

## **Basic Services**

The following services are provided by the module when it is using its default IP address:

- FTP server (used for firmware download)
- HTTP/Web server
- Modbus/TCP server
- EtherNet/IP explicit message server
- SNMP agent
- RSTP

**NOTE:** Using the module as a messaging server, when the module is using its default IP address, is not recommended. The module will replace the default IP address with a served or user-configured IP address as soon as one is received.

# Channel Properties - EtherNet/IP Page

#### Description

The EtherNet/IP page is displayed only when Unity Pro is operating in Advanced Mode

(see page 48). Advanced mode properties are identified by the 🧔 icon.

Use the EtherNet/IP page to configure the following communication module properties:

- properties that determine how the communication module, as a scanner, opens connections for both implicit and explicit messages
- the frequency for transmitting produced data over implicit messaging connections
- · the timeout period for explicit messaging connections
- the behavior of the communication module—as a scanner—when:
  - the application is stopped, or
  - the communication module receives a reset service request

The EtherNet/IP page looks like this:

Image: Second state is STOP       False         Image: Second state is STOP       Stop	Group/Parameter	Value	Unit
FW_Open EM Connection Timeout       3000       ms         EM Connection RPI       10000       ms         EM Request Timeout       10       s         Behavior	🖃 🦲 Timeout		
EM Connection RPI       10000       ms         EM Request Timeout       10       s         Behavior	FW_Open I/O Connection Timeout	5000	ms
Image: Second state       10       s         Image: Second state       10       s <td>FW_Open EM Connection Timeout</td> <td>3000</td> <td>ms</td>	FW_Open EM Connection Timeout	3000	ms
Behavior     Allow RESET via explicit message     False     Behavior when CPU state is STOP     Stop	EM Connection RPI	10000	ms
Allow RESET via explicit message     False     Behavior when CPU state is STOP     Stop	EM Request Timeout	10	S
Behavior when CPU state is STOP Stop	🖃 🧰 Behavior		
	🖉 🦉 Allow RESET via explicit message	False	
Description	Behavior when CPU state is STOP	Stop	
	Description		

To display this page, select the **Channel Properties** —**EtherNet/IP** node in the navigation tree located on the left side of the **Device Editor**.

**NOTE:** Refer to the topic Configuring Properties in the Device Editor (see page 55) for instructions on how to edit properties.

# **Properties**

**Note:** Users experienced in the configuration of EtherNet/IP networks can edit the following readwrite properties.

Name	Description
Timeout	
FW_Open IO Connection Timing	The amount of time the communication module waits for the Forward_Open IO messaging transaction to open an implicit messaging connection. Default = 5000 ms
FW_Open EM Connection Timing	The amount of time the communication module waits for the Forward_Open IO messaging transaction to open an explicit messaging connection. Default = 3000 ms
EM Connected RPI	The value used to set the T->O (target to originator) and O->T (originator to target) requested packet interval (RPI) for explicit message connections. This value is used to calculate the lifetime of a connection. Default = 10000 ms.
EM Request Timeout	The amount of time the communication module waits between a request and reply of an explicit message. Default =10 s.
Output	
Allow reset explicit message	<ul> <li>The behavior of the communication module—as scanner—when it receives a reset service request:</li> <li>TRUE indicates the module will accept the request and reset itself.</li> <li>FALSE indicates the module ignores the reset service request and continues uninterrupted operations. Default = FALSE</li> </ul>
Behavior when CPU state is STOP	<ul> <li>The state of the communication module when the CPU application goes into a STOP state:</li> <li>TRUE indicates that the module enters STOP state (implicit connections are closed).</li> <li>FALSE indicates that the module enters IDLE state (implicit connections are not closed).</li> <li>Default = FALSE</li> </ul>

# Section 2.5 Ethernet Services

#### **Overview**

This section describes how to enable and configure Ethernet services provided by the BMX NOC 0401 communication module.

#### What Is in This Section?

This section contains the following topics:

Торіс	Page
Enabling Ethernet Services	75
Configuring the DHCP and FDR Servers	77
Configuring the SNMP Agent	84
Configuring Access Control	87
Configuring QoS Ethernet Packet Tagging	90
Configuring the Rapid Spanning Tree Protocol	94
Configuring the Email Service	98
Sending Email via the SEND_EMAIL Block	101
Configuring the Network Time Service	103

# **Enabling Ethernet Services**

#### **Service List**

Use the **Services** page to enable and disable Ethernet services provided by the communications module.

**NOTE:** After you enable any service, you can configure its settings. Unity Pro applies default settings to services you enable but elect not to configure.

The Services page looks like this:

Access Control	Enabled 💌
Address Server	Enabled 💌
QoS Tagging	Enabled 💽
I/O Communication Control	Enabled 🗾
RSTP	Enabled 💌
Port Mirroring	Enabled 💌
IGMP Snooping	Enabled 💌
Network Time Service	Enabled 💌
Email	Enabled 💌
OK Cancel	Apply

To display this page, select the **Services** node in the navigation tree located on the left side of the **Device Editor**.

After you **Enable** a service in this page, the next step is to configure that service. Depending upon the specific service, it can be configured in either the Unity Pro **Device Editor** (by selecting a node beneath the **Services** parent node) or in the module's web pages.

**NOTE:** Refer to the topic Configuring Properties in the Device Editor (see page 55) for instructions on how to edit properties in Unity Pro.

# **Service Descriptions**

The Ethernet communication module can be configured to provide the following services:

This service	Enables the module to	Configurable in
SNMP	<ul> <li>serve as an SNMP v1 agent</li> <li>provide trap information to up to two devices configured as SNMP managers.</li> </ul>	(not editable)
	<b>NOTE:</b> The SNMP service is enabled by default and cannot be disabled.	
Access Control	deny access to the Ethernet communication module from unauthorized devices.	Device Editor
Address Server	provide both IP addressing parameters and operating parameters to other Ethernet devices.	Device Editor
QoS Tagging	add <i>Differentiated Services Code Point</i> (DSCP) tags to Ethernet packets so that network switches can prioritize the transmission and forwarding of Ethernet packets.	Device Editor
	<b>NOTE:</b> Before enabling QoS tagging, confirm that devices connected to the Ethernet communication module support QoS tagging.	
I/O Communication Control	allow the Unity Pro application to control the enabling and disabling of individual connections between the communication module and remote I/O devices.	Device Editor
	<ul> <li>NOTE:</li> <li>The application can open and close individual connections using the control bits located at the beginning of the output area.</li> <li>If this service is disabled the user—via the application program—cannot toggle on and off connection control bits</li> </ul>	
RSTP	employ the <i>rapid spanning tree protocol</i> (RSTP)—in combination with other similarly-configured network devices—to manage redundant physical connections and create a loop-free logical path connecting the network devices.	Device Editor
Port Mirroring	duplicate the traffic entering and exiting any one of the four Ethernet ports onto another non-RSTP destination port, for the purpose of diagnosing the source port.	Web pages
IGMP Snooping	restrict outbound multicast transmissions to only those ports with downstream consumers.	<no configuration="" required=""></no>
Network Time Service	provide the source time synchronization signal for the PLC controller, which manages an internal clock to maintain this time.	Device Editor
Email	enable the sending—but not receiving—of email messages from the PLC application to a standard SMTP server.	Device Editor

# **Configuring the DHCP and FDR Servers**

#### Description

The Ethernet communication module includes both a DHCP and a Faulty Device Replacement (FDR) server. The DHCP server provides IP address settings to networked Ethernet devices. The FDR server provides operating parameter settings to replacement Ethernet devices that are equipped with FDR client functionality.

Use the Address Server page to:

- enable and disable the communication module's FDR service
- view an automatically generated list of devices included in the communication module's Ethernet configuration, displaying for each device:
  - IP addressing parameters, and
  - whether the device's IP addressing parameters are provided by the communication module's embedded DHCP server
- manually add remote devices—that are not part of the communication module's Ethernet configuration—to the communication module's DHCP client list

**NOTE:** Confirm that each device you manually add is equipped with DHCP client software, and is configured to subscribe to the communication module's IP addressing service.

Device Number 003	IP Address 192.168.1.6	DHCP Enabled	Identifier Ty Device Nam		Sub-Network Mask           1         255.255.255.0	Gateway IP Addres
anually Added De	Identifier Type			Sub-Network Mask		Add Device Manuall
	1		entifier S 22212_24	Sub-Network Mask 255.255.255.0	Gateway IP Address 192.169.0.0	Add Device Manuall
	1		ontifior	Pub Notwork Mook	Catoway ID Address	

The Address Server page looks like this:

To display this page:

Step	Description
1	Select the <b>Services</b> node in the navigation tree located on the left side of the <b>Device Editor</b> . The <b>Services</b> page opens.
2	In the <b>Services</b> page, set the <b>Address Server</b> field to <b>Enabled</b> . The <b>Address Server</b> node appears in the navigation tree.
3	Select the Address Server node in the navigation tree.

# Enabling the FDR Service

To enable the communication module's FDR service, set the **FDR Server** field to **Enabled**. To disable the service, toggle the same field to **Disabled**.

**NOTE:** Refer to the topic Configuring Properties in the Device Editor (see page 55) for instructions on how to apply edited properties to networked devices.

Any networked Ethernet device equipped with FDR client functionality can subscribe to the communication module's FDR service. The communication module can store up to 1 MB of FDR client operating parameter files. When this file storage capacity is reached, the module can not store any additional client FDR files.

The communication module can store FDR client files for up to 128 devices, depending on the size of each stored file. For example, if the size of each FDR client file is small—not more than 8 Kb— the module could store up to the maximum of 128 parameter files.

# Manually Adding Remote Devices to the DHCP Service

Remote devices that are part of the communication module's Ethernet configuration—and which have subscribed to the communication module's IP addressing service—automatically appear in the **Automatically Added Devices** list.

Other remote devices—that are not part of the communication module's configuration—can be manually added to the communication module's DHCP IP addressing service.

To manually add networked Ethernet devices, which are not part of the communication module's Ethernet configuration, to the communication module's IP addressing service:

Step	Description	
1		erver page, click the Add Device Manually button. Unity Pro adds the list of Manually Added Devices.
2	In the new row, o	configure the following parameters for the client device:
	IP Address	Type in the IP address of the client device.
	Identifier Type	<ul> <li>Select the type of value the client device will use to identify itself to the FDR server:</li> <li>MAC address</li> <li>Device Name</li> </ul>
	Identifier	Depending upon the identifier type, type in the client device setting for the MAC address or Name.
	Mask	Type in the client device subnet mask.
	Gateway	Type in the gateway address that remote devices can use to communicate with devices located on other networks. Use 0.0.0.0 if remote devices will not communicate with devices located on other networks.
3		Configuring Properties in the Device Editor (see page 55) for ow to apply edited properties to networked devices.

#### Viewing the Auto-Generated DHCP Client List

The list of Automatically Added Devices includes a row for each remote device that is:

- part of the communication module's Ethernet configuration, and
- configured to subscribe to the communication module's DHCP addressing service

**NOTE:** You cannot add devices to this list in this page. Instead, use the configuration pages for the remote device to subscribe to this service.

The list of **Automatically Added Devices** contains the following information for each networked device:

Property	Description
Device Number	The number assigned to the device in the Unity Pro configuration.
IP Address	The client device IP address.
Enable DHCP	TRUE indicates that the device subscribes to the DHCP service.
Identifier Type	Indicates the mechanism used by the server to recognize the client (MAC address or DHCP device name).
Identifier	The actual MAC address or DHCP device name.
Mask	The client device subnet mask.
Gateway	The IP address a DHCP client device will use to access other devices that are not located on the local subnet. A value of 0.0.0.0 constrains the DHCP client device by allowing it to communicate only with devices on the local subnet.

# Subscribing to the DHCP Service for a Device that is Part of the Configuration

An Ethernet device—that is part of the communication module Ethernet configuration—can subscribe to the communication module's IP addressing service. To subscribe to this service, follow these steps:

Step	Action
1	In the <b>DTM Browser</b> , select the Ethernet communication module that is connected to the remote device that you want to add to the DHCP service. In the following example, the communication module with the alias name of <b>NOC01</b> is selected:
	DTM Browser       X         Host PC       < 192.168.1.4 > NOC01         Image: Second Seco
	device bearing the alias name <b>NIC2212_01</b> , which is the module you want to add to the DHCP service.
2	With <b>NOC01</b> selected in the <b>DTM Browser</b> , click the right mouse button, and select <b>Open</b> in the pop-up menu.:
	Open
	Add
	Delete Del
	Field bus discovery
	Connect
	Disconnect
	Load data from device
	Store data to device
	Device menu
	Properties ALT + Enter
	Print device
	Zoom out
	Expand all
	Collapse all
	The Device Editor opens.

Step	Action
3	In the navigation tree on the left side of the <b>Device Editor</b> , expand the <b>Device List</b> node and select the device for which you want to enable the DHCP service. In this example, select <b>NIC2212_01</b> :
	Image: Services         Image: Service
	Unity Pro displays the properties for the selected remote device in the right pane of the window.
4	In the right pane of the window, select the <b>Address Setting</b> tab to display the following page:
	Properties Address Setting Change Address IP Address: 192 . 168 . 1 . 6
	Address Server:
	DHCP for this device: Enabled
	Identified by: Device Name
	Identifier: NIC2212_01
	Subnet Mask:         255 . 255 . 0           Gateway:         0 . 0 . 0 . 0
	Gateway: 0 . 0 . 0 . 0
	OK Cancel Apply

Step	Action	
5	In the Address Server are	ea of this page, configure the following properties:
	DHCP for this device	Select Enabled
	Identified by	The choices are: • MAC Address, or • Device Name Select Device Name.
	Identifier	Unity Pro has automatically added the device name <b>NIC2212_01</b> . For the purpose of this example, accept this default value.
	Subnet Mask	Unity Pro has automatically applied the same subnet mask used for the Ethernet communication module. For the purpose of this example, accept the default value of <b>255.255.255.0</b> .
	Gateway	For the purpose of this example, accept the default value of <b>0.0.0.</b>
6		s. Configuring Properties in the Device Editor <i>(see page 55)</i> liting and saving property settings in this window.

# **Configuring the SNMP Agent**

#### Description

The Ethernet communication module includes an SNMP v1 agent. An SNMP agent is a software component running on the communication module that allows access to the module's diagnostic and management information via the SNMP service.

SNMP browsers, network management software, and other tools typically use SNMP to access this data. In addition, the SNMP agent can be configured with the IP address of up to two devices—typically PC's running network management software—to be the target of event driven trap messages. These trap messages inform the management device of events such as cold start, and detected authentication failures.

Use the **SNMP** page to configure the SNMP agent in the communication module. The SNMP agent can connect to and communicate with up to 2 SNMP managers as part of an SNMP service. The SNMP service includes:

- authentication checking, by the Ethernet communication module, of any SNMP manager that sends SNMP requests
- management of event, or trap, reporting by the module

The **SNMP** page looks like this:

Group/Parameter	Value	Unit
🖃 🧰 IP Address Managers		
IP Address Manager 1	0.0.0.0	
💷 🕨 IP Address Manager 2	0.0.0.0	
🖃 🧰 Agent		
Location (SysLocation)		
Contact (SysContact)		
📃 🕨 SNMP Manager	False	
🖃 🧰 Community Names		
set	Public	
📃 🕨 Det	Public	
📃 🕨 Trap	Public	
🖃 🧰 Security		
Enable "Authentication Failure" Trap	False	
Description		
ОК Са	ncel	Apply

To display this page:

Step	Description
1	Select the <b>Services</b> node in the navigation tree located on the left side of the <b>Device Editor</b> . The <b>Services</b> page opens.
2	In the <b>Services</b> page, set the <b>SNMP</b> field to <b>Enabled</b> , then click <b>OK</b> or <b>Apply</b> . The <b>SNMP</b> node appears in the navigation tree.
3	Select the <b>SNMP</b> node in the navigation tree.

**NOTE:** Refer to the topic Configuring Properties in the Device Editor (*see page 55*) for instructions on how to edit properties.

#### Viewing and Configuring SNMP Properties

**NOTE:** The sysName SNMP parameter is neither editable nor visible in the Unity Pro Ethernet Configuration Tool software. By default, the sysName is set to the Ethernet communication module part number.

When DHCP is enabled and **Device Name** is selected as the DHCP identifier for the module, the SNMP sysName parameter is not set to the module part number, but is instead the device name.

The following properties can be viewed and edited in the SNMP page:

Property	Description
IP Address Managers:	
IP Address Manager 1	The IP address of the first SNMP manager to which the SNMP agent sends notices of traps.
IP Address Manager 2	The IP address of the second SNMP manager to which the SNMP agent sends notices of traps.
Agent:	
Location	The device location (32 characters maximum)
Contact	Information describing the person to contact for device maintenance (32 characters maximum)
SNMP Manager	<ul> <li>Select either:</li> <li>TRUE: the Location and Contact information are editable in this page</li> <li>FALSE: Location and Contact settings are not editable in this page</li> </ul>
Community Names:	
Get	Password required by the SNMP agent before executing read commands from an SNMP manager. Default = <b>public</b> .
Set	Password required by the SNMP agent before executing write commands from an SNMP manager. Default = public
Тгар	Password an SNMP manager requires from the SNMP agent before the manager will accept trap notices from the agent. Default = <b>public</b>
Security:	
Enable Authentication Failure Trap	<b>TRUE</b> causes the SNMP agent to send a trap notification message to the SNMP manager if an unauthorized manager sends a Get or Set command to the agent. Default = <b>FALSE</b> .

# **Configuring Access Control**

#### Description

Use the **Access Control** page to restrict access to the Ethernet communication module in its role as either a Modbus TCP or EtherNet/IP server. When access control is enabled in the **Services** page, add the IP addresses of the following devices to the list of **Authorized Addresses** to permit communication with that device:

- the Ethernet communication module itself, so that the module can use EtherNet/IP explicit messaging for any of the following purposes:
  - obtaining diagnostic data
  - resetting the module
  - changing the IP address
- any client device that may send a request to the Ethernet communication module, in its role as either Modbus TCP or EtherNet/IP server
- your own maintenance PC, so that you can communicate with the PLC via Unity Pro to configure and diagnose your application, and to view the module's web pages
- any target device to which the Ethernet communication module may send a Modbus TCP explicit message

**NOTE:** You need not add to list the IP address of devices that will be the target of EtherNet/IP explicit messages.

When access control is disabled in the **Services** page, the Ethernet communication module will accept Modbus TCP and EtherNet/IP requests from any device.

The following graphic depicts the **Access Control** page immediately after a new row has been added to the list of **Authorized Addresses**, but before the new item has been configured:

Authorized Addresses	Add Remove
OK Cancel	Apply

To display this page:

Step	Description
1	Select the <b>Services</b> node in the navigation tree located on the left side of the <b>Device Editor</b> . The <b>Services</b> page opens.
2	In the Services page, set the Access Control field to Enabled and click either OK or Apply. The Access Control node appears in the navigation tree.
3	Select the Access Control node in the navigation tree.

**NOTE:** Refer to the topic Configuring Properties in the Device Editor (see page 55) for instructions on how to edit properties.

# Adding and Removing Devices in the Authorized Address List

Step	Description
1	<ul> <li>In the Access Control page, click Add.</li> <li>A new row appears in the Authorized Addresses list, displaying:</li> <li>a red exclamation point, indicating editing has begun, and</li> <li>a placeholder IP address of 0.0.0.0</li> </ul>
2	Double-click the left mouse button on the placeholder IP address. The IP address field expands and becomes editable.
3	In the new IP address field, type in the IP address of the device which will be able to access the communication module, then press <b>Enter</b> .
4	Repeat steps 1 through 3, above, for each additional device to which you want to grant access to the communication module.
5	Refer to the topic Configuring Properties in the Device Editor (see page 55) for instructions on how to save your configuration edits.

To add a device to the Authorized Addresses list:

To remove a device from the **Authorized Addresses** list, select its IP address in the list, then click **Remove**. The selected IP address is removed.

# **Configuring QoS Ethernet Packet Tagging**

# Description

The Ethernet communication module can be configured to perform Ethernet packet tagging. The module supports the OSI layer 3 Quality of Service (QoS) standard defined in RFC-2475. When you enable QoS, the module adds a *differentiated services code point* (DSCP) tag to each Ethernet packet it transmits, thereby indicating the priority of that packet.

Use the QoS page to:

- · specify the source of QoS packet priority settings, and
- view or edit QoS DSCP prioritization values

The contents of the **QoS** page depends on the Ethernet communication module you selected for your project: **BMX NOC 0401** or **BMX NOC 0401.2**.

**NOTE:** The DSCP Value settings input in the **QoS** page are synchronized with the same settings in the **QoS Queue** tab of the **Channel Properties**  $\rightarrow$ **Switch** page. Edits to a common property in either page will change that value in the other page.

The **QoS** page displays five EtherNet/IP traffic types when you are operating in **Advanced Mode** (see page 48), or two EtherNet/IP traffic types when Advanced Mode is de-selected.

To display the QoS page:

Step	Description
1	Select the <b>Services</b> node in the navigation tree located on the left side of the <b>Device Editor</b> . The <b>Services</b> page opens.
2	In the <b>Services</b> page, set the <b>QoS Tagging</b> field to <b>Enabled</b> , then click <b>OK</b> or <b>Apply</b> . The <b>QoS</b> node appears in the navigation tree.
3	Select the <b>QoS</b> node in the navigation tree.

**NOTE:** Refer to the topic Configuring Properties in the Device Editor (see page 55) for instructions on how to edit properties.

# The QoS Page for the BMX NOC 0401.2 Ethernet Communication Module

The following **QoS** page displays the default values for the **BMX NOC 0401.2** module displays when operating in **Advanced Mode**:

Use Value from: Configuration	
DSCP Value for I/O Data Scheduled Priority Messages	47
DSCP Value for Explicit Messages	27
DSCP Value for I/O Data Urgent Priority Messages	55
DSCP Value for I/O Data High Priority Messages	43
DSCP Value for I/O Data Low Priority Messages	31
Modbus TCP Traffic	
DSCP Value for I/O Messages	47
DSCP Value for Explicit Messages	27
Network Time Protocol Traffic	
DSCP Value for Network Time Protocol Messages	59
OK Cano	el Apply

# The QoS Page for the BMX NOC 0401 Ethernet Communication Module

The following **QoS** page displays the default values for the **BMX NOC 0401** module displays when operating in **Advanced Mode**:

Use Value from: Configuration	
Type of Traffic	
DSCP Value for I/O Data Urgent Priority Messages (EtherNet/IP):	55
DSCP Value for I/O Data Scheduled Priority Messages (EtherNet/IP):	47
DSCP Value for I/O Data High Priority Messages (Modbus/TCP - EtherNet/IP):	43
DSCP Value for I/O Data Low Priority Messages (EtherNet/IP):	31
DSCP Value for Explicit Message (Modbus/TCP - EtherNet/IP):	27
OK Cancel	Apply

#### Specifying the Source of QoS Settings

The five QoS prioritization values can be set either from the communication module's flash memory, or in this page. To specify the QoS configuration source, set the **Use value from** field to either:

Setting	Description
Configuration <sup>1</sup>	The communication module uses the settings input in the <b>Type of Traffic</b> section of this page.
Flash <sup>1</sup> The communication module uses the settings saved in the module's memory. The fields in the <b>Type of Traffic</b> section are read-only.	
1. Schneider Electric recommends that QoS values be set in the configuration, and not be saving settings to flash memory. Settings saved to flash memory will be lost if the module replaced.	

**NOTE:** You can also edit QoS configuration settings by using explicit messages to set the attributes of the QoS CIP object (see page 254).

# **Type of Traffic Settings**

QoS tagging lets you prioritize Ethernet packet streams based on the type of traffic in that stream. The communication module recognizes the traffic types described below. When the **Use value from** field is set to **Configuration**, you can edit the prioritization values in this page. Each traffic type can have a prioritization value from 0... 63.

Traffic Type	Default
DSCP Value for IO Data Scheduled Priority Messages (EtherNet/IP)	43
DSCP Value for Explicit Message (Modbus TCP & EtherNet/IP)	27
DSCP Value for IO Data Urgent Priority Messages (EtherNet/IP) <sup>1</sup>	55
DSCP Value for IO Data High Priority Messages (Modbus TCP & EtherNet/IP) <sup>1</sup>	43
DSCP Value for IO Data Low Priority Messages (EtherNet/IP) <sup>1</sup>	31
DSCP Value for Network Time Protocol Messages	59
1. Visible only when Advanced Mode (see page 48) is enabled.	

To effectively implement QoS settings in your Ethernet network:

- use network switches that support QoS
- · consistently apply DSCP values to network devices and switches that support DSCP
- verify that switches apply a consistent set of rules for sorting DSCP tags, when transmitting and receiving Ethernet packets

**NOTE:** The QoS settings for Scheduled, High, and Low priority messages also apply to input and output priority messages for a remote device. You can configure these settings for a remote device *(see Quantum, 140 NOC 771 01 Ethernet Communication Module, User Manual)* in the **Device Editor** by selecting a device connection node, then opening the connection's **General** page.

# **Configuring the Rapid Spanning Tree Protocol**

#### Description

Ethernet ports 3 and 4, located on the front of the BMX NOC 0401 communication module, support the *Rapid Spanning Tree Protocol* (RSTP). RSTP is an OSI layer 2 protocol defined by IEEE 802.1D 2004. RSTP performs two necessary services:

- it creates a loop-free logical network path for Ethernet devices that are part of a topology that includes redundant physical paths
- it automatically restores network communication—by activating redundant links—in the event the network experiences a loss of service

RSTP software, operating simultaneously in every network switch, obtains information from each switch which enables the software to create a hierarchical logical network topology. RSTP is a flexible protocol that can be implemented on many physical topologies, including ring, mesh, or a combination of ring and mesh.

Use the **RSTP**  $\rightarrow$ **General** and the **RSTP**  $\rightarrow$ **Advanced** pages to configure RSTP for the embedded Ethernet switch in the communication module.

NOTE: RSTP can be implemented only when every network switch is configured to support RSTP.

The **RSTP** →**General** page looks like this:

I	General	Advanced		
l	RSTP Ope	ration State		
l	Bridge Priority:		32768	•
	ОК		Cancel	Apply

Bridge Parameters	20 s			
Transmit Hold Count:	40 Times			
Hello Time:	2 s			
Port Parameters				
Port 3 Parameters				
RSTP:	Enabled 💌			
Priority:	0 💌			
RTP Cost:	Auto	Value:	N/A	_
Edge Port:	Auto			
Point to Point:	Auto			
Port 4 Parameters				
RSTP:	Enabled 🗾			
Priority:	0 💌			
RTP Cost:	Auto	Value:	N/A	
Edge Port:	Auto			
Point to Point:	Auto			

The **RSTP** Advanced page looks like this:

To display these pages:

Step	Description
1	Select the <b>Services</b> node in the navigation tree located on the left side of the <b>Device Editor</b> . The <b>Services</b> page opens.
2	In the <b>Services</b> page, set the <b>RSTP</b> field to <b>Enabled</b> , then click <b>OK</b> or <b>Apply</b> . The <b>RSTP</b> node appears in the navigation tree.
3	Select the <b>RSTP</b> node in the navigation tree, then click on either the <b>General</b> or <b>Advanced</b> tab to display that page.

**NOTE:** Refer to the topic Configuring Properties in the Device Editor (see page 55) for instructions on how to edit properties.

# **Configuring RSTP Properties**

The following properties can be viewed and edited in the **RSTP General** page:

Property	Description
RSTP Operation State: Bridge Priority	A 2-byte value for the switch, from 0 to 65535, with a default of 32768 (the midpoint).
	<b>NOTE:</b> Network switches running RSTP software periodically exchange information about themselves using special packets called Bridge Protocol Data Units (BPDUs), which act as a heartbeat. The Bridge Priority value is contained in the BPDU and establishes the relative position of the switch in the RSTP hierarchy.

Property	Description	
Bridge Parameters:		
Maximum Age Time	This value is set to The length of time, from 6 to 40 seconds, that the switch waits for receipt of the next hello message, before initiating a change to the RSTP topology. Default = 40 s.	
Transmit Hold Count	The maximum number of BPDUs, from 1 to 40, that the switch can transmit per second. Default = 40.	
Hello Time	(read-only) The frequency—set at 2 seconds—that the embedded switch sends heartbeat BPDUs.	
Port Parameters (These propertie	es can be separately configured for ports 3 and 4):	
RSTP	(read-only) This property is set to <b>Enabled</b> in the <b>Services</b> page.	
Priority	<ul> <li>The priority assigned to the switch port, an integer from 0 to 240 in increments of 16. Default = 0. This value is used by the RSTP process i it needs to break a tie between two ports on the same switch when identifying a:</li> <li>root port: the port on a non-root switch that is closest to the root bridg in terms of path cost, or</li> <li>designated port: the port at one end of a network segment through which traffic passes on its way to the root bridge</li> </ul>	
RSTP Cost	<ul> <li>The method used to determine the RSTP cost of the path through the embedded switch. Values include:</li> <li>Auto—the RSTP protocol will automatically assign a value to the switch by operation of the RSTP algorithm</li> <li>Manual—you input the RSTP cost—an integer from 1 to 20000000-in the Value field.</li> </ul>	
Edge Port	(read-only) Set to a fixed value of <b>Auto</b> . The RSTP process automatically determines if the port is an RSTP edge port.	
Point to Point	(read-only) Set to a fixed value of <b>Auto</b> . The RSTP process automatically determines if the port is an RSTP point-to-point port.	

# **Configuring the Email Service**

# Using the Email Service

Use the Simple Mail Transfer Protocol (SMTP) service to configure up to three (3) Email messages. The PLC uses the Email messages you configure to notify specified Email recipients about meaningful run-time events—for example, a change in the value of a variable, or a threshold overrun.

NOTE: The Email service is available only when you first perform the following tasks:

- upgrade the firmware in the **BMX NOC 0401** Ethernet communication module to version 2.01 or higher
- select the **BMX NOC 0401.2** Ethernet communication module for your project using Unity Proversion 7.0 or higher

Email messages are transmitted by the execution of a SEND\_EMAIL (see page 101) function block included in your application logic.

**NOTE:** To successfully send an Email message using the SEND\_EMAIL block, the Email service and PLC application must be synchronized—i.e., the Email service must be activated whenever the PLC is in RUN mode.

You can configure the Email service only in the **Email Configuration** page of Unity Pro. You can diagnose the operation of the Email service in the diagnostic pages of both the Unity Pro software *(see page 326)* and the communication module web pages *(see page 393)*.

# **Configuring Email Service Parameters**

Use the following page to configure up to three Email messages:

SMTP Server	Configuration
SMTP Server	IP Address: 192 . 168 . 1 . 1 SMTP Server Port: 25
- Password Au	Ithentication
Authenticatio	n: Enabled V
	Password:
Email Header	1
From:	operator1@company.com
To:	merle@mainoffice.com
Subject:	Pump #1 pumping mud, Merle, shut her down
Email Header	2
From:	operator17@company.com
To:	fred@company.com
Subject:	Transformer #7 over-load
Email Header	3
From:	operator21@company.com
To:	carl@company.com
Subject:	Circuit breaker activated

# To display this page:

Step	Description
1	Select the <b>Services</b> node in the navigation tree located on the left side of the <b>Device Editor</b> . The <b>Services</b> page opens.
2	In the <b>Services</b> page, set the <b>Email</b> field to <b>Enabled</b> . The <b>Email</b> node appears in the navigation tree.
3	Select the Email node in the navigation tree.

# Viewing and Configuring Email Settings

The configurable Email service parameters include the following:

Parameter	Description	
SMTP Server Configuration:		
SMTP Server IP Address:	The IP address of the Email server that will relay Email messages.	
SMTP Server Port:	TCP port used by the Email server. Default = 25.	
Password Authentication:		
Authentication:	<ul><li>Is client authentication by the Email server:</li><li>Disabled (default)</li><li>Enabled</li></ul>	
Login:	If the Email server is configured for client authentication, the user name, up to 64 characters.	
Password:	If the Email server is configured for client authentication, the client password string, up to 64 characters.	
Email Header 13:		
From:	The Email address of the sender, up to 64 characters.	
To:	The Email addresses of the recipients, up to 128 characters.	
Subject:	The static part of the Email message, up to 32 characters.	

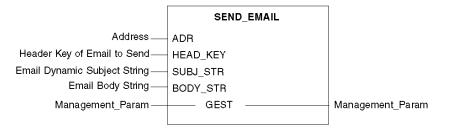
# Sending Email via the SEND\_EMAIL Block

# Using SEND\_EMAIL to Send Pre-configured Email Messages

Use the SEND\_EMAIL block in your application to programmatically send any of three email messages you previously configured in Unity Pro (see page 98).

**NOTE:** To successfully send an Email message using the SEND\_EMAIL block, synchronize the Email client service and PLC application—i.e., activate the Email client service whenever the PLC is in RUN mode.

# **FBD Representation**



#### **Input Parameters**

The following table describes the input parameters:

Parameters	Data Type	Description
ADR	ARRAY [07] OF INT	The path to the destination device, in the format of <i>rack.slot.channel</i> . Use the EFB ADDR to convert from the string format to the array of INT. For example, if the module is configured at rack 0, slot 4, channel 0, use: ADDR('0.4.0').
HEAD_KEY	INT	The email header number previously configured in Unity Pro <i>(see page 98)</i> . Only values of 1, 2, and 3 are valid).
SUBJ_STR	STRING	The dynamic part of the email subject that is appended to the static subject string.
BODY_STR	STRING	The body of the email.
		<b>NOTE:</b> Use the <b>\$N</b> (or <b>\$n</b> ) two-character tag to insert a line break in the email text.

# Input / Output Parameters

The following table describes the  ${\tt GEST}$  management parameter, which is the only input/output parameter:

Parameters	Data Type	Description
GEST	ARRAY [03] OF INT	The management parameter, consisting of 4 words.

The GEST management parameter presents the following structure:

Description	Word Order	MSB	LSB
System-managed data	1	Exchange number	Activity bit—the first bit of the first word. It indicates the execution status of the communication: • 1 = Email is being sent • 0 = Email complete
	2	Operation report (see page 428)	Communication report (see page 427)
User-managed	3	Timeout	
data	4	Length: the size of th	e data buffer.
		<b>NOTE:</b> The length parameter is an output parameter. This word is written by the system and equals the total length of the email (header + body). The maximum size of header + body is 1024 characters.	

# **Configuring the Network Time Service**

#### **The Network Time Protocol Client**

The Ethernet communication module includes a network time protocol (NTP) client. After you enable the network time service (*see page 75*), you can configure it by:

- identifying two external NTP servers—a primary server, and a secondary server—the Ethernet communication module uses to synchronize its internal time setting
- specifying the time zone location of the module
- enabling the automatic adjustment of the module internal time setting for daylight saving time changes

The Ethernet communication module sends its internal time setting to the PLC controller over the shared backplane. The PLC manages an internal clock to maintain this time, and uses the time setting to time-stamp system events and I/O data.

NOTE: The network time service is available only when you first perform the following tasks:

- upgrade the firmware in the BMX NOC 0401 Ethernet communication module to version 2.01 or higher
- select the BMX NOC 0401.2 Ethernet communication module for your project using Unity Proversion 7.0 or higher

Operation of the network time service can be monitored and diagnosed in:

- the Network Time Service Diagnostics page of the Unity Pro software (see page 340), and
- the Network Time Service web page (see page 416)

You can configure the network time only in the following page:

NTP Server Configuration	
Primary NTP Server IP Address:	192 . 168 . 1 . 1
Secondary NTP Server IP Address:	192 . 168 . 1 . 2
Polling Period:	18 (1-120) seconds
Time Zone:	
(UTC-05:00) Eastern Time (US & Canada)	×
Timezone Offset:	0 (-1439 to +1439) Minutes
Daylight Saving	
Automatically adjust clock for daylight saving:	Disabled V
Start Daylight Saving: Month: March	Day of Week: Sunday Veek#: 1
End Daylight Saving: Month: November	Day of Week: Sunday V Week#: 1

# To display this page:

Step	Description
1	Select the <b>Services</b> node in the navigation tree located on the left side of the <b>Device Editor</b> . The <b>Services</b> page opens.
2	In the Services page, set the Network Time Service field to Enabled. The Network Time Service node appears in the navigation tree.
3	Select the Network Time Service node in the navigation tree.

# Viewing and Configuring Network Time Service Settings

The following settings can be viewed and edited in this page:

Property	Description		
NTP Server Configuration	ו:		
Primary NTP Server IP Address	The IP address of the NTP server, from which the Ethernet communication module first requests a time setting.		
Secondary NTP Server IP Address	The IP address of the back-up NTP server, from which the Ethernet communication module requests a time setting, after not receiving a response from the primary NTP server.		
Polling Period	The frequency (1120 seconds) the Ethernet communication module uses for requesting a time setting from the NTP server. Default = 18 seconds.		
Time Zone:	·		
Time Zone Setting	The time zone associated with the Ethernet communication module, selected from a list that includes time zones around the globe. Default = Greenwich Mean Time (GMT) + 0 minutes.		
Timezone Offset	The number of minutes (–1439+1439) used to adjust the Time Zone Setting. Default = 0 minutes.		
Daylight Saving:	l		
Automatically adjust clock for daylight saving	<ul> <li>Enabled: turns ON the automatic clock adjustment for daylight savings.</li> <li>Disabled: turns OFF the automatic clock adjustment for daylight savings.</li> <li>Default = Disabled.</li> <li>If automatic adjustment of the clock for daylight savings is</li> </ul>		
	If automatic adjustment of the clock for daylight savings is enabled, use the next two fields to configure daylight saving adjustments.		
Start Daylight Saving	Month	Select the month daylight savings begins. Default = March.	
	Day of Week	Select the day of the week daylight savings begins. Default = Sunday.	
	Week#	Select the week of the month daylight savings begins. Default = 1 (fist week of the month).	
End Daylight Saving	Month	Select the month daylight savings ends. Default = November.	
	Day of Week	Select the day of the week daylight savings ends. Default = Sunday.	
	Week#	Select the week of the month daylight savings ends. Default = 1 (fist week of the month).	

# Section 2.6 Security

# **Security Features**

# Security and HTTP, FTP, and TFTP Services

You can enhance security for your project by disabling the FTP/TFTP and HTTP services at times when you do not need to use them. The module uses the HTTP service to provide access to the embedded webpages. The module uses the FTP and TFTP services to support various features including firmware upgrades, and FDR services.

The module's HTTP, FTP, and TFTP services can be disabled or enabled using the **DTM Browser Security** screen.

HTTP, FTP, and TFTP services are disabled by default in DTM instances created using BMX NOC 0401 module firmware version 2.04 or later and Unity Pro version 8.1 or later. They are enabled by default in instances created using previous versions of Unity Pro.

You can use Unity Pro to enable or disable HTTP, FTP, and TFTP services as described in the following procedure.

If the HTTP, FTP, or TFTP services have been enabled with Unity Pro, they can also be enabled or disabled at run time using a DATA\_EXCH function block. (See the *Communication Block Library* for Unity Pro.)

# Using Unity Pro to Enable and Disable Firmware Upgrade & FDR and Web Access Services

Perform the following steps to enable or disable FTP/TFTP or HTTP services on the module.

Step	Action	
1	In the Unity Pro main menu, select <b>Tools</b> → <b>DTM Browser</b> to open the <b>DTM Browser</b> .	
2	Confirm that the DTM you want to use is not connected to the actual communication module or device. If necessary, disconnect the DTM from the module or device (see page 44).	
3	In the <b>DTM Browser</b> , select the module. Right-click and select <b>Open</b> to open the <b>Device Editor</b> .	
4	Click the Security node in the navigation tree in the left panel to open the Security screen.	
5	On the <b>Security</b> screen, choose the appropriate setting: ( <b>Enabled</b> or <b>Disabled</b> ) for the service or services.	
6	Click: • Apply to save the changes and keep the window - or - • OK to save the changes and close the window	

The edits do not take effect until they are successfully downloaded from your PC to the CPU and from the CPU to the communication modules and network devices.

# Section 2.7

# Configuring the Ethernet Communication Module as an EtherNet/IP Adapter

# Overview

This section describes how to configure the Ethernet communication module to act as an EtherNet/IP adapter, using a functionality called Local Slave. The communication module supports up to three instances of local slaves.

In its role as a EtherNet/IP adapter, the module initiates no messages. Instead, it responds to:

- implicit messaging requests from a scanner device in the network, and
- explicit messaging requests—directed to the communication module's assembly object (see page 247)—from other devices on the network
   NOTE: If no local slave instance is enabled, the communication module can respond to explicit messaging requests directed at its CIP objects (see page 243) other than the assembly object.

#### What Is in This Section?

This section contains the following topics:

Торіс	Page
Introducing the Local Slave	
Configuring a Local Slave	111
Local Slave Inputs and Outputs	117

# Introducing the Local Slave

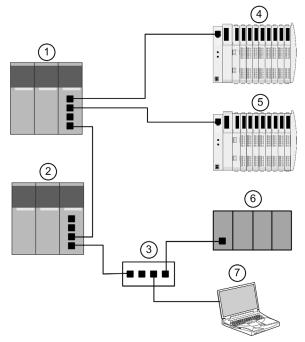
#### Local Slave Networking Example

The Ethernet communication module supports up to three instances of the local slave functionality. The local slave functionality allows other scanners on the network to read from, and write to, the Ethernet communication module using implicit messaging. Each local slave instance can accept one exclusive owner connection and one listen only connection. Through a local slave, a remote scanner can access the communication module's CIP Assembly object (*see page 247*). The local slave function is especially beneficial for peer to peer data exchanges at a repetitive rate.

#### NOTE:

- The Ethernet communication module can provide three local slave adapter instances, while simultaneously performing as a scanner. These roles are not mutually exclusive.
- The local slave is exclusively an EtherNet/IP functionality

In this example, the local slave instance is part of the following topology:



The sample configuration, above, includes the following devices:

- A primary PLC (1) incorporating the BMX NOC 0401 Ethernet communication module with one local slave instance enabled. The PLC scans I/O data from remote devices (4 and 5)
- A secondary PLC (2) that "listens" to the scan of the primary PLC's local slave by the third-party PLC (6)
- A managed Ethernet switch (3)

- An Advantys STB island (4), with an STB NIC 2212 EtherNet/IP network interface module plus 8 I/O modules
- An Advantys STB island (5), with an STB NIP 2212 Modbus TCP network interface module plus 8 I/O modules
- A third party scanner (6)—which lacks adapter capability, and therefore cannot itself be scanned by the primary PLC (1)—that:
  - collects data from other sources (not part of this network)
  - writes data to inputs of the primary PLC's local slave
  - scans the primary PLC's local slave's output data via an exclusive owner connection
- A PC running the following software:
  - Unity Pro
  - the Unity Pro Configuration Tool
  - Advantys Configuration Software

#### NOTE:

- Because the third party scanner (6) and the secondary scanner (2) are both receiving the same data produced by the local slave, configure the requested packet interval (RPI) setting of the third party scanner's exclusive owner connection and the secondary scanner's listen only connection to the same setting.
- By enabling a local slave on the primary PLC (1):
  - PLC (1) allows the third party PLC (6) to write to it at a repetitive rate, even if PLC (6) is not capable of acting as an adapter.
  - the secondary PLC (2) is able to scan the primary PLC (1) at a repetitive rate, rather than through application intensive explicit messaging.

The topics in this section show you how to use Unity Pro software installed in the PC (7, above) to configure a local slave, and to create input and output items in support of the peer-to-peer data transfers between and among scanners.

# **Configuring a Local Slave**

#### Description

The Ethernet communication module presents three identical **Local Slave** configuration pages. Use each page to configure a separate local slave instance. Create a local slave instance by:

- · enabling and naming the local slave
- · specifying the size of local slave input and output assemblies
- configuring local slave variable names

To display this page, select one of the three **Local Slave** nodes in the navigation tree located on the left side of the **Device Editor**.

**NOTE:** Refer to the topic Configuring Properties in the Device Editor (see page 55) for instructions on how to edit properties.

The following steps describe a sample configuration for **Local Slave 1**. Your configuration may be different.

#### **Configuration Example: Local Slave 1**

In the sample network configuration (see Quantum, 140 NOC 771 01 Ethernet Communication Module, User Manual), the application in the third-party PLC produces data, which is available in the PLC's Ethernet communication module as inputs. In this example, the third-party device produces the following information:

- production totals for manufacturing line A
- production totals for manufacturing line B
- the number of production interruption events for line A
- the number of production interruption events for line B

Any information that needs to be passed to the third-party device—for example, confirmation that data from the third-party device has been received by the PLC—is accessible in the third-party device as input data. In this example, the third-party device is programmed to scan Local Slave 1 for this confirmation.

When configuring inputs and outputs in both the local slave and the third-party PLC, associate inputs and outputs as follows:

Associate these local slave items:	With these third-party PLC items:	
Outputs (T to O)—assembly instance 101	Inputs—assembly instance 101	
Inputs (O to T)—assembly instance 102	Outputs—assembly instance 102	

Properties				
Number:	000 💌	Active C	onfiguration	n: Enabled
Comment:				<b>A</b>
	3			▼ ▶
Connection Bit:	0			
Assembly				
Outputs (T to O):	101	Outputs (T to O) Size:	2	(1-509) Bytes
Inputs (O to T):	102	Inputs (O to T) Size:	8	(1-505) Bytes
Configuration:	103	Configuration Size:	0	(0-200) Words
IO Structure Name				
_ Input			_	Default Name
Structure Name:		T_NOC01_LS1_IN	_	
Variable Name:		NOC01_LS1_IN		
Output				
Structure Name:		T_NOC01_LS1_OUT		
Variable Name:		NOC01_LS1_OUT		
		ОК	Cancel	Apply

The configured Local Slave page looks like this:

## Enabling and Naming the Local Slave

Use the **Properties** section of the **Local Slave** page to enable (or disable) and identify the local slave.

Setting	Description
Number	The unique number—or identifier—assigned to the device. By default, Unity Pro assigns: • 000 = local slave 1 • 001 = local slave 2 • 002 = local slave 3 In this example, accept the default <b>000</b> .
Active Configuration	<ul> <li>Enabled activates the local slave.</li> <li>Disabled de-activates the local slave, but retains the current local slave settings.</li> <li>In this example, select Enabled.</li> </ul>
Comment	An optional free text comment field up to 80 characters maximum. In this example, leave blank.
Connection bit	<ul> <li>Auto-generated integer (0127) indicating the offset of the connection's:</li> <li>health bit, located in the module's input area</li> <li>control bit, located in the module's output area</li> </ul>
	<b>Note:</b> This setting is auto-generated after the local slave settings are input and the network configuration is saved.

## Configuring the Size of Local Slave Input and Output Assemblies

Use the **Assemblies** section of the **Local Slave** page to configure the size of the local slave inputs and outputs. The assembly numbers are non-editable, and are assigned by Unity Pro as follows:

Assembly number	Local slave number	Used for connection		
101	1	T->O <sup>1</sup>		
102	1	O->T Exclusive Owner		
103	1	Configuration		
199	1	O->T Listen Only		
111	2	T->0		
112	2	O->T Exclusive Owner		
113	2	Configuration		
200	2	O->T Listen Only		
121	3	T->0		
122	3	O->T Exclusive Owner		
123	3	Configuration		
201	3	O->T Listen Only		
<ul> <li>1. In this table:</li> <li>O indicates the originator—or scanner—device</li> </ul>				

• T indicates the target—or adapter—device

The Local Slave assembly settings include:.

Setting	Description
Outputs (T->O)	A read-only value (see table, above). In this example, <b>101</b> .
Outputs (T->O) Size	The maximum size—in bytes—reserved for local slave outputs. An integer from 1 to 509. In this example, only two output bytes are used: type in <b>2</b> .
Inputs (O->T)	A read-only value (see table, above). In this example, <b>102</b> .
Inputs (O->T) Size	The maximum size—in bytes—reserved for local slave inputs. An integer from 0 to 505. In this example, only eight input bytes are used: type in <b>8</b> .
Configuration	A read-only value (see table, above). In this example, <b>103</b> .
Configuration Size	A read-only value set to <b>0</b> .

**NOTE:** When using explicit messaging to read the Ethernet communication module's assembly object, you need to allocate sufficient room for the response, because the size of the response will equal the sum of:

the assembly size + Reply service (1 byte) + General Status (1 byte)

#### **Configuring Local Slave I/O Variable Names**

Each input and output that Unity Pro creates for your application has both a non-editable structure name (used by Unity Pro to internally identify input and output items) and an editable variable name.

Use the I/O Structure Name section of the Local Slave page to:

- view and edit local slave input and output variable names
- view non-editable local slave structure names

The following property settings have been made in this example:

Setting	Description
Input:	
Structure Name	The read-only name for input structures. By default, it is the concatenation of: <ul> <li>the prefix T</li></ul>
	In this case, the default would be T_NOC01_01_IN.
Variable Name	<ul> <li>The editable base name for input variables. By default, it is the concatenation of:</li> <li>the alias device name—in this case NOC01</li> <li>the device number—in this case 01</li> <li>the suffix _IN</li> </ul>
	In this case, the default would be NOC01_01_IN. For this example, accept the default variable name.
Output:	· · · · · · · · · · · · · · · · · · ·
Structure Name	The read-only name for output structures. By default, it is the concatenation of: • the prefix T_ • the alias device name—in this case NOC01 • the device number—in this case 01 • the suffix _OUT
	In this case, the default would be T_NOC01_01_OUT.
Variable Name	<ul> <li>The editable base name for output variables. By default, it is the concatenation of:</li> <li>the alias device name—in this case NOC01</li> <li>the device number—in this case 01</li> <li>the suffix _OUT</li> <li>In this case, the default would be NOC01 01 OUT.</li> </ul>
	For this example, accept the default variable name.

If you have edited one or more variable names, you can restore the default variable names by clicking on the **Default Name** button.

## Local Slave Inputs and Outputs

#### Introduction

The Ethernet communication module serves as an adapter when the **Active Configuration** field is set to **Enabled** in the configuration window for one (or more) of the module's local slave nodes.

When a local slave instance of an Ethernet communication module is enabled, the designated memory location allocated to that instance is exposed to, and can be accessed by, other devices.

The I/O data exchange, between the remote device and the local slave, is configured as part of the remote device's configuration settings.

#### Configuring the I/O Items

You can configure input and output items in groups of 1 or more single bits, 8-bit bytes, 16-bit words, 32-bit dwords, or 32-bit IEEE floating values. The number of items you create depends upon the data type and size of each item.

The process for creating and defining I/O items for the local slave is the same as for any adapter class device, and depends upon the type of items you wish to create.

In support of the ongoing configuration example, the following items are required:

- 4 input word items
- 1 output word item

**NOTE:** The items created, below, are designed to hold data received from, or sent to, the thirdparty scanner. In addition to these items, it is necessary to include logic in the application programs in which the Ethernet communication module and the third-party scanner, respectively, are included. Writing this code is beyond the scope of this example.

## **Creating Input Word Items**

To create input items for local slave 01:

Step	Action
1	Select the Input tab to open that page:
	Input Input (bit) Output Output (bit)
	Offset/Device Offset/Connection Item Name  Default Item Name Root
	4 4 Define Item(s)
	5 5 Delete Item(s)
	8 8 Show Properties
	9 9
	Select a zone and click on the "Define Item(s)" button to create - one or several items - an array
	OK Cancel Apply
2 3	will be a 16-bit words, each item consists of 2 rows.         In the Default Item Name Root input box type: ProductionTotal_LineA.         Starting at the beginning of the table, select the first two rows: 0 and 1:
	Input Input (bit) Output Output (bit)
	Offset/Device Offset/Connection Item Name     Default Item Name
	0 0 ProductionTotal_LineA
	3 3 Define Hom(c)
	6 6 Delete Item(s)
	8 8 Show Properties
	Select a zone and click on the "Define Item(s)" button to create - one or several items - an array
	OK Cancel Apply

Step	Action							
4	Click the <b>Define Item(s)</b> button. <b>Result</b> : The <b>Item Name Definition</b> dialog opens:							
	Item Name Definintion							
	New Item(s) Data Type:							
	WORD							
	Define Selected Area As:							
	One or Several Single Item(s)							
	Item Name (32 char max):							
	ProductionTotal_LineA							
	OK Cancel Help							
5	Select WORD as the New Item(s) Data Type, then click OK. Result: A new item is created:							
	Input Input (bit) Output Output (bit)							
	16         0         0         ProductionTotal_LineA           1         1         1							
	4 4 4 Define Item(s)							
	6 6 Delete Item(s)							
	7 7 8 8 8 Show Properties							
	Select a zone and click on the "Define Item(s)" button to create - one or several items - an array							
	OK Cancel Apply							
6	Click <b>Apply</b> to save the new items, and leave the page open.							
7	Repeat steps 2 - 6 for each new word item you need to create. In this example,							
	that includes the following items:							
	Rows 2-3, Default Items Name Root: ProductionTotal_LineB							
	<ul> <li>Rows 4-5: Default Items Name Root: Events_LineA</li> <li>Rows 6-7: Default Items Name Root: Events_LineB</li> </ul>							
8	Create output words.							

## Creating Output Word Items

To create output items for local slave 01:

Input	Input (t	oit) Output	Output (bit)	
Offse	t/Device	Offset/Connection	Item Name	Default Item Name Ro
	0	0		BLOCKA
	1	1		
	2	2		
	4	4		Define Item(s)
	5	5		Delete Item(s)
Select a z	one and clicl	< on the "Define Item(s)"	button to create	Show Properties
	one and clicl veral items	< on the "Define Item(s)"	button to create	Show Propertie:
- one or se		< on the "Define Item(s)"	button to create	Show Properties Cancel Apply

Step	Action
3	Starting at the beginning of the table, select the first 2 rows, 0 and 1:
	Input Input (bit) Output Output (bit)
	Offset/Device Offset/Connection Item Name Default Item Name Root
	DataReceived
	4 4 5 5 5
	Delete Item(s)
	Show Properties
	Select a zone and click on the "Define Item(s)" button to create
	- an array
	OK Cancel Apply
4	Click the <b>Define Item(s)</b> button.
	Result: The Item Name Definition dialog opens:
	Item Name Definintion
	New Item(s) Data Type:
	WORD
	Define Selected Area As:
	One or Several Single Item(s)
	Item Name (32 char max):
	DataReceived
	OK Cancel Help

Step	Action				
5			he <b>New Item(s)</b> n is created:	Data Type, ther	n click <b>OK</b> .
	Input	Input	(bit) Output	Output (bit)	1
	/ Off	set/Device	Offset/Connection	Item Name	- Default Item Name Root -
	16	0	0 Da 1	taReceived	DataReceived
		2	2		
		3	3		Define Item(s)
		4	4		
			-		Delete Item(s)
					Show Properties
		several items	ck on the "Define Item(s)	button to create	
	- one or	several items		DK	Cancel Apply
6	- one or - an arra	several items		ок	Cancel Apply

## **Using Local Slave Inputs and Outputs**

The inputs and outputs created, above, are used as follows:

- The third-party device updates values of the following variables:
  - ProductionTotal\_LineA
  - ProductionTotal\_LineB
  - Events\_LineA
  - Events\_LineB
- The Ethernet communication module updates value of the DataReceived variable in the thirdparty device at the configured RPI.

# **Chapter 3** Adding Devices to an Ethernet Network

#### **Overview**

This chapter presents examples of how to add devices to, and how to configure these device for operations on, your Ethernet network.

## What Is in This Chapter?

This chapter contains the following sections:

Section	Торіс	Page
3.1	Hardware Catalog	124
3.2	Adding an EtherNet/IP Device to the Network	133
3.3	Adding a Modbus TCP Device to the Network	170

# Section 3.1 Hardware Catalog

#### **Overview**

Unity Pro includes a collection of modules and devices—called the **Hardware Catalog**—that you can add to a Unity Pro project. EtherNet/IP and Modbus TCP devices are located in the hardware catalog's **DTM Catalog** page. Each device in the catalog is represented by a DTM that defines the parameters of the module or device.

Not every device on the market today offer device-specific DTMs. Some devices are instead defined by a device-specific EDS file. Unity Pro displays each EDS file in the form of a DTM. In this way, you can use Unity Pro to configure these Ethernet/IP devices—defined by an EDS file—in the same way you would configure a DTM-defined device.

Other devices lack both a DTM and an EDS file. You can configure these devices by using a Generic DTM that is included in the **DTM Catalog** page.

This section address the topics:

- how to add a DTM to the catalog
- how to add an EDS file to the catalog
- how to update the catalog
- how to remove an EDS file from the catalog

#### What Is in This Section?

This section contains the following topics:

Торіс	Page
Adding a DTM to the Unity Pro Hardware Catalog	125
Add an EDS File to the Unity Pro Hardware Catalog	126
Updating the Unity Pro Hardware Catalog	129
Remove an EDS File from the Unity Pro Hardware Catalog	131

# Adding a DTM to the Unity Pro Hardware Catalog

## A Manufacturer Defined Process

Before a you can add a DTM to the Unity Pro **Hardware Catalog**, install it on the host PC—the same PC that is running Unity Pro—by means of an installation process defined by the device manufacturer.

Consult your device documentation, provided by the device manufacturer, for information describing how to install a device DTM on your PC.

For instructions on how to install the BMX NOC 0401 Ethernet communication module, refer to the topic Installing Unity Pro Ethernet Configuration Tool Software (see page 23).

**NOTE:** After you successfully install a device DTM on your PC, update the Unity Pro Hardware Catalog (*see page 129*) so the new DTM is visible in the catalog and available to be added to a Unity Pro project.

# Add an EDS File to the Unity Pro Hardware Catalog

#### Overview

Unity Pro includes a wizard you can use to add one or more EDS files to the Unity Pro **Hardware Catalog**. The wizard presents a series of instruction screens that:

- simplify the process of adding EDS files to the catalog, and
- provide a redundancy check in case you attempt to add duplicate EDS files to the catalog

**NOTE:** The Unity Pro **Hardware Catalog** displays a partial collection of DTMs and EDS files registered with the ODVA. This library includes DTMs and EDS files for products not manufactured or sold by Schneider Electric. The non-Schneider Electric EDS files are identified by vendor in the catalog. Please contact the identified device's manufacturer for inquiries regarding the corresponding non-Schneider Electric EDS files.

#### Adding EDS Files

To add one or more EDS files to the library:

Step	Action
1	If the <b>DTM Browser</b> is not already open, in the Unity Pro main menu select <b>Tools DTM Browser</b> .
2	In the <b>DTM Browser</b> , select a communication module, then click the right mouse button. A pop-up menu opens.
3	In the pop-up menu, select <b>Device menu</b> → <b>Add EDS to library</b> . The introductory page of the wizard opens.

Step	Action
4	Click <b>Next</b> . Page 2 of the wizard opens:
	EDS Addition
	EtherNet/IP <sup>TM</sup>
	Select the Location of the EDS File(s):  Add File(s)  Add all the EDS from the Directory Look in Subfolders
	Directory or File Name:
	The EDS Files usable in EIP-CT are registered in the EDS base. Select the location of the file(s) and click on the Next button to insert the EDS files in the base.
	<pre></pre>
5	<ul> <li>In the Select the Location of the EDS File(s) section, select either:</li> <li>Add File(s), to add one or more EDS files you will individually select, or</li> <li>Add all the EDS from the Directory, to add all files from a folder you will select.</li> <li>Select Look in Subfolders to also add EDS files in subfolders beneath the folder you selected.</li> </ul>
6	Click the <b>Browse</b> button. The <b>Open</b> dialog opens.
7	Use the <b>Open</b> dialog to navigate to and select: • one or more EDS files, or • a folder containing EDS files
8	After you have made your selections), click <b>Open</b> . The dialog closes and your selection appears in the <b>Directory or File Name</b> field.
9	Click <b>Next</b> . The wizard compares the selected EDS files against existing files in the library.
10	(Conditional) If one or more selected EDS files is a duplicate, a <b>File Already Exists</b> message opens. <b>Close</b> the message.

Step	Action		
11	Page 3 of the wizard opens indicating the Status of each device you attempted to add:		
	• a green check mark $\checkmark$ indicates the EDS file can be added		
	<ul> <li>a blue informational icon (1) indicates a redundant file</li> </ul>		
	<ul> <li>a red exclamation point   indicates an invalid EDS file</li> </ul>		
	(Optional) Select a file in the list, then click View Selected File to open it.		
12	Click <b>Next</b> to add the non-duplicate files. Page 4 of the wizard opens, indicating the action is complete.		
13	Click Finish to close the wizard.		
14	The next step is to update the Unity Pro <b>Hardware Catalog</b> (see page 129), so that the newly added device is available for inclusion in a Unity Pro project.		

# Updating the Unity Pro Hardware Catalog

#### **Updating Hardware Catalog**

After you have followed the manufacturer's instructions and installed a module or device DTM on your PC, the next step is to update the Unity Pro **Hardware Catalog**. Updating the **Hardware Catalog** makes the new Ethernet module or device available for addition to your Unity Pro application.

### To update the Hardware Catalog:

Step	Action			
1	In the Unity Pro main menu, select <b>Tools</b> → <b>Hardware Catalog</b> . The <b>Hardware Catalog</b> window opens.			
2	In the <b>Hardware Catalog</b> window, select the <b>DTM Catalog</b> tab to display a module and device DTM list. At the time of initial software installation, the catalog displays no devices:			
	Hardware catalog			
3	Click the External Update Tool button. The FDT/DTM Catalog window opens:			
	Block     Devices     Version     Date     Vendor       Device     Gateway       Module       Update     Stop			
4	In the <b>FDT/DTM Catalog</b> window, click <b>Update</b> . The window refreshes itself, as indicated by the progress bar in the lower right corner of the window.			

Step	Action			
5	After the update has finished, click <b>Close</b> . The <b>FDT/DTM Catalog</b> window closes and the <b>Hardware Catalog</b> displays.			
6	In the Hardware Catalo	g window, click <b>Reload ca</b>	talog to refre	sh the DTM list.
	All devices     Overloses     Vendors     Vendors     Vendors     Vendors     Vendors     Groups     Oroups     Protocols     I     External Update Tool     Rel     I     I     I/S FB Bus    DIO Bu	Device     Advanced Generic EDS     Generic Device     Generic Device for Explicit Messaging     M_NOC0401     P_ETC101     Q_NOC77101     STBNIC2212 (from EDS)     Generic Device	Type Device Device Device Communication Communication Device	Vendor Schneider Electric Schneider Electric Schneider Electric Schneider Electric Schneider Electric Schneider Electric Schneider Electric

## Remove an EDS File from the Unity Pro Hardware Catalog

#### **Overview**

You can remove a module or device from the list of available devices in the Unity Pro Hardware Catalog by removing its EDS file. When you remove an EDS file from the library, the device or module is no longer displayed by Unity Pro in the DTM Catalog page of the Hardware Catalog window.

However, removing an EDS file from the library does not delete the file. Instead, the EDS file remains in its stored location and can again be added to the catalog (see page 126) at a future time.

#### **Removing an EDS File from the Catalog**

To remove an EDS file from the catalog:

Step	Action
1	If the <b>DTM Browser</b> is not already open, in the Unity Pro main menu select <b>Tools</b> $\rightarrow$ <b>DTM Browser</b> .
2	In the <b>DTM Browser</b> , select a communication module, then click the right mouse button. A pop-up menu opens.
3	In the pop-up menu, select <b>Device menu</b> → <b>Remove EDS from library</b> . The following window opens:
	EDS Deletion from Device Library
	EtherNet/IP
	Display: All EDS Sort by: File Name
	Displayed Name
	Device Library     EtherNet/IP Devices     Chassis     Modules
	Delete Selected File(s)         View Selected File(s)         Close         Help

Step	Action		
4	Use the selection lists in the heading of this window to specify how EDS files will be displayed:		
	Display	Filters the list of displayed EDS files; select: • All EDS (no filtering) • Only Devices • Only Chassis • Only Modules	
	Sort by	Sorts the list of displayed EDS files; select: • File Name • Manufacturer • Category • Device Name	
	Displayed Name	<ul> <li>The description displayed for each device; select:</li> <li>Catalog Name</li> <li>Product Name</li> </ul>	
5	In the <b>Device Library</b> tree control, navigate to and select the EDS file you want to remove.		
6	(Optional) Click the <b>View Selected File</b> button to display the read-only contents o the selected EDS file.		
7	Click the Delete Selected File button. A message box opens.		
8	Click <b>Yes</b> to remove the selected EDS file from the list.		
9	When you have finished removing EDS files, click Close.		
10	The next step is to update the Hardware Catalog (see page 129).		

# Section 3.2 Adding an EtherNet/IP Device to the Network

#### **Overview**

This section extends the sample Unity Pro application, by describing how to:

- add an STB NIC 2212 EtherNet/IP network interface module to your Unity Pro application
- configure the STB NIC 2212 module
- configure EtherNet/IP connections linking the BMX NOC 0401 communication module and the STB NIC 2212 network interface module
- configure I/O items for the Advantys Island

**NOTE:** The instructions in this chapter describe a single, specific device configuration example. Refer to the Unity Pro help files for additional information about alternative configuration choices.

#### What Is in This Section?

This section contains the following topics:

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# **Setting Up Your Network**

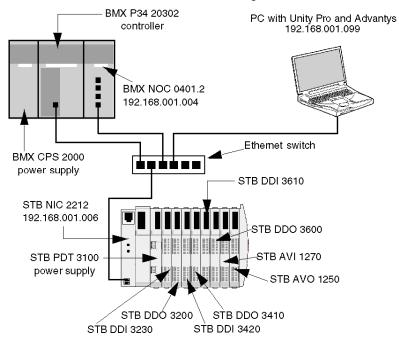
#### Overview

This sample network includes the following hardware and software:

- a controller rack with:
  - BMX CPS 2000, 100/240 VAC power supply
  - BMX P34 20302 controller
  - BMX NOC 0401.2 Ethernet communication module
- a remote STB Advantys island with:
  - STB NIC 2212 EtherNet/IP network interface module
  - STB PDT 3100 power distribution module
  - STB DDI 3230 2 pt digital input module
  - STB DDO 3200 2 pt digital output module
  - STB DDI 3420 4 pt digital input module
  - STB DDO 3410 4 pt digital output module
  - STB DDI 3610 6 pt digital input module
  - STB DDO 3600 6 pt digital output module
  - STB AVI 1270 2 pt analog input module
  - STB AVO 1250 2 pt analog output module
- a PC running both Unity Pro (version 5.0 or higher) and Advantys configuration software (version 5.0 or higher)
- an Ethernet managed switch that is connected to the both the controller and island by means of twisted pair Ethernet cable and RJ45 connectors.

## **Network Topology**

The Ethernet network devices used in this configuration include the following:



To re-create this example:

- use the IP addresses for your own configuration's:
  - PC
  - BMX NOC 0401.2 Ethernet communication module
  - STB NIC 2212 network interface module
- check wiring

**NOTE:** Unity Pro software running in the PC is used to configure the BMX P34 20302 controller. In this example, the PC is indirectly wired to the CPU's Ethernet port via the Ethernet switch. Alternatively, you could bypass the switch and directly wire the PC to either the CPU's Modbus or USB ports.

## Adding an STB NIC 2212 Remote Device

#### **Overview**

You can use the Unity Pro device library to add a remote device—in this example the STB NIC 2212 module—to your project. Only a remote device that is part of your Unity Pro device library can be added to your project. Refer to the topic describing the Add EDS File Wizard (see page 126) for instructions on how to add a device EDS file to the device library.

Alternatively, with a remote device already added to your device library, you can use automatic device discovery to populate your project. Perform automatic device discovery by using the **Field bus discovery** command with a communication module selected in the **DTM Browser**.

In either case, you need to update the list of available modules and devices, as follows:

Step	Action
1	In the Unity Pro main menu, select <b>Tools</b> — <b>Hardware Catalog</b> to display that window.
2	In the <b>Hardware Catalog</b> window, click on the <b>DTM Catalog</b> tab to open that page.
2	In the <b>DTM Catalog</b> page, click <b>Reload catalog</b> . The list of available devices, as displayed both in the <b>DTM Catalog</b> page and the <b>Add</b> dialog, is updated and reflects any device additions or deletions.

## Adding an STB NIC 2212 Remote Device

To add the STB NIC 2212 to your project, follow these steps:

Step	Action				
1	In the <b>DTM Browser</b> , select the Eth click the right mouse button. A pop-			odule node, a	and then
2	In the pop-up menu, select Add	The follo	owing dialog oper	ns:	
	Add				×
	Device	Туре	Vendor	Version 🔺	
	Advanced Generic EDS	Device	Schneider Electric	1.04.0001	
	Generic Device	Device	Schneider Electric	1.04.0001	
	Generic Device for Explicit Messa	Device	Schneider Electric	1.04.0001	
	Modbus Device	Device	Schneider Electric	1.04.0001	
	STBNIC2212 (from EDS)	Device	Schneider Electric	2.10	
	TCDEI-888N-D1U (from EDS)	Device	Molex Incorporated	3.4	
	TCDEI-888N-DYU (from EDS)	Device	Molex Incorporated	3.4	
	TCDEI-888P-D1U (from EDS)	Device	Molex Incorporated	3.4	
	Add DTM			Close	
3	In the <b>Add</b> dialog, select the <b>STBN</b> window for the STB NIC 2212 netw		-		operties

Step	Action
4	In the <b>General</b> page of the <b>Properties</b> window, edit the default <b>Alias name</b> , because retaining the original default name can result in duplicate module names. In this example, type in the name <b>NIC2212_01</b> :
	Properties of
	General       Device Information       DTM Information       Protocol Information         DTM name management
	Variable name: NIC2212_01_IN Default output I/O vision Variable name: NIC2212_01_OUT
	OK Cancel Help
5	When you edit the <b>Alias name</b> , Unity Pro applies it as the base for both structure and variable names. <b>NOTE:</b> No additional editing needs to be performed in the pages of this window.
	Except for the <b>Alias name</b> field, parameters are read-only.
	Click <b>OK</b> . Unity Pro adds the new STB NIC 2212 network interface module to the <b>DTM Browser</b> , beneath the communication module.
6	Refer to the topic Configuring Properties in the Device Editor (see page 55) for instructions on how to save your configuration edits.

The next step is to configure the device you have just added to the project.

# **Configuring STB NIC 2212 Properties**

#### **Overview**

Use the pages of the **Device Editor** to view and edit settings for a remote device. Before you can edit the device settings, disconnect the DTM from the remote device (see page 47).

To display the DTM settings for a remote device, select the device name, which is found under the **Device List** node in the left pane of the **Device Editor**.

For the purposes of this example, which configures an STB NIC 2212 network interface module, select the node named **NIC2212 01**. The **Device Editor** displays the following pages:

- Properties
- Address Setting

**NOTE:** Refer to the topic Configuring Properties in the Device Editor (see page 55) for instructions on how to edit properties.

## **Configuring the Properties Page**

The Properties page for an STB NIC 2212 network interface module looks like this:

Properties Address Setting
Properties
Number:         003         Active Configuration:         Enabled         Image: Configuration in the image: Co
Comment:
IO Structure Name
Structure Name: T_NIC2212_01_IN
Variable Name: NIC2212_01_IN
Output Structure Name: T_NIC2212_01_OUT
Variable Name: NIC2212_01_OUT
Items Management Import Mode: Manual Reimport Items
OK Cancel Apply

The following settings are used in this sample configuration. Use settings that are appropriate for
your actual application:

Step	Action		
1	In the <b>Properties</b> section of the page, edit the following:		
	Number	The relative position of the device in the list, from 0 to 127. For this example, accept the default of <b>003</b> .	
	Active Configuration	<ul> <li>Enabled: adds this device to the Unity Pro project configuration</li> <li>Disabled: removes this device from the Unity Pro project configuration</li> </ul>	
		Accept the default setting of Enabled.	
2	In the IO Structure Name section of the page, edit the following:		
	Input area:		
	Structure Name	(Read-only) Unity Pro automatically assigns a structure name based on the variable name, in this case <b>T_NIC2212_01_IN</b> .	
	Variable Name	Accept the auto-generated input variable name (based on the alias name (see page 137)): <b>NIC2212_01_IN</b> .	
	Output area:		
	Structure Name	(Read-only) Unity Pro automatically assigns a structure name based on the variable name, in this case <b>T_NIC2212_01_OUT</b> .	
	Variable Name	Accept the auto-generated output variable name (based on the alias name): <b>NIC2212_01_OUT</b> .	
	Default Name button	Restores the default variable and structure names. For this example, custom names are used instead of the default names.	

Step	Action		
3	In the Items Management section of the page, edit the following:		
	Import mode	<ul> <li>Automatic: Select this if I/O items are pre-defined for the device in its DTM, and will not subsequently be edited. These items are automatically created and added to the configuration, and later updated if the items list if the device DTM changes. These autocreated items cannot be edited in the Device Editor.</li> <li>Manual: Select this if I/O items will be manually created or edited. If the device DTM pre-defines I/O items, those pre-defined I/O items are automatically created and added to the configuration, and can later be manually edited in the Device Editor. The I/O items list is not affected by changes to the device DTM.</li> <li>NOTE:</li> <li>Because the STB NIC 2212 DTM does not contain preconfigured input and output items, select Manual.</li> <li>To view I/O items, navigate to and select the Items node in the left pane of the Device Editor, as follows:</li> </ul>	
		<ul> <li>Channel Properties</li> <li>Services</li> <li>EtherNet/IP Local Slaves</li> <li>Device List</li> <li>Read Input / Write Output Data</li> <li>Logging</li> </ul>	
	Reimport Items	Imports the I/O items list from the device DTM, overwriting any manual I/O item edits. Enabled only when <b>Import</b> <b>mode</b> is set to <b>Manual</b> .	
4	Click Apply to save your edits, and leave the window open for further edits.		

## **Configuring the Address Setting Page**

Use the **Address Setting** page to enable the DHCP client in the STB NIC 2212 network interface module. When the DHCP client is enabled in the remote device, it will obtain its IP address from the DHCP server in the Ethernet communication module. The **Address Setting** page looks like this:

Properties Address Setting				
Change Address				
IP Address:	192 . 168 . 1 . 6			
Address Server:				
DHCP for this device	Enabled			
Identified by:	Device Name			
Identifier:	NIC2212_01			
Subnet Mask:	255 . 255 . 255 . 0			
Gateway:	0.0.0.0			
ОК	Cancel Apply			

The following settings are used in this sample configuration. Use settings that are appropriate for your actual application:

Step	Action		
1	In the Address Setting	<b>s</b> page, edit the following:	
	IP Address	<ul> <li>By default:</li> <li>the first three octet values equal the first three octet values of the Ethernet communication module, and</li> <li>the fourth octet value equals this device Number setting—in this case, the default value would be 004.</li> <li>In our continuing example, type in the address 192.168.1.6.</li> </ul>	
	DHCP for this Device	<ul> <li>Enabled activates the DHCP client in this device. The device obtains its IP address from the DHCP service provided by the Ethernet communication module and appears on the auto-generated DHCP client list (see page 80).</li> <li>Disabled (the default) de-activates the DHCP client in this device.</li> <li>Select Enabled.</li> </ul>	
	Identified by	If DHCP for this Device is Enabled, this indicates the device identifier type: MAC Address, or Device Name	
		Select Device Name.	
	Identifier	If <b>DHCP for this Device</b> is <b>Enabled</b> , the specific device MAC Address or Name value. Accept the default setting of <b>NIC2212_01</b> (based on the Alias name).	
	Mask	The device subnet mask. The default = 255.255.255.0. Accept the default value.	
	Gateway	The gateway address used to reach this device. The default of 0.0.0.0 indicates this device is located on the same subnet as the Ethernet communication module. Accept the default value.	
2	Click <b>OK</b> to save your edits.		

The next step is to configure the connection between the communication module and the remote device.

# **Configuring EtherNet/IP Connections**

### **Overview**

An EtherNet/IP connection provides a communication link between two or more devices. Properties for a single connection can be configured in the DTMs for the connected devices.

Use the **Device Editor** to view and edit connection settings. The following example presents settings for a connection between the BMX NOC 0401 communication module and a remote STB NIC 2212 network interface module. Configuration edits are made to the DTMs for each device.

When making DTM edits, disconnect the selected DTM from the actual module or device *(see page 47)*.

**NOTE:** Refer to the topic Configuring Properties in the Device Editor (see page 55) for instructions on how to edit properties.

### **Configuring Connection Settings in the Communication Module DTM**

Unity Pro automatically creates a connection between a communication module and remote device, when the remote device is added to the Unity Pro project. Thereafter, many edits to the connection can be made in the DTM for the remote device. However, some of the connection parameters can also be configured in the DTM for the communication module, as demonstrated below.

The following connection settings for this sample configuration can be set in the DTM for the communication module. Use settings that are appropriate for your actual application:

Step	Action
1	<ul> <li>Open the DTM for the communications module—in this example NOC01—by selecting it in the Device Editor, then do one of the following:</li> <li>in the main menu, select Edit →Open, or</li> <li>click the right mouse button, and select Open in the pop-up menu</li> </ul>
	The communication module DTM opens in the <b>Device Editor</b> .
2	In the navigation pane (on the left side of the <b>Device Editor</b> ) select the node representing the connection from the communication module to the remote device, in this case: <b>Device List →NIC2212_01 →Read Input / Write Output Data</b>

Step	Action							
3	Click on the <b>Connection Settings</b> tab to open the following page:							
	Connection Settings Connection Information							
		Parameter	Value Unit					
		nnection Bit	1					
		quest Packet Interval (RPI) ne-out Multiplier	30 x4	ms				
	Description	Description						
		ОК	Cancel	Apply				
	<b>NOTE:</b> To view the <b>Time-out Multiplier</b> parameter, confirm that Unity Pro is operating in <b>Advanced Mode</b> .							
4	In the Connection	Settings page, edit the follo	owing settings:					
	Connection Bit	<ul> <li>(Read-only) The offset for both the health bit and the control bit for this connection. Offset values are auto-generated by the Unity Pro Ethernet Configuration Tool, beginning at 0, and are prioritized according to the connection type, as follows:</li> <li>1 Modbus TCP connections</li> <li>2 local slave connections</li> <li>3 EtherNet/IP connections</li> </ul>						
		<b>NOTE:</b> The initial value of this EtherNet/IP connection is 1, because only a single local slave has previously been enabled. When a single Modbus TCP connection is created, the value of this connection bit offset changes to 2.						
	Request Packet Interval (RPI)	The refresh period for this connection, from 2 to 65535 ms. Default = 12 ms. Type in <b>30</b> ms.						
	<b>NOTE:</b> This parameter can be set in the DTM for the communication module or the remote device.							
	Time-out Multiplier	ne-out Multiplier This setting, multiplied against the RPI, produces a value that triggers an inactivity timeout. Setting selections include: x4, x8, x16, x32, x64, x128, x256 and x512. Accept the default of x4.						
	<b>NOTE:</b> The Connection Information page is read-only when the communication module is selected. This information needs to be set in the DTM for the remote device.							
5	Click OK to save yo	ur settings.						

## Configuring Connection Settings in the Remote Device DTM

Connections between a communication module and remote device can be created and edited in the DTM for the remote device.

In this example, the following configuration edits are made to the connection that Unity Pro automatically created, when the remote device was added to the project. Use settings that are appropriate for your actual application:

Step	Action				
1	<ul> <li>Open the DTM for the remote device—in this example NIC2212_01—by selecting it in the Device Editor, then do one of the following:</li> <li>in the main menu, select Edit →Open, or</li> <li>click the right mouse button, and select Open in the pop-up menu</li> <li>The remote device DTM opens in the Device Editor.</li> </ul>				
2	In the navigation pane (on the left side of the <b>Device Editor</b> ), confirm that the remote device connection is of the type <b>Read Input / Write Output Data</b> . To view the connection type, select <b>NIC2212_01</b> in the left pane of the <b>Device Editor</b> . If the connection type is not of the type <b>Read Input / Write Output Data</b> , delete the existing connection and add a new one, as follows:				
	а	With the connection selected in the left pane, click the <b>Remove Connection</b> button. The existing connection is removed.			
	b	Click the Add Connection button. The Select the connection to add dialog opens.			
	c Use the scroll buttons on the drop down list to display and select the <b>Read Input</b> <b>Output Data</b> connection type.				
	d	Click <b>OK</b> to close the <b>Select the connection to add</b> dialog. The new connection node appears.			
	е	Click <b>Apply</b> to save the new connection, leaving the <b>Device Editor</b> open for additional edits.			

Step	Action		
3	With the Read Input / Write Output Data	node selected, cli	ick on the <b>General</b> tab:
	General Identity Check		
	Group/Parameter	Value	Unit
	▶ RPI	30	ms
	📮 🧰 Input T -> O		
	Input size	19	bytes
	Input mode	Multicast	
	📄 🖓 Input type	Fixed	
	► Input priority	Scheduled	
	Input trigger	Cyclic	
	Dutput O -> T	0	
	Output size	6	bytes
	Output mode	Point to Point	
	Output type	Fixed	
	Dutput priority	Scheduled	
	DescriptionOK	Cancel	Apply

Step	Action						
4	In the General page, edit the following settings:						
	RPI	The refresh period for this connection. Accept the value of <b>30</b> ms. (This parameter can be in the DTM for the communication module or the remote device.)					
	Input size	The number of bytes reserved for input data, from 0 to 505. Type in <b>19</b> .					
		<b>NOTE:</b> Unity Pro reserves input data in increments of 4 bytes (2 words). In this example, typing in the value of 19 bytes reserve 20 bytes of input memory.					
	Input mode	The transmission type: • Multicast • Point to Point					
		Accept the default selection of Multicast.					
	Input type	Ethernet packet type—fixed or variable length—to be transmitted. Only <b>Fixed</b> length packets are supported.					
	Input priority	<ul> <li>The transmission priority. The value depends upon the device DTM. Values can include:</li> <li>Low</li> <li>High</li> <li>Scheduled</li> </ul>					
		<b>NOTE:</b> For remote modules that support more than one priority value, you can use this setting to specify the order in which the Ethernet communication module will handle packets. For more information, refer to the topic describing QoS Packet Prioritization (see Quantum, 140 NOC 771 01 Ethernet Communication Module, User Manual).					
		For the purpose of this example, accept the default selection of <b>Scheduled</b> .					
	Input trigger	<ul><li>The transmission trigger. Values can include:</li><li>Cyclic</li><li>Change of state or application</li></ul>					
		For input I/O data, select <b>Cyclic</b> .					
	Output size	The number of bytes reserved for output data, from to 509. Type in 6.					
		<b>NOTE:</b> Unity Pro reserves output data in increments of 4 bytes (2 words). In this example, typing in the value of 6 bytes reserves 8 bytes of output memory.					
	Output mode	Accept the default selection of <b>Point to Point</b> .					
	Output type	(Read-only). Only Fixed length packets are supported.					
	Output priority	Accept the default selection of Scheduled.					

Step	Action					
5	Click on the Identity Check tab to open the following page:					
	General	Identity Check				
		Parameter Value Unit				
		Check Identity Disable				
	Description	n				
		OK Cancel Apply				
6	In the <b>Identity Check</b> page, set rules for comparing the identity of the remote device, as defined by its DTM or EDS file, against the identity of the actual remote device located on the network. Complete the following settings:					
	Check Identity	<ul> <li>Define the rule Unity Pro will use in comparing the configured versus the actual remote device. Settings include:</li> <li>Must match exactly—the DTM or EDS file exactly matches the remote device</li> <li>Disable—no checking occurs; the identity portion of the connection is filled with zero values (the default setting)</li> <li>Must be compatible—if the remote device is not the same as defined by the DTM/EDS, it emulates the DTM/EDS definitions</li> <li>None—no checking occurs; the identity portion of the connection is omitted</li> <li>Custom—enables the following 6 parameter settings, to be set individually.</li> <li>For this example, select Disable.</li> </ul>				
	If Check identity is set to Custom, complete the following 6 fields:					
	Compatibility Mode	<ul> <li>True—for each of the following selected tests, the DTM/EDS and remote device need only be compatible</li> <li>False—for each of the following selected tests, the DTM/EDS and remote device need to match exactly</li> </ul>				
	Minor Version	For each of the parameters to the left, select one of the following settings:				
	Major Version	<ul> <li>Compatible—include the parameter in the test</li> <li>Not checked—the parameter is not included in the test</li> </ul>				
	Product Code					
	Product Type					
	Product Vendor					
7	Click OK to sav	e your settings.				

The next step is to configure I/O settings.

# **Connecting to the Advantys STB Island**

### **Overview**

In this example, you will use the Advantys configuration software running on your PC to:

- connect the Advantys configuration software to the STB NIC 2212 and the 8 I/O modules that comprise the Advantys STB island
- upload Advantys STB island configuration to the Advantys configuration software in your PC
- display a fieldbus image for the Advantys STB island showing the relative location of:
  - status information
  - input data
  - output data

Using the data presented in the fieldbus image, you can use Unity Pro to create input and output items that map to specific status, input, output, and output echo data.

**NOTE:** Before proceeding with the following instructions, confirm that you have auto-configured the Advantys STB island by pressing the **RST** button on the front of the STB NIC 2212 module.

### **Making the Connection**

To connect to the STB NIC 2212 and I/O modules using the Advantys configuration software:

Step	Action				
1	Startup the Advantys configuration software on your PC. A dialog opens displaying available project types.				
2	Select STB.				
3	Select File New Workspace. The New Workspace window opens (below).				
4	<ul> <li>For this example, type in the following field values:</li> <li>for the field Workspace File type in Advantys</li> <li>for the field Island File type in Advantys_01</li> </ul>				
	📓 New Workspace				
	Workspace File     Island File       Name:     Name:       Advantys     Advantys_01				
	Location: C:\Program Files\Schneid Name with path: C:\Program Files\Schneider				
	C:\Program Files\Schneider				
5	Click <b>OK</b> . The Advantys configuration software displays an empty DIN rail in the center of the screen.				

Step	Action					
6	Select <b>Online</b> $\rightarrow$ <b>Connection Settings</b> . The <b>Connection Settings</b> window opens (below).					
7	In the <b>Connection Settings</b> window, accept the <b>Modbus Node ID</b> default setting of <b>1</b> , select <b>TCP/IP</b> , and click the <b>Settings</b> button:					
	Connection Settings					
	Connection Type Serial TCP/IP Settings Modbus Node ID 1 1 1 - 247 OK Cancel					
	The TCP/IP Parameters dialog opens (below).					
8	In the <b>Remote IP Address</b> field, type in the IP address for the STB NIC 2212, in this example: <b>192.168.1.6</b> .					
	TCP/IP Parameters					
	Parameters Remote Name: Remote IP Address: 192 . 168 . 1 . 6					
	Derive IP from MAC IP <-> Name OK Cancel					
9	Click OK to close the TCP/IP Parameters dialog, and click OK again to close the Connection Settings dialog.					
10	Select Online					
	Data Transfer       Image: Configuration in the workspace does not match the configuration in the connected island. Please select one of the following options.         (Download into the island disabled. No configuration data available.)					
	Upload Download Cancel					

Step	Action
11	Select <b>Upload</b> in the <b>Data Transfer</b> dialog. The island workspace is populated with island data and shows the STB NIC 2212 and the island modules (below):
	NIC 2212 RWA EER MS NS NS NS NS NS NS NS NS NS N
	EtherNet/IP INPUT A A A A A A A A A A A A A A A A A A A
	Advantys
	1/127 2/- 3/1 4/2 5/3 6/4 7/5 8/6 9/7 10/8 11/-
	<ul> <li>Note: A box appears beneath each module containing one or two integers—for example 3/1. These integers serve the following purpose:</li> <li>The left-side integer (3 in this example) identifies the module's physical position—left to right—among the modules in the rack.</li> <li>The right side integer (1 in this example) identifies the module's relative.</li> </ul>
	<ul> <li>The right-side integer (1 in this example) identifies the module's relative position—left to right—among only data producing/receiving modules. If the module is not a data producing/receiving module (e.g. a power supply, or end of segment module) no right-side integer appears.</li> </ul>

Step	Action
12	Select Island
	Image page:
	I/O Image Overview
	Fieldbus Image   HMI <-> PLC
	Input Data Word   15   14   13   12   11   10   9   8   7   6   5   4   3   2   1   0
	1         S
	3         -         -         5         5         5         5         4
	5 6 6 6 6 6 6
	7 7 7 7 7 7 7 7 7
	8         7
	10 8 8 8 8 8 8
	Location: Word 1, Bit 15
	Family: Networking Module: STBNIC2212 - V2.xx (1/1/127)
	ttem: NIM status bit -> EtherNet/IP Label: NIM Status WD
	Label: NIM _Status_WD Output Data
	Word         15         14         13         12         11         10         9         8         7         6         5         4         3         2         1           1         -         -         6         6         6         6         -         -         4         4         4         2         2
	2         8
	ок
	Each table cell contains one of the following alpha-numeric indicators:
	<ul> <li>S indicates a status bit for the STB NIC 2212 network interface module</li> </ul>
	• an integer identifies the relative position—from left to right—of a data
	<ul> <li>producing/receiving module with input or output data in that cell. For example:</li> <li>the STB DDI 3230 input module is the first data producing or receiving module</li> </ul>
	in the rack; its data is designated by the integer 1 in bits 0 - 3 of word 2 in the
	<ul> <li>Input Data table</li> <li>the STB DDO 3600 output module is the sixth data producing module in the</li> </ul>
	rack; its status and output echo data is designated by the integer 6 in bits 8 -
	13 of word 4 and in bits 0 - 5 of word 5 in the <b>Input Data</b> table; its output data
	is designated by the integer 6 in bits 8 - 13 of word 1 in the <b>Output Data</b> table <b>Notes:</b>
	Select a cell in either the Input Data or Output Data tables to display—in the middle
	of the page—a description of the cell data and its source module.
	Convert the size of the <b>Input Data</b> table and the <b>Output Data</b> table from words to bytes (i.e. divide by 2), then use that data as the values for the <b>Input Size</b> (19) and
	<b>Output Size</b> (6) parameters when configuring the remote device's connection
	properties.

# **Configuring I/O Items**

## Overview

The final task in this example is to add I/O items to the configuration of the STB NIC 2212 and its 8 I/O modules. To accomplish this:

- use the Advantys configuration software to identify the relative position of each I/O module's inputs and outputs
- use the Unity Pro Device Editor to create input and output items, defining each item's:
  - name
  - data type

## I/O Item Types and Sizes

The goal is to create a collection of input items and output items that equal the input size and output size specified for the STB NIC 2212 (see *Quantum, 140 NOC 771 01 Ethernet Communication Module, User Manual*). In this example, items need to be created for:

- 19 bytes of inputs
- 6 bytes of outputs

The Unity Pro **Device Editor** provides great flexibility in creating input and output items. You can create input and output items in groups of 1 or more single bits, 8-bit bytes, 16-bit words, 32-bit dwords, or 32-bit IEEE floating values. The number of items you create depends upon the data type and size of each item.

In the sample project, the following items were created:

- discrete bits for digital inputs and outputs
- 8-bit bytes or 16-bit words for analog inputs and outputs

## Mapping Input and Output Items

Use the **Fieldbus Image** page of the **I/O Image Overview** window in the Advantys configuration software to identify the number and type of I/O items you need to create, as follows:

Step	Action
1	In the Advantys configuration software, select Island $\rightarrow$ I/O Image Overview. The I/O Image window opens to the Fieldbus Image page.
2	Select the first cell (word 1, cell 0) in the <b>Input Data</b> table to display—in the middle of the page—a description of the cell data and its source module.
3	Make a note of the word, bit(s), module and item information for that cell.
4	Repeat steps 2 and 3 for each cell containing either an S or an integer.

**NOTE:** The Fieldbus Image presents input and output data in the form of 16-bit words (starting with word 1). You need to rearrange this data for the Unity Pro Ethernet Configuration Tool, which presents the same data in the form of 8-bit bytes (starting with byte 0).

NOTE: When you create items, align items of data type WORD and DWORD, as follows:

- WORD items: align these items on a 16-bit boundary
- DWORD items: align these items on a 32-bit boundary.

This process yields the following tables of input and output data:

Input Data:

Advantys Fieldbus Image		Unity Pro EIP Items		STB Module	Description
Word	Bit(s)	Byte	Bit(s)	-	
1	0-15	0	0-7	NIC 2212	low byte status
		1	0-7	-	high byte status
2	0-1	2	0-1	DDI 3230	input data
	2-3	-	2-3	DDI 3230	input status
	4-5		4-5	DDO 3200	output data echo
	6-7		6-7	DDO 3200	output status
	8-11	3	0-3	DDI 3420	input data
	12-15		4-7	DDI 3420	input status
3	0-3	4	0-3	DDO 3410	output data echo
	4-7		4-7	DDO 3410	output status
	8-13	5	0-5	DDI 3610	input data
	14-15		6-7	NA	not used
4	0-5	6	0-5	DDI 3610	input status
	6-7		6-7	NA	not used
	8-13	7	0-5	DDO 3600	output data echo
	14-15		6-7	NA	not used
5	0-5	8	0-5	DDO 3600	output status
	6-15	8	6-7	NA	not used
		9	0-7	-	
6	0-15	10	0-7	AVI 1270	input data ch 1
		11	0-7	_	
7	0-7	12	0-7	AVI 1270	input status ch 1
	8-15	13	0-7	NA	not used
8	0-15	14	0-7	AVI 1270	input data ch 2
		15	0-7	1	
9	0-7	16	0-7	AVI 1270	input status ch 2
	8-15	17	0-7	AVO 1250	output status ch 1

Advantys Fie	Idbus Image	Unity Pro	EIP Items	STB Module	Description
Word	Bit(s)	Byte	Bit(s)		
10	0-7	18	0-7	AVO 1250	output status ch 2
	8-15	NA	NA	NA	not used

Output Data:

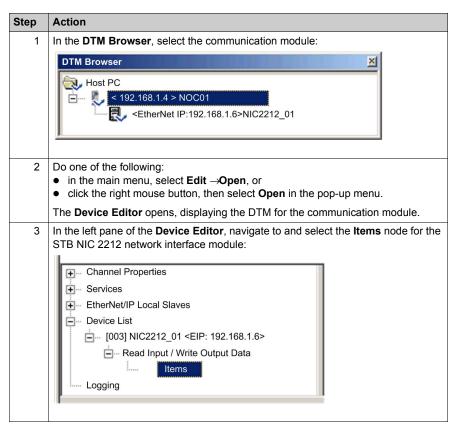
Advantys Fie	ldbus Image	Unity Pro	EIP Items	Module	Description
Word	Bit(s)	Byte	Bit(s)		
1	0-1	0	0-1	DDO 3200	output data
	2-5		2-5	DDO 3410	output data
	6-7		6-7	NA	not used
	8-13	1	0-5	DDO 3600	output data
	14-15		6-7	NA	not used
2	0-15	2	0-7	AVO 1250	output data ch 1
		3	0-7		
3	0-15	4	0-7	AVO 1250	output data ch 2
		5	0-7		

This example shows you how to create 19 bytes of inputs and 6 bytes of outputs. To more efficiently use space, this example creates items in the following sequence:

- input bit items
- input byte and word items
- output bit items
- output byte and word items

### **Creating Input Bit Items**

To create input bit items for the STB NIC 2212 example, beginning with 16 discrete inputs for NIC 2212 status:



4										
	The Items	window	opens:							
	Input	Input (bi	it) Outp	ut Í (	Dutput (bit)	1				
	Offs	et/Device	Offset/Conne	ection	Item Name			Default Ite	em Name Root	
		0		0				BLOC	KA	
		1		1				1 BEOO	U.L.	
		2		3						
		4		4				Det	fine Item(s)	
		5		5				Del	ete Item(s)	
		6		6 7				Den	ete iterri(3)	
		8		8				Shov	v Properties	
		9		9						
		10		10			•			
	- an arra	ау								
					ОК		C	Cancel	Apply	
5	Select the	Innut (b	it) tab to d	isplav t	hat nage	2				
6							ot n	amere	presenting	hovi
Ũ									3232_in_da	
7	In the Item					iput b				ια.
	in byte.)	1 <b>s List</b> , s	elect the fi	rst 2 ro				ese rows	s represent	
	in byte.)		elect the fi	rst 2 ro <sub>Output</sub>	ws in the		. (Th	ese rows	s represent	
	1	Inp Device Off	ut (bit)	Output	ws in the	table	. (Th	1	n Name Root	
	Input	Inp Device Off 0	ut (bit) set/Connection 0	Output	in Byte Ite	e table	. (Th	Default Iter	n Name Root	
	Input	Device Off 0 0	ut (bit) set/Connection 0 0	Output	in Byte Ite	e table	. (Th	1	n Name Root	
	Input	Device Off	ut (bit) set/Connection 0 0 0 0	Output	in Byte Ite	e table	. (Th	Default Iter	n Name Root	
	Input Offset/E	Device Offi 0 0 0 0 0 0 0 0	ut (bit) set/Connection 0 0 0 0 0	Output	in Byte Itte	e table	. (Th	Default Iter	n Name Root	
		Device Offi 0 0 0 0 0 0 0 0 0 0	ut (bit) set/Connection 0 0 0 0 0 0 0	Output	in Byte Itte	e table	. (Th	Default Iter	n Name Root 2_in_data ne Item(s)	
		Device Offi 0 0 0 0 0 0 0 0	ut (bit) set/Connection 0 0 0 0 0	Output	in Byte Itte	e table	. (Th	Default Iter	n Name Root	
	Input	Device Off 0 0 0 0 0 0 0 0 0 0 0 0 0 0 1	ut (bit) set/Connection 0 0 0 0 0 0 0 0 0 0 1	Output	in Byte Itte	e table	. (Th	Default Iter	n Name Root 2_in_data ne Item(s)	
		Device Off 0 0 0 0 0 0 0 0 0 0 0 0 0 0	ut (bit) set/Connection 0 0 0 0 0 0 0 0 0 0 0 0 0	Output	in Byte Itte	e table	t)	Default Iter	n Name Root 2_in_data ne Item(s) te Item(s)	
		Device Off 0 0 0 0 0 0 0 0 0 0 0 0 0 0 1	ut (bit) set/Connection 0 0 0 0 0 0 0 0 0 0 1	Output	ws in the	e table	t)	Default Iter	n Name Root 2_in_data ne Item(s) te Item(s)	
	Input	Inp           0         0           0         0           0         0           0         0           0         0           0         0           1         1	ut (bit) set/Connection 0 0 0 0 0 0 0 0 0 0 1	Output	ws in the 0 1 2 3 4 5 6 7 0 1 1	Dutput (bi	t)	Default Iter	n Name Root 2_in_data ne Item(s) te Item(s)	

Step	Action	ı				
8	Click th	he <b>Define I</b>	tem(s) button	. The Item I	Name Definitio	on dialog opens:
	Item N	lame Definitio	n	×		
	Defin Item(		ea As One or Seve	ral Single		
		Name: 3232_in_data_	1×*			
		5252_III_Uata_				
		ок	Cancel	Help		
		The asteris created.	k (*) indicates	a series of	discrete items	with the same root name
9			t Item Name a	and click <b>O</b>	2 discrete in	out items are created:
Ŭ	-					
		and the second s				
		nput Ir	nput (bit)	Output	Output (bit)	
		Offset/Device	Offset/Connection		Item Name	Default Item Name Root
		Offset/Device	Offset/Connection	Position in Byte	Item Name DDI3232_in_data_I)	(0 DDI3232 in data
		Offset/Device	Offset/Connection 0 0	Position in Byte 0 1	Item Name	(0 DDI3232 in data
		Offset/Device	Offset/Connection	Position in Byte 0 1 2	Item Name DDI3232_in_data_I)	<0 DDI3232_in_data
	1	Offset/Device	Offset/Connection 0 0 0 0 0 0	Position in Byte 0 1	Item Name DDI3232_in_data_I)	(0 DDI3232 in data
	1	Offset/Device	Offset/Connection 0 0 0 0 0 0 0 0	Position in Byte 0 1 2 3 4 5	Item Name DDI3232_in_data_I)	CO DDI3232_in_data Define Item(s)
	1	Offset/Device	Offset/Connection 0 0 0 0 0 0 0 0 0 0	Position in Bytee 0 1 2 3 4 5 6	Item Name DDI3232_in_data_I)	<0 DDI3232_in_data
	1	Offset/Device	Offset/Connection 0 0 0 0 0 0 0 0 0 0 0 0 0	Position in Byte 0 1 2 3 4 5 6 7	Item Name DDI3232_in_data_I)	DDI3232_in_data
		Offset/Device 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	Offset/Connection 0 0 0 0 0 0 0 0 0 0	Position in Bytee 0 1 2 3 4 5 6	Item Name DDI3232_in_data_I)	CO DDI3232_in_data Define Item(s)
		Offset/Device 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	Offset/Connection 0 0 0 0 0 0 0 0 0 0 0 0 0 0 1 1	Position in Byte 0 1 2 3 4 5 6 6 7 0 0	Item Name DDI3232_in_data_I) DDI3232_in_data_I	DDI3232_in_data
		Offset/Device 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	Offset/Connection 0 0 0 0 0 0 0 0 0 0 1 1	Position in Byte 0 1 2 3 4 5 6 7 7 0 1	Item Name DDI3232_in_data_1) DDI3232_in_data_1)	CO DDI3232_in_data Define Item(s) Delete Item(s) Show Properties
	Select	Offset/Device 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	Offset/Connection 0 0 0 0 0 0 0 0 1 1 ck on the "Define Ite	Position in Byte 0 1 2 3 4 5 6 7 7 0 1	Item Name DDI3232_in_data_1) DDI3232_in_data_1)	CO DDI3232_in_data Define Item(s) Delete Item(s) Show Properties
	Select	Offset/Device 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	Offset/Connection 0 0 0 0 0 0 0 0 1 1 ck on the "Define Ite	Position in Byte 0 1 2 3 4 5 6 7 7 0 1	Item Name DDI3232_in_data_1) DDI3232_in_data_1)	CO DDI3232_in_data Define Item(s) Delete Item(s) Show Properties
	Select	Offset/Device 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	Offset/Connection 0 0 0 0 0 0 0 0 1 1 ck on the "Define Ite	Position in Byte 0 1 2 3 4 5 6 7 7 0 1	Item Name DDI3232_in_data_1) DDI3232_in_data_1)	CO DDI3232_in_data Define Item(s) Delete Item(s) Show Properties
	Select	Offset/Device 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	Offset/Connection 0 0 0 0 0 0 0 0 1 1 ck on the "Define Ite	Position in Byte 0 1 2 3 4 5 6 7 7 0 1	Item Name DDI3232_in_data_1) DDI3232_in_data_1) DDI3232_in_data_1)	<pre>     DDI3232_in_data     Define Item(s)     Delete Item(s)     Show Properties     </pre>
	Select	Offset/Device 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	Offset/Connection 0 0 0 0 0 0 0 0 1 1 ck on the "Define Ite	Position in Byter 0 1 2 3 4 5 6 7 0 1 m(s)" button to c	Item Name DDI3232_in_data_1) DDI3232_in_data_1) DDI3232_in_data_1)	<ul> <li>DDI3232_in_data</li> <li>Define Item(s)</li> <li>Delete Item(s)</li> <li>Show Properties</li> </ul>
10	Select	Offset/Device	Offset/Connection 0 0 0 0 0 0 0 0 1 1 ck on the "Define Ite	Position in Byte 0 1 2 3 4 5 6 7 0 1 sm(s)" button to c	Item Name DDI3232_in_data_l) DDI3232_in_data_l) reate	<ul> <li>DDI3232_in_data</li> <li>Define Item(s)</li> <li>Delete Item(s)</li> <li>Show Properties</li> </ul>

Step	Action
11	<ul> <li>Repeat steps 6 - 10 for each group of discrete input items you need to create. In this example, that includes items for each of the following groups:</li> <li>Byte: 0, Bits: 2-3, Default Items Name Root: DDI3230_in_st</li> <li>Byte: 0, Bits: 4-5, Default Items Name Root: DDO3200_out_echo</li> <li>Byte: 0, Bits: 6-7, Default Items Name Root: DDO3200_out_st</li> <li>Byte: 1, Bits: 0-3, Default Items Name Root: DDI3420_in_data</li> <li>Byte: 2, Bits: 0-3, Default Items Name Root: DDO3410_out_echo</li> <li>Byte: 2, Bits: 0-3, Default Items Name Root: DDO3410_out_echo</li> <li>Byte: 3, Bits: 0-5, Default Items Name Root: DDI3410_out_st</li> <li>Byte: 4, Bits: 0-5, Default Items Name Root: DDI3610_in_data</li> <li>Byte: 4, Bits: 0-5, Default Items Name Root: DDO3600_out_echo</li> <li>Byte: 5, Bits: 0-5, Default Items Name Root: DDO3600_out_echo</li> </ul>
12	The next task is to create input bytes and words.

# **Creating Input Items**

To create input items for the STB NIC 2212 example, begin with an input data byte containing low byte status for the STB NIC 2212 module:

Step	Action
1	Select the <b>Input</b> tab to return to that page:
	Input Input (bit) Output Output (bit)
	Offset/Device Offset/Connection Item Name Default Item Name Root
	Define Item(s)
	6 6 Delete Item(s)
	8 8 Show Properties
	9 9
	Select a zone and click on the "Define Item(s)" button to create         - one or several items         - an array         OK       Cancel
	<b>NOTE:</b> In this example, both the <b>Offset/Device</b> and <b>Offset/Connection</b> columns represent the byte address. The items you create will be either an 8-bit byte or a 16-bit word
2	In the Default Item Name Root input box type: NIC22212_01_LO_st.

Step	Action
3	Starting at the first available whole input word, select the single row at byte 8:
	Input Input (bit) Output Output (bit)
	Offset/Device Offset/Connection Item Name     Default Item Name Root
	0 0 NIC221 01 LO st
	3 3 4 4
	8     8       9     9
	- one or several items - an array
	OK Cancel Apply
4	Click the <b>Define Item(s)</b> button. The <b>Item Name Definition</b> dialog opens:
	Item Name Definintion
	New Item(s) Data Type:
	Byte
	Define Selected Area As:
	One or Several Single Item(s)
	Item Name (32 char max):
	NIC2212_01_LO_st_IB8
	,
	OK Cancel Help

Step	Action
5	Select <b>Byte</b> as the <b>New Item(s) Data Type</b> , then click <b>OK</b> . A new byte item is created:
	Input Input (bit) Output Output (bit)
	Offset/Device       Offset/Connection       Item Name         0       0       0         1       1       1         2       2       0         3       3       0         4       4       0         5       5       0         6       6       0         9       9       0         10       10       0
	- one or several items - an array OK Cancel Apply
6	Click <b>Apply</b> to save the new items, and leave the page open.
7	<ul> <li>Repeat steps 2 - 6 for each byte or word input item you need to create.</li> <li>NOTE: The number of rows you select for a new item depends upon the item type. If the item is a:</li> <li>byte: select a single row</li> <li>word: select two rows, beginning at the next available whole word</li> <li>In this example, you will create items for each of the following:</li> <li>Byte: 9, Default Items Name Root: NIC2212_01_HI_st</li> <li>Word: 10, Default Items Name Root: AVI1270_CH1_in_data</li> <li>Byte: 12, Default Items Name Root: AVI1270_CH1_in_st</li> <li>Word: 14-15, Default Items Name Root: AVI1270_CH2_in_data</li> <li>Byte: 16, Default Items Name Root: AVI1270_CH2_in_st</li> <li>Byte: 17, Default Items Name Root: AVO1250 CH1 out st</li> </ul>
	<ul> <li>Byte: 18, Default Items Name Root: AVO1250_CH2_out_st</li> </ul>
8	The next task is to create output bits.

## **Creating Output Bit Items**

To create output bit items for the STB NIC 2212 example, beginning with 2 output bits for the STB DDO3200 module:

Step	Action		
1	Select the Output (bit) tab to op	en the following page	2:
	Input Input (bit) Output	Output (bit)	
	Offset/Device Offset/Connection Position	in Byte Item Name	Default Item Name Root
		0	BLOCKA
		2	
		4	Define Item(s)
	$ \begin{vmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 &$	5	Delete Item(s)
	0 0	7	Show Properties
		0	Show Properties
		2	
	Select a zone and click on the "Define Item - one or several item(s)	s)" button to create	
	L	1	
		OK	Cancel Apply
	NOTE: Both the Offset/Device a	and Offset/Connecti	on columns represent the
	byte address of an output, while	•	
	position—within the byte—of eac	ch discrete output iter	n.
2	In the Default Items Name Roo	t input box type: DDC	03200_out_data.

Step	Action					
3	In the <b>Iten</b> 2 rows:	ns List, select th	e rows that co	prrespond to	o bits 0-1 in byte 0—i.e., the	first
	Input	Input (bit)	Output C	Dutput (bit)		
	Offset/D	Device Offset/Connectic	n Position in Byte	Item Name	Default Item Name Root	
		0 0 0 0	0		DDO3200_out_data	
	Ŏ	0 0	2			
		0 0	3		Define Item(s)	
		0 0	5		Delete Item(s)	
		0 0	6		Delete item(3)	
	ŏ	1 1	0		Show Properties	
		1 1 1 1	1		<b>•</b>	
4			outton. The <b>Ite</b>	ок em Name D	Cancel Apply Definition dialog opens:	1
		Definition		×		
		00_out_data_QX0		1		
	NOTE: Th	• • •	Help	s of discrete	e items with the same root na	ame

Step	Action
5	Accept the default output name and click OK. 2 discrete output items are crea
	Input Input (bit) Output Output (bit)
	Offset/Device Offset/Connection Position in Byte Item Name Default Item Name Root
	0 0 0 DDO3200_out_data_QX0
	0 0 1 DD03200_out_data_QX1
	0 0 0 3 0 0 0 4 Define Item(s)
	O         0         6         Delete Item(s)
	O 1 1 0 Show Properties
	- one or several item(s)
	OK Cancel Apply
6	Click Apply to save the new items, and leave the page open.
7	<ul> <li>Repeat steps 2 - 6 for each group of discrete output items you need to create. this example, that includes items for each of the following groups:</li> <li>Byte: 0, Bits: 2-5, Default Items Name Root: DDO3410_out_data</li> <li>Byte: 1, Bits: 0-5, Default Items Name Root: DDO3600_out_data</li> </ul>
8	The next task is to create output bytes and words.

# **Creating Numeric Output Items**

To create output items for the STB NIC 2212, example, beginning with an output data word for the STB AVO 1250 module:

1	Action Click on the Output	tab to open the	following page	e:	
	Input Input (	bit) Output	Output (bit)		
	Offset/Device	Offset/Connection	Item Name	C	efault Item Name Root
	0	0			BLOCKA
	1	1			BLOCKA
	2	2			
		3			Define Item(s)
	4	4			
		5			Delete Item(s)
					Show Properties
	Select a zone and clic - one or several items - an array	k on the "Define Item(s)	button to create		Show Properties
	- one or several items	k on the "Define Item(s)"	' button to create	Cancel	Show Properties
	- one or several items	ple, both the <b>Off</b>	ok set/Device an	d Offset/(	Apply Connection colun

Step	Action						
3	3 Starting at the next available whole word, select 2 rows: 2 and 3:						
	Input	Input (bit)	Output	Output (bit)	1		
	Offset/D	evice Offset/C	Connection	Item Name	Default Item Name Root		
		0	0		AVO1250_CH1_out_data		
		2	Input (bit) Output Output (bit) ice Offset/Connection Item Name Define Item(s) 2 2 2 4 4 4 5 5 5 Define Item(s) Define Item(s) Define Item(s) Show Properties and click on the "Define Item(s)" button to create Items OK Cancel Apply re Item(s) button. The Item Name Definition dialog opens: nintion ata Type: ad Area As: al Single Item(s)				
		4	4		Define Item(s)		
	Starting at the next available whole word, select 2 rows: 2 and 3:						
					Show Properties		
			"Define Item(s)" I	outton to create			
		la nema					
	1						
				ок	Cancel Apply		
			_				
4	Click the Def	ine Item(s)	button. The	Item Name De	finition dialog opens:		
		Data Type:					
	WORD						
	Define Selec	cted Area As:					
	One or Seve	eral Single Item(	5)	7			
	Item Name (	(32 char max):					
	AV01250_0	CH1_out_data_C	₹W2				
	ОК	Ca	ncel	Help			
					I		

Step	Action						
5	Accept the default output name and click <b>OK</b> . the following output word item is created:						
	Input Input (bit) Output Output (bit)						
	Offset/Device Offset/Connection Item Name      Default Item Name Root						
	0 0 0 AVO1250_CH1_out_data						
	1 1 2 2 AVO1250 CH1 out data QW2						
	16 3 3 Define Item(s)						
	Delete Item(s)						
	Select a zone and click on the "Define Item(s)" button to create - one or several items - an array OK Cancel Apply						
6	Click <b>Apply</b> to save the new item and leave the page open.						
7	Repeat steps 2 - 6 for the AVO 1250 channel 2 output data at bytes 4 and 5.						
8	Click <b>OK</b> to close the <b>Items</b> window.						
9	Select File →Save to save your edits.						

# Section 3.3 Adding a Modbus TCP Device to the Network

### **Overview**

This section extends the sample Unity Pro application, by describing how to:

- add an STB NIP 2212 Modbus TCP network interface module to your Unity Pro application
- configure the STB NIP 2212 module
- configure a Modbus TCP connection linking the BMX NOC 0401 communication module and the STB NIP 2212 network interface module

**NOTE:** The instructions in this chapter describe a single, specific device configuration example. Refer to the Unity Pro help files for additional information about alternative configuration choices.

### What Is in This Section?

This section contains the following topics:

Торіс		
Setting Up Your Network	171	
Adding an STB NIP 2212 Remote Device	173	
Configuring STB NIP 2212 Properties	175	
Connecting to the Advantys STB Island		
Configuring I/O Items	187	

# **Setting Up Your Network**

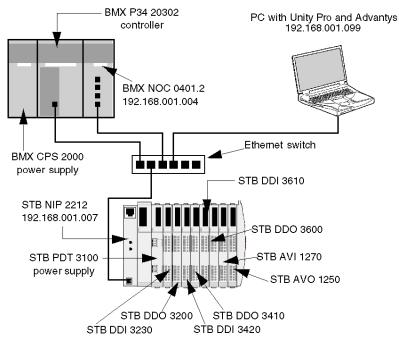
### Overview

This sample network includes the following hardware and software:

- a controller rack with:
  - BMX CPS 2000, 100/240 VAC power supply
  - BMX P34 20302 controller
  - BMX NOC 0401.2 Ethernet communication module
- a remote STB Advantys island with:
  - STB NIP 2212 Modbus TCP network interface module
  - STB PDT 3100 power distribution module
  - STB DDI 3230 2 pt digital input module
  - STB DDO 3200 2 pt digital output module
  - STB DDI 3420 4 pt digital input module
  - STB DDO 3410 4 pt digital output module
  - STB DDI 3610 6 pt digital input module
  - STB DDO 3600 6 pt digital output module
  - STB AVI 1270 2 pt analog input module
  - STB AVO 1250 2 pt analog output module
- a PC running both Unity Pro (version 5.0 or higher) and Advantys configuration software (version 5.0 or higher)
- an Ethernet managed switch that is connected to the both the controller and island by means of twisted pair Ethernet cable and RJ45 connectors.

## **Network Topology**

The Ethernet network devices used in this configuration include the following:



To re-create this example:

- use the IP addresses for your own configuration's:
  - PC
  - BMX NOC 0401.2 Ethernet communication module
  - STB NIP 2212 network interface module
- check wiring

**NOTE:** Unity Pro software running in the PC is used to configure the BMX P34 20302 controller. In this example, the PC is indirectly wired to the CPU's Ethernet port via the Ethernet switch. Alternatively, you could bypass the switch and directly wire the PC to either the CPU's Modbus or USB ports.

# Adding an STB NIP 2212 Remote Device

### **Overview**

Use the generic Modbus DTM selection, in the **Add** dialog, to select and insert an STB NIP 2212 module to your project.

### Adding an STB NIP 2212 Remote Device

To add the STB NIP 2212 to your project, follow these steps:

	Action							
In the <b>DTM Browser</b> , select the Ethernet communication module node, and then click the right mouse button. A pop-up menu opens.								
In the menu, select Add The following dialog opens:								
Add								
Device	Туре	Vendor	Version	•				
Advanced Generic EDS	Device	Schneider Electric	1.04.0001					
Generic Device	Device	Schneider Electric	1.04.0001					
Generic Device for Explicit Messa	Device	Device Schneider Electric *						
Modbus Device	Device	Schneider Electric	1.04.0001					
STBNIC2212 (from EDS)	Device	Schneider Electric	2.10					
TCDEI-888N-D1U (from EDS)	Device	Molex Incorporated	3.4					
TCDEI-888N-DYU (from EDS)	Device         Molex Incorporated           Device         Molex Incorporated	Molex Incorporated	3.4	_				
TCDEI-888P-D1U (from EDS)		3.4	•					
Add DTM Close								
0				perties				
	In the menu, select Add The follow Add	In the menu, select Add The following diale Add	In the menu, select Add The following dialog opens:           Add <ul></ul>	In the menu, select Add The following dialog opens:           Add <ul></ul>				

Step	Action
4	In the <b>General</b> page of the <b>Properties</b> window, edit the default <b>Alias name</b> to read <b>NIP2212_01</b> :
	Properties of
	General       Device Information       DTM Information       Protocol Information         DTM name management
	OK Cancel Help When you edit the Alias name, Unity Pro applies it as the base name for both structure and variable names.
	<b>NOTE:</b> No additional editing needs to be performed in the pages of this window. Except for the <b>Alias name</b> field, parameters are read-only.
5	Click <b>OK</b> . Unity Pro adds the new STB NIP 2212 network interface module to the <b>DTM Browser</b> , beneath the communication module.
6	Refer to the topic Configuring Properties in the Device Editor (see page 55) for instructions on how to save your configuration edits.

The next step is to configure the device you have just added to the project.

# **Configuring STB NIP 2212 Properties**

### **Overview**

Use the pages of the **Device Editor** to view and edit settings for a remote device. To edit the device settings, disconnect the DTM from the remote device (*see page 47*).

To display the DTM settings for a remote device, select the device name, which is found under the **Device List** node in the left pane of the **Device Editor**.

For the purposes of this example, which configures an STB NIP 2212 network interface module, select the node named **NIP2212\_01**. The **Device Editor** displays the following pages:

- Properties
- Address Setting
- Request Setting

**NOTE:** Refer to the topic Configuring Properties in the Device Editor (see page 55) for instructions on how to edit properties.

# **Configuring the Properties Page**

Use the **Properties** page to:

- add the remote device to, or remove it from, the configuration
- edit the base name for variables and data structures used by the remote device
- indicate how input and output items will be created and edited

The **Properties** page for an STB NIP 2212 network interface module looks like this:

Properties Address Setting F	Request Setting
┌ Properties	
Number: 004	Active Configuration: Enabled
Comment:	A V V
IO Structure Name	Default Name
Structure Name:	T_NIP2212_01_IN
Variable Name:	NIP2212_01_IN
Output	
Structure Name:	T_NIP2212_01_OUT
Variable Name:	NIP2212_01_OUT
Items Management	
Import Mode: Manual	Reimport Items
	OK Cancel Apply

Step	Action					
1	In the <b>Properties</b> section of the page, edit the following:					
	Number	The relative position of the device in the list, from 0127. For this example, accept the default of <b>004</b> .				
	Active Configuration	<ul> <li>Enabled: adds this device to the Unity Pro project configuration</li> <li>Disabled: removes this device from the Unity Proproject configuration</li> </ul>				
		Accept the default setting of <b>Enabled</b> .				
2	In the IO Structure Name s	ection of the page, edit the following:				
	Input area:					
	Structure Name	(Read-only) Unity Pro automatically assigns a structure name based on the variable name, in this case <b>T_NIP2212_01_IN</b> .				
	Variable Name	Accept the auto-generated variable name (based on the alias name (see page 173)): NIP2212_01_IN.				
	Output area:	Output area:				
	Structure Name	(Read-only) Unity Pro automatically assigns a structure name based on the variable name, in this case <b>T_NIP2212_01_OUT</b> .				
	Variable Name	Accept the auto-generated variable name (based of the alias name): NIP2212_01_OUT.				
	Default Name button	Restores the default variable and structure names. For this example, custom names are used.				
3	In the Items Management section of the page, edit the following:					
	Import mode	<ul> <li>Automatic: I/O items are taken from the device DTM and updated if the items list in the device DTM changes. Items cannot be edited in the Device Editor.</li> <li>Manual: I/O items are manually added in the Device Editor. The I/O items list is not affected by changes to the device DTM.</li> </ul>				
		In this example, select Manual.				
	Reimport Items	Imports the I/O items list from the device DTM, overwriting any manual I/O item edits. Enabled only when <b>Import mode</b> is set to <b>Manual</b> .				
4	Click Apply to save your ed	its, and leave the window open for further edits.				

The following settings are used in this sample configuration. Use settings that are appropriate for your actual application:

# **Configuring the Address Setting Page**

Use the Address Setting page to:

- configure the IP address for the remote device
- enable, or disable, DHCP client software for the remote device

When the DHCP client software is enabled in the remote device, it will obtain its IP address from the DHCP server in the Ethernet communication module. The **Address Setting** page looks like this:

Properties Address Setting R	equest Setting			
Change Address				
IP Address:	192 . 168 . 1 . 7			
Address Server:				
DHCP for this device	Enabled			
Identified by:	Device Name			
Identifier:	NIP2212_01			
Subnet Mask:	255 . 255 . 255 . 0			
Gateway:	0.0.0.0			
ОК	Cancel Apply			

Step	Action				
1	In the Address Settings page, edit the following:				
	IP Address	<ul> <li>By default:</li> <li>the first three octet values equal the first three octet values of the Ethernet communication module, and</li> <li>the fourth octet value equals this device Number setting—in this case, 004.</li> </ul>			
		In this example, the IP address is <b>192.169.1.7</b> .			
	DHCP for this Device	<ul> <li>Enabled activates the DHCP client in this device. The device obtains its IP address from the DHCP service provided by the Ethernet communication module and appears on the auto-generated DHCP client list (see page 80).</li> <li>Disabled (the default) de-activates the DHCP client in this device.</li> </ul>			
		Select Enabled.			
	Identified by	If DHCP for this Device is Enabled, this indicates the device identifier type: • MAC Address, or • Device Name Select Device Name.			
	Identifier	If <b>DHCP for this Device</b> is <b>Enabled</b> , the specific device MAC Address or Name value. Type in <b>NIP2212_01</b> .			
	Mask	The device subnet mask. The default = 255.255.255.0. Accept the default value.			
	Gateway	The gateway address used to reach this device. The default of 0.0.0.0 indicates this device is located on the same subnet as the Ethernet communication module. Accept the default value.			
2	Click Apply to save your ed	its, and leave the window open for further edits.			

The following settings are used in this sample configuration. Use settings that are appropriate for your actual application:

The next step is to configure the connection between the communication module and the remote device.

### **Configuring the Request Setting Page**

Use the **Request Setting** page to add, configure, and remove Modbus requests for the remote device. Each request represents a separate link between the communication module and the remote device.

The Request Setting page for an STB NIP 2212 network interface module looks like this:

Properties Address Setting		s Setting	Request Setting					
Connection Bit	Unit ID	Health Time Out	Repetitive Rate	RD Address	RD Length	Last Value	WR Address	WR Length
0	255	1500	60	5391	18	Hold Value	0	5
Add Request		Remove						
Add Request		Remove						
					OK	Ca	incel	Apply

The Add Request function is enabled only when Import Mode is set to Manual.

The following settings are used in this sample configuration. Use settings that are appropriate for your actual application:

Step	Action	
1	In the Reques	st Settings page, edit the following:
	Connection Bit	<ul> <li>(Read-only) The offset for both the health bit and the control bit for this connection. Offset values are auto-generated by the Unity Pro Ethernet Configuration Tool—starting at 0—based on the connection type, in the following order:</li> <li>1. Modbus TCP connections</li> <li>2. Local Slave connections</li> <li>3. EtherNet/IP connections</li> </ul>
		<b>NOTE:</b> When this Modbus TCP connection is created, the offset values for the previously created local slave and EtherNet/IP connections are incremented by 1: the local slave connection bit is set to 1, and the EtherNet/IP connection bit value is set to 2.
	Unit ID	<ul> <li>The number of the device, or module, that is the target of the connection. A value of:</li> <li>255 (the default) used to access the Ethernet communication module itself</li> <li>254 causes no Modbus message to be sent; the module reports an event</li> <li>0253 identifies the device number of the target device, behind a Modbus TCP to Modbus gateway</li> </ul>
		<b>NOTE:</b> When accessing data in the Ethernet communication module itself, use 255. When accessing data in the application running in the PLC, use a value from 0 to 254 (a value of 1 is recommended).
		Because the remote device itself is the request target, accept the default value of 255.
	Health Timeout	The maximum allowed period, in milliseconds, between device responses, from 0120000 ms in increments of 5 ms. When this setting is exceeded, the health timeout bit is set to 1. The default = 1500 ms. Accept the default value of <b>1500</b> .
	Repetitive Rate	The data scan rate, from 060000 ms, in intervals of 5 ms. The default = 60 ms. Accept the default value of <b>60</b> .
	RD Address	Address in the remote device of the input data image. The input data image begins at word 45391. Because there is an offset of 40000 in the M340 platform, type in a value of <b>5391</b> .
	RD Length	The number of words in the remote device, from 0125, that the communication module will read. Because the Modbus device will be configured for 18 words of input items, type in a value of <b>18</b> .
	Last Value	<ul><li>The behavior of inputs in the application in the event communication is lost:</li><li>Hold Value (the default)</li><li>Set To Zero</li></ul>
		Accept the default.
	WR Address	Address in the remote device of the output data image. The output data image begins at word 40000. Because there is an offset of 40000 in the M340 platform, type in a value of <b>0</b> .
	WR Length	The number of words in the remote device, from 0 to 120, to which the communication module will write. Because the Modbus device will be configured for 5 words of output items, type in a value of <b>5</b> .

Step	Action
2	Click <b>OK</b> to save your edits, and close the window.

The next step is to connect the Unity Pro project to the Advantys Island.

# **Connecting to the Advantys STB Island**

## **Overview**

In this example, you will use the Advantys configuration software running on your PC to:

- connect the Advantys configuration software to the STB NIP 2212 and the 8 I/O modules that comprise the Advantys STB island
- upload Advantys STB island configuration to the Advantys configuration software in your PC
- display a fieldbus image for the Advantys STB island showing the relative location of:
  - input data
  - output data

Using the data presented in the fieldbus image, you can use Unity Pro to create input and output items that map to specific input, output, and output echo data.

**NOTE:** Before proceeding with the following instructions, confirm that you have auto-configured the Advantys STB island by pressing the **RST** button on the front of the STB NIP 2212 module.

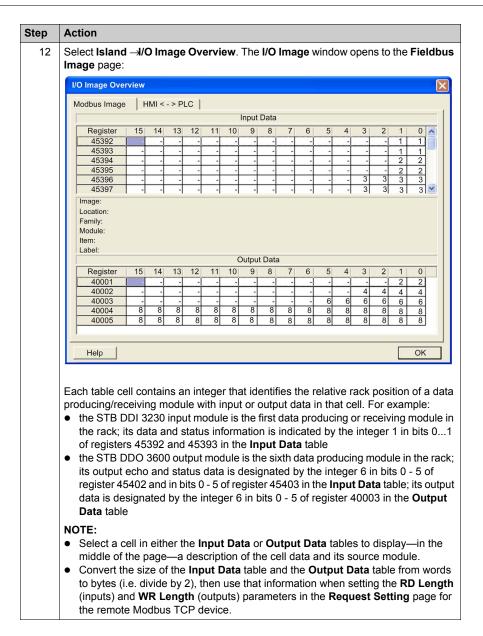
#### **Making the Connection**

To connect to the STB NIP 2212 and I/O modules using the Advantys configuration software:

Step	Action				
1	Startup the Advantys configuration software on your PC. A dialog opens displaying available project types.				
2	Select STB.				
3	Select File $\rightarrow$ New Workspace. The New Workspace window opens (below).				
4	<ul> <li>For this example, type in the following field values:</li> <li>for the field Workspace File type in Advantys</li> <li>for the field Island File type in Advantys_02</li> </ul>				
	Workspace   Workspace   Name:   Advantys   Location:   C:\Program Files\Schneider   Name with path:   C:\Program Files\Schneider   OK     Cancel				
5	Click <b>OK</b> . The Advantys configuration software displays an empty DIN rail in the center of the screen.				

Step	Action					
6	Select Online – Connection Settings. The Connection Settings window opens (below).					
7	In the <b>Connection Settings</b> window, accept the <b>Modbus Node ID</b> default setting of 1, select <b>TCP/IP</b> , and click the <b>Settings</b> button:					
	Connection Settings					
	Connection Type Serial TCP/IP Settings Modbus Node ID 1 1 1 - 247 OK Cancel					
	The <b>TCP/IP Parameters</b> dialog opens (below).					
8	In the <b>Remote IP Address</b> field, type in the IP address for the STB NIP 2212, in this example: <b>192.168.1.7</b> .					
	ICP/IP Parameters					
	Parameters Remote Name: Remote IP Address: 192 . 168 . 1 . 7					
	Derive IP from MAC IP <-> Name OK Cancel					
9	Click <b>OK</b> to close the <b>TCP/IP Parameters</b> dialog, and click <b>OK</b> again to close the <b>Connection Settings</b> dialog.					
10	Select Online Connect. The Data Transfer dialog opens (below):					
	Data Transfer       Image: Configuration in the workspace does not match the configuration in the connected island. Please select one of the following options.         (Download into the island disabled. No configuration data available.)					
	Upload Download Cancel					

Step	Action							
11	Select <b>Upload</b> in the <b>Data Transfer</b> dialog. The island workspace is populated with island data and shows the STB NIP 2212 and the island modules (below):							
	Ethernet INPUT A A A A A A A A							
	Advantys							
	1/127 2/ 3/1 4/2 5/3 6/4 7/5 8/6 9/7 10/8 11/							
	<ul> <li>Note: A box appears beneath each module containing one or two integers—for example 3/1. These integers serve the following purpose:</li> <li>The left-side integer (3 in this example) identifies the module's physical position—left to right—among the modules in the rack.</li> <li>The right-side integer (1 in this example) identifies the module's relative position—left to right—among only data producing/receiving modules. If the</li> </ul>							
	module is not a data producing/receiving module (e.g. a power supply, or end of segment module) no right-side integer appears.							



# **Configuring I/O Items**

## Overview

The next task in this example is to add I/O items to the configuration of the STB NIP 2212 and its 8 I/O modules. To accomplish this:

- use the Modbus Image page of the Advantys configuration software to identify the relative position of each I/O module's inputs and outputs
- use the Unity Pro Device Editor to create input and output items, defining each item's:
  - name
  - data type

NOTE: You can manually configure I/O items only when Input Mode is set to Manual.

## I/O Item Types and Sizes

Because the Modbus TCP network interface module transmits data in the form of 16-bit words, in this example you will create every input and output item using the **WORD** data type. This remains true even if the item contains only a few bits of data. Bit-packing is not permitted when, as in this example, the remote device is a Modbus TCP network interface module.

**NOTE:** When you add more devices to your network, it may be necessary to increase the size and index location of both inputs and outputs for your Unity Pro project (*see page 36*).

In this example, the following number and type of items need to be created:

- 18 input words
- 5 output words

# **Mapping Input and Output Items**

Use the **Fieldbus Image** page of the **I/O Image Overview** window in the Advantys configuration software to identify the number and type of I/O items you need to create, as follows:

Step	Action
1	In the Advantys configuration software, select Island $\rightarrow$ I/O Image Overview. The I/O Image window opens to the Modbus Image page.
2	Select the cell 0 of the first word (45392) in the <b>Input Data</b> table to display—in the middle of the page—a description of the cell data and its source module.
3	Make a note of the register number and item information for that word.
4	Repeat steps 2 and 3 for each word.

**NOTE:** The Modbus Image presents input and output data in the form of 16-bit words (starting with word 1). You need to maintain this data format as you create input and output items in Unity Pro.

NOTE: When you create items, align items of data type WORD and DWORD, as follows:

- WORD items: align these items on a 16-bit boundary
- DWORD items: align these items on a 32-bit boundary

This process yields the following tables of input and output data: Input Data (Read):

Advantys M	Iodbus Image	Unity Pro Items		STB Module	Description
Register	Bit(s)	Bytes	Bit(s)		
45392	0-1	0	0-1	DDI 3230	input data
		1	not used	_	
45393	0-1	2	0-1	DDI 3230	input status
		3	not used	_	
45394	0-1	4	0-1	DDO 3200	output data echo
		5	not used		
45395	0-1	6	0-1	DDO 3200	output status
		7	not used		
45396	0-3	8	0-3	DDI 3420	input data
		9	not used		
45397	0-3	10	0-3	DDI 3420	input status
		11	not used		
45398	0-3	12	0-3	DDO 3410	output data echo
		13	not used		
45399	0-3	14	0-3	DDO 3410	output status
		15	not used		
45400	0-5	16	0-5	DDI 3610	input data
		17	not used		
45401	0-5	18	0-5	DDI 3610	input status
		19	not used		
45402	0-5	20	0-5	DDO 3600	output data echo
		21	not used		
45403	0-5	22	0-5	DDO 3600	output status
		23	not used		
45404	0-15	24	0-7	AVI 1270	input data ch 1
		25	0-7		
45405	0-7	26	0-7	AVI 1270	input status ch 1
		27	not used	1	
45406	0-15	28	0-7	AVI 1270	input data ch 2
		29	0-7		

Advantys Mo	odbus Image	Unity Pro	Items	STB Module	Description
Register	Bit(s)	Bytes	Bit(s)		
45407	0-7	30	0-7	AVI 1270	input status ch 2
		31	not used		
45408	0-7	32	0-7	AVI 1270	output status ch 1
		33	not used		
45409	0-7	34	0-7	AVI 1270	output status ch 2
		35	not used		

Output Data (Write):

Advantys Mo	odbus Image	Unity Pro Items		STB Module	Description
Register	Bit(s)	Byte	Bit(s)		
40001	0-1	0	0-1	DDO 3200	output data
		1	not used		
40002	0-3	2	0-3	DDO 3410	output data
		3	not used	-	
40003	0-5	4	0-5	DDO 3600	output data
		5	not used		
40004	0-15	6	0-7	AVO 1250	output data ch 1
		7	0-7		
40005	0-15	8	0-7	AVO 1250	output data ch 2
		9	0-7		

This example shows you how to create 18 words of inputs and 5 words of outputs. This example creates items in the following sequence:

- input word items
- output word items

# **Creating Input Word Items**

To create input items for the STB NIP 2212 example, beginning with an input word for the DDI 3230 input module:

Step	Action
1	In the DTM Browser, select the communication module:
	DTM Browser
	Rest PC
	E
	EtherNet IP: 192.168.1.6 > NIC2212_01 Modbus: 192.168.1.7 > NIP2212_01
2	Do one of the following:
	<ul> <li>in the main menu, select Edit →Open, or</li> <li>click the right mouse button, then select Open in the pop-up menu.</li> </ul>
	The <b>Device Editor</b> opens, displaying the DTM for the communication module.
3	In the left pane of the <b>Device Editor</b> , navigate to and select the <b>Items</b> node for the
0	STB NIP 2212 network interface module:
	Channel Properties
	Services     EtherNet/IP Local Slaves
	Device List
	■ [003] NIC2212 01 <eip: 192.168.1.6=""></eip:>
	[004] NIP2212_01 <mdb: 192.168.1.7=""></mdb:>
	Request 1: Items
	Logging

4	Soloot the		open that page	JC.			
4				-			
	Input	Input (bit)	Output 0	Dutput (bit)			
	Offse	t/Device Offs	set/Connection	Item Name		Default Ite	m Name Root
		0	0			BLOCK	(A
		1	1		_     _	1	
		2 3	3		_		1
		4	4			Def	ine Item(s)
		5	5			Dek	ete Item(s)
		6	6 7			Dele	ete iterii(s)
		7 8	8			Show	Properties
		9	9				
		10	10		-		
					1	1	
				ОК	Car	ncel	Apply
١	will be a 16	bit word, ea	ach item cons	ists of 2 row	s.		e items you cr
5	will be a 16 In the <b>Defa</b>	bit word, ea		ists of 2 row it box type: <b>I</b>	s. DDI3230	_in_da	ta.
5	will be a 16 In the <b>Defa</b>	bit word, ea	ach item cons <b>me Root</b> inpu	ists of 2 row it box type: <b>I</b>	s. DDI3230	_in_da	ta.
5	will be a 16 In the <b>Defa</b> Starting at	b-bit word, ea <b>ult Item Na</b> the beginnir Input (bit)	ach item cons me Root inpung of the table	ists of 2 row it box type: <b>I</b> , select the f	s. DDI3230 irst two i	_in_da <sup>.</sup> ows: 0	ta. and 1:
5	will be a 16 In the <b>Defa</b> Starting at	b-bit word, ea <b>ult Item Na</b> the beginnir Input (bit) fset/Device C	ach item cons me Root inpu ng of the table Output	ists of 2 row it box type: <b>I</b> , select the f	s. DDI3230 irst two i	_in_da <sup>.</sup> ows: 0	ta.
5	will be a 16 In the <b>Defa</b> Starting at	b-bit word, ea <b>ult Item Na</b> the beginnir Input (bit)	ach item cons me Root inpu ng of the table Output Offset/Connection	ists of 2 row it box type: <b>I</b> , select the f	s. DDI3230 irst two i	_in_da fows: 0	ta. and 1:
5	will be a 16 In the <b>Defa</b> Starting at	b-bit word, ea <b>ult Item Na</b> the beginnir Input (bit) fset/Device C 0 1 2	ach item cons me Root inpu ng of the table Output Offset/Connection 1 2	ists of 2 row it box type: <b>I</b> , select the f	s. DDI3230 irst two i	_in_da fows: 0	ta. and 1: fault Item Name Roc
5	will be a 16 In the <b>Defa</b> Starting at	B-bit word, ea	ach item cons me Root inpu ng of the table Output Offset/Connection	ists of 2 row it box type: <b>I</b> , select the f	s. DDI3230 irst two i	_in_da fows: 0	ta. and 1: fault Item Name Roc
5	will be a 16 In the <b>Defa</b> Starting at	b-bit word, ea <b>ult Item Na</b> the beginnir Input (bit) fset/Device C 0 1 2	ach item cons me Root inpu ng of the table Output Offset/Connection	ists of 2 row it box type: <b>I</b> , select the f	s. DDI3230 irst two i	_in_da fows: 0	ta. and 1: fault Item Name Roc DDI3230_in_data
5	will be a 16 In the <b>Defa</b> Starting at	B-bit word, ea ult Item Na the beginnir Input (bit) Iset/Device C 0 1 2 3 4	ach item cons me Root inpu ng of the table Output Offset/Connection	ists of 2 row it box type: <b>I</b> , select the f	s. DDI3230 irst two i	_in_da fows: 0	ta. and 1: fault Item Name Roc DDI3230_in_data
5	will be a 16 In the <b>Defa</b> Starting at	B-bit word, ea ult Item Na the beginnir Input (bit) fset/Device C 0 1 2 3 4 5 6 7	ach item cons me Root inpu ng of the table Output Offset/Connection	ists of 2 row it box type: <b>I</b> , select the f	s. DDI3230 irst two i	_in_da fows: 0	ta. and 1: fault Item Name Roc DDI3230_in_data Define Item(s)
5	will be a 16 In the <b>Defa</b> Starting at	B-bit word, ea ult Item Na the beginnir Input (bit) fset/Device C 0 1 2 3 4 5 6 7 8	ach item cons me Root inpu- ng of the table Output Offset/Connection	ists of 2 row it box type: <b>I</b> , select the f	s. DDI3230 irst two i	_in_da fows: 0	ta. and 1: fault Item Name Roc DDI3230_in_data Define Item(s)
5	will be a 16 In the <b>Defa</b> Starting at	B-bit word, ea ult Item Na the beginnir Input (bit) fset/Device C 0 1 2 3 4 5 6 7	ach item cons me Root inpu- ng of the table Output Offset/Connection	ists of 2 row it box type: <b>I</b> , select the f	s. DDI3230 irst two i	_in_da rows: 0	ta. and 1: fault Item Name Roc DDI3230_in_data Define Item(s)
5	will be a 16 In the <b>Defa</b> Starting at	B-bit word, ea ult Item Na the beginnir Input (bit) fset/Device C 0 1 2 3 4 5 6 7 8 9 10	ach item cons me Root inpu- ng of the table Output Offset/Connection	ists of 2 row It box type: <b>I</b> , select the f Output (bit) Item Name	s. DDI3230 irst two i	_in_da fows: 0	ta. and 1: fault Item Name Roc DDI3230_in_data Define Item(s)
5	will be a 16 In the <b>Defa</b> Starting at	B-bit word, ea ult Item Na the beginnir Input (bit) fset/Device C 0 1 2 3 4 5 6 7 8 9 10	ach item cons me Root inpu- ng of the table Output Offset/Connection	ists of 2 row It box type: <b>I</b> , select the f Output (bit) Item Name	s. DDI3230 irst two i	_in_da rows: 0	ta. and 1: fault Item Name Roc DDI3230_in_data Define Item(s)

Step	Action
7	Click the Define Item(s) button. The Item Name Definition dialog opens:
	Item Name Definintion
	New Item(s) Data Type:
	WORD
	WORD
	Define Selected Area As:
	One or Several Single Item(s)
	Item Name (32 char max):
	DDI3230 in data IW0
	OK Cancel Help
	NOTE: The Define Item(s) button is enabled only when Input Mode is set to
-	Manual.
8	Select WORD as the New Item(s) Data Type, then click OK. A new item is created:
	Input Input (bit) Output Output (bit)
	Offset/Device Offset/Connection Item Name     Default Item Name Root
	16 0 0 DDI3230_in_data_IWO
	Define Item(s)
	6 6 Delete Item(s)
	7 7 8 8 Show Properties
	Select a zone and click on the "Define Item(s)" button to create
	- one or several items
	- an array
	OK Cancel Apply
9	Click <b>Apply</b> to save the new items, and leave the page open.

Step	Action
10	<ul> <li>Repeat steps 2 - 6 for each new word item you need to create. In this example, that includes the following items:</li> <li>Rows 2-3, Default Items Name Root: DDI3230_in_st</li> <li>Rows 4-5: Default Items Name Root: DDO3200_out_echo</li> <li>Rows 6-7: Default Items Name Root: DDI3420_in_data</li> <li>Rows 8-9: Default Items Name Root: DDI3420_in_st</li> <li>Rows 10-11: Default Items Name Root: DDI3420_in_st</li> <li>Rows 12-13: Default Items Name Root: DDO3410_out_echo</li> <li>Rows 14-15: Default Items Name Root: DDI3410_out_st</li> <li>Rows 16-17: Default Items Name Root: DDI3610_in_data</li> <li>Rows 18-19: Default Items Name Root: DDI3610_in_st</li> </ul>
	<ul> <li>Rows 20-21: Default Items Name Root: DDO3600_out_echo</li> <li>Rows 22-23: Default Items Name Root: DDO3600_out_st</li> <li>Rows 24-25: Default Items Name Root: AVI1270_CH1_in_data</li> <li>Rows 26-27: Default Items Name Root: AVI1270_CH1_in_st</li> <li>Rows 28-29: Default Items Name Root: AVI1270_CH2_in_data</li> <li>Rows 30-31: Default Items Name Root: AVI1270_CH2_in_st</li> <li>Rows 32-33: Default Items Name Root: AVO1250_CH1_out_st</li> <li>Rows 34-35: Default Items Name Root: AVO1250_CH2_out_st</li> </ul>
11	The next task is to create output words.

# Creating Output Word Items

To create output items for the STB NIP 2212, example, beginning with an output data word for the DDO 3200 output module:

Step	Action						
1	Click on the <b>Output</b> tab to open the following page:						
	Input Input (bit) Output Output (bit)						
	Offset/Device Offset/Connection Item Name Default Item Name Root						
	0 0 1 1 1 BLOCKA						
	2 2 3 3 4 4 Define Item(s)						
	Show Properties						
	Select a zone and click on the "Define Item(s)" button to create - one or several items - an array						
	OK Cancel Apply						
	<b>NOTE:</b> In this example, each row represents a byte. Because the items you create will be a 16-bit word, each item consists of 2 rows.						
2	In the Default Item Name Root input box type: DDO3200_out_data.						

Step	Action
3	Starting at the beginning of the table, select the first 2 rows, 0 and 1:
	Input Input (bit) Output Output (bit)
	Offset/Device Offset/Connection Item Name Default Item Name Root
	0 0 DDO3200_out_data
	2 2 3 3 Define Item(s)
	Delete Item(s)
	Show Properties
	Select a zone and click on the "Define Item(s)" button to create - one or several items
	- an array
	OK Cancel Apply
4	Click the Define Item(s) button. The Item Name Definition dialog opens:
	Item Name Definintion
	New Item(s) Data Type:
	WORD
	Define Selected Area As:
	One or Several Single Item(s)
	Item Name (32 char max):
	DDO3200_out_data_QW0
	OK Cancel Help
	NOTE: The Define Item(s) button is enabled only when Input Mode is set to
	Manual.

Step	Action					
5	Select <b>WORD</b> as the created:	New Item(s) D	<b>ata Type</b> , then	click OK. A new item is		
	Input Input (bit)	Output	Output (bit)			
		1	Item Name 03200_out_data_QW0	DDO3200_out_data		
		2 3 4 5		Define Item(s)		
	Select a zone and click or - one or several items - an array	the "Define Item(s)" b	utton to create	Show Properties Cancel Apply		
6	Click <b>Apply</b> to save the	ne new item and	d leave the pag	e open.		
7	<ul> <li>Repeat steps 2 - 6 for each new word item you need to create. In this example, that includes the following items:</li> <li>Rows 2-3, Default Items Name Root: DDO3410_out_data</li> <li>Rows 4-5: Default Items Name Root: DDO3600_out_data</li> <li>Rows 6-7: Default Items Name Root: AVO1250_CH1_out_data</li> <li>Rows 8-9: Default Items Name Root: AVO1250_CH2_out_data</li> </ul>					
8	Click OK to close the	Items window.				
9	Select File →Save to	save your edits	6.			

The next task is to update the Unity Pro application (see Quantum, 140 NOC 771 01 Ethernet Communication Module, User Manual).

# **Chapter 4** Working With Derived Data Types

## **Overview**

This chapter describes how to complete your project by creating, updating, and viewing derived data type (DDT) variables in Unity Pro.

# What Is in This Chapter?

This chapter contains the following topics:

Торіс			
Creating and Updating Derived Data Types	198		
Working with Derived Data Type Variables	200		
Effect of Activating and De-activating Devices on I/O %MW Memory Addresses	210		

# **Creating and Updating Derived Data Types**

# **Creating or Updating Derived Data Types**

After you have completed your edits in the **Device Editor**, the next step is to let Unity Pro create the necessary program objects—in the form of derived data types (DDTs) and variables—that will support your network design. To do this, follow these steps:

Step	Action								
1	In the <b>Project Browser</b> , navigate to and select the communication module.								
2	<ul> <li>Do one of the following:</li> <li>click the right mouse button, and select <b>Open</b> in the pop-up menu, or</li> <li>in the <b>Edit</b> menu, select <b>Open</b>.</li> </ul>								
	The <b>Configuration</b> page of the Ethernet communication module opens, below:								
	0.1 : BMX NOC 0401								
	Ethernet 4 Port 10/100 RJ45								
	Configuration								
	Project Network name: M_NOC0401								
	Inputs     Outputs       %MW Index:     0       Max size:     16								
	EIP connectivity network								
3	Click the Update application button.								
	NOTE:								
	<ul> <li>Every time you use the Device Editor to make changes to your Unity Pro project, return to this screen and click the Update application button to save your edits.</li> </ul>								
	<ul> <li>Unity Pro refreshes the collection of DDTs and variables—by adding, editing, or deleting previously generated DDTs and variables—each time you:</li> <li>click on the Update application button, above, or</li> <li>select either Build →Build Changes or Build →Rebuild All Project</li> </ul>								

Step	Action						
4	Click <b>OK</b> . The <b>Project Browser</b> displays the new or edited derived data types, below:						
	Documentation						

# Working with Derived Data Type Variables

### **Derived Data Type Variables**

When you click on the **Update application** button, Unity Pro creates a collection of derived data types and variables. These are used by Unity Pro to support communication and data transfer between the PLC and the various local slaves, remote devices, and their I/O items. You can access these derived data types and variables in the Unity Pro **Data Editor** and add them to a user-defined **Animation Table**, where you can monitor read-only variables and edit read-write variables.

Use these data types and variables to:

- view the status of connections from the communication module to remote EtherNet/IP and Modbus TCP devices, where:
  - the status of connections is displayed in the form of a HEALTH\_BITS array consisting of 32 bytes
  - each connection is represented by a single bit in the array
  - a bit value of 1 indicates the connection is healthy
  - a bit value of 0 indicates the connection is lost, or the communication module can no longer communicate with the remote device
- toggle a connection ON (1) or OFF (0) by writing to a selected bit in a 32 byte CONTROL\_BITS array

**NOTE:** Distinguish between toggling a bit in the CONTROL\_BITS array on or off, and enabling or disabling a remote device.

 monitor the value of local slave and remote device input and output items you created in the Unity Pro Device Editor

# Identifying Derived Variables in the Data Editor

To view your Unity Pro application's derived data type variables:

Step	Description							
1	In the <b>Project Browser</b> , navigate to and double-click the left mouse button on <b>Variables &amp; FB instances</b> → <b>Derived Variables</b> :							
	Project Browser							
	E Structural View							
	Project							
	E Configuration							
	🛨 🖳 Derived Data Types							
	Derived FB Types							
	Variables & FB instances Elementary Variables							
	Derived Variables							
	IO Derived Variables							
	Elementary FB Instances							
	Derived FB Instances							
	E Communication							
	Program							
	Animation Tables							
	Operator Screens							
	Documentation							

Step	Description						
2	The Data Editor opens, di	splaying the Varia	bles page:				
	👹 Data Editor				_ <b>_</b> _×		
		Function Blocks   DFB	Types				
	Filter			EDT			
	Name 🗠	Туре 🗸	Address -	Value	Comment -		
		T_NIC2212_01_IN	%MW39				
		T_NIC2212_01_OUT	%MW123				
	■ ● ● ■ NIP2212_01_IN	T_NIP2212_01_IN	%MW17				
		T_NIP2212_01_OUT	%MW117				
		T_NOC01_IN	%MW1				
	NOC01_LS1_IN	T_NOC01_LS1_IN	%MW35				
	NOC01_LS1_OUT	T_NOC01_LS1_OUT T_NOC01_OUT	%MW122 %MW101				
	NOC01_OUT		76101001				
		1	-	1			
	NOTE:						
	<ul> <li>A check mark appears i display these variables.</li> </ul>		ox. (If not, sele	ect the I	<b>DDT</b> checkbox		
	• The red arrow and lock	,	variable name	was au	uto-generated b		
	Unity Pro based on the cannot be edited.	configuration of th	e local slave	or remo	te device and		

## Displaying the Order of Input and Output Items in PLC Memory

The **Data Editor** displays the address of each input and output variable. Click once on the **Address** column header to sort input and output addresses in ascending order. When you open the first input and output variables, you can see both the connection health bits and the connection control bits:

Data Editor	DT Types   Fun	ction Blocks	DFB Ty	rpes			_0
Filter							DDT
Name	•	Туре	τ.	Address	Value	Comment	-
E-8 NOC01_I		T_NOC01_IN		%MW1		1	
😟 🔏 📑 HEALT	H_BITS_IN	ARRAY[031]	OF BYTE	%MW1			
😟 🙈 🗐 NIP2212	01_IN	T_NIP2212_01	L IN	%MW17			
😟 🙈 🔵 NOC01_L	S1_IN	T_NOC01_LS	1_IN	%MW35			
	01 IN	T NIC2212 01	1 IN	%MW39			
E 8 NOC01_0	DUT	T NOC01 OU	T	%MW101			
	ROL BITS OUT	ARRAY[031]	OF BYTE	%MW101			
+ NIP2212	01_OUT	T_NIP2212_01	OUT	%MW117			
DOC01 L	S1 OUT	T NOC01 LS	1 OUT	%MW122			
🗄 🔒 🗐 NIC2212	01_OUT	T_NIC2212_0*	1_OUT	%MW123			
			_				
,					÷		

Note the order of inputs and outputs in the above example. Recall that the user defines the size and location of inputs and outputs (see page 36). However, within the reserved area for both inputs and outputs, Unity Pro assigns addresses to variables in the following order:

Inputs	Order	Outputs				
Health bits <sup>1</sup>	1	Control bits <sup>1</sup>				
Modbus TCP input variables <sup>2</sup>	2	Modbus TCP output variables <sup>2</sup>				
Local Slave input variables <sup>3</sup>	3	Local Slave output variables <sup>3</sup>				
EtherNet/IP input variables <sup>2</sup>	4	EtherNet/IP output variables <sup>2</sup>				
<ul> <li>i. by device type: a. Modbus TCP; b. local slave; c. EtherNet/IP</li> <li>ii. within each device type:</li> <li>a. by device or local slave number</li> <li>b. within a device: by connection number</li> </ul>						
<ul> <li>2. Device variables are sub-ordered as follows:</li> <li>i. by device number</li> <li>ii. within a device: by connection number</li> <li>iii. within a connection: by item offset</li> </ul>						
<ul> <li>3. Local slave variables are sub-ordered as follows:</li> <li>i. by local slave number</li> <li>ii. within each local slave: by item offset</li> </ul>						

**NOTE:** When a device is added to or removed from the project, or when the active status of an existing device or a local slave changes, the specific location of inputs and outputs in PLC memory also changes.

### Identifying the Connection Health Bits

The Ethernet communication module can support up to 128 connections to remote devices. The health of each connection is represented in a single bit value. A health bit value of:

- 1 indicates the connection is active
- 0 indicates the connection is inactive

The health bits are contained in a 32-byte array in the **Variables** page of the **Data Editor**. To display offline this byte array, first sort the variables in ascending order of address, then open the first input variable as shown below:

😻 Data Editor								
Variables DDT Types Function Blocks DFB Types								
Filter	Filter							
Name 🔻	Туре 🔻	Address	Value	Comment 🔹 🔺				
E-8 NOC01_IN	T_NOC01_IN	%MW1	1					
🗄 🚜 📗 HEALTH_BITS_IN	ARRAY[031]OF BYTE	%MW1						
HEALTH_BITS_IN[0]	BYTE	%MW1						
	BYTE	%MW1						
HEALTH_BITS_IN[2]	BYTE	%MW2						
	BYTE	%MW2						
HEALTH_BITS_IN[4]	BYTE	%MW3						
HEALTH_BITS_IN[5]	BYTE	%MW3						
HEALTH_BITS_IN[6]	BYTE	%MW4						
HEALTH BITS IN[7]	BYTE	%MW4						
HEALTH_BITS_IN[7]	BYTE	%MW5		<u> </u>				

To determine which health bit is mapped to a specific remote device connection, in the **Device Editor** for the Ethernet communications

Step	Action					
1	In the <b>Device Editor</b> for the Ethernet communication module, under the <b>Device List</b> node, navigate to and select: • for Modbus TCP devices: the main device node • for EtherNet/IP devices: a connection node					
2	For a Modbus TCP device, open the <b>Request Setting</b> page and look for the <b>Connection Bit</b> number:					
	Connection Bit         Unit ID         Health Time Out         Repetitive Rate         RD Address         RD Length         Last Value         WR Address         WR Length           0         255         1500         60         5392         18         Hold Value         1         5           Add Request         Remove         Remove					
	OK Cancel Apply					
	In the above example (which displays the left portion of a truncated <b>Request Setting</b> page), the <b>Connection Bit</b> value of 0 maps to the first bit in the first byte of the <b>HEALTH_BITS_IN</b> array, which can be represented as <code>HEALTH_BITS_IN[0].0</code> .					

Step	Action		
3	For an EtherNet/IP device, open the <b>Connect</b> <b>Connection Bit</b> number:	ion Settings page	and look for the
	Connection Settings Connection Information	]	
	Parameter	Value	Unit
	Connection Bit	2	
	Request Packet Interval (RPI)	30 x4	ms
	/ / / / / / / / / / / / / / / / / / /		
	Description		
	ОК	Cancel	Apply
	In the above example, the <b>Connection Bit</b> val byte of the <b>HEALTH_BITS_IN</b> array, which ca HEALTH_BITS_IN[0].2.	•	
4	For a local slave, open the local slave configu for the <b>Connection Bit</b> number:	ration page (see pa	age 111) and look

## Monitoring Connection Health Bits in an Animation Table

Use an animation table to monitor the status of connection health bits and other variables. To add health bits to an animation table, follow these steps:

Step	Action						
1	In the <b>Project Browser</b> , select the <b>Animation Tables</b> node and click the right mouse button. A pop-up menu opens.						
2	Select New Animation	Table.					
3	In the New Animation	Table dialog, type in values for the following fields:					
	Name	Type in a name for the new animation table. In this example, type in <b>Connection_Health_Bits</b> .					
	Number of animated charactersAccept the default value of <b>100</b> .						
	The completed dialog lo	ooks like this:					
	New Animation Table	X					
	Functional Mode:						
		×					
	Extended String Animatic Number of animated cha						
	Temporary Table	OK Cancel					
4	Click <b>OK</b> . The dialog clo table opens.	oses and the new Connection_Health_Bits animation					
5	Double-click on the first	empty row in the Name column, then click the ellipsis					
	button 🛄. The Instar	nce Selection dialog opens.					

Step	Action	
6	In the Instance Selection dialog, navigate t HEALTH_BITS_IN array:	o and select the entire
	Animation Table : Instance Selection	
	NOC01_IN.HEALTH_BITS_IN	
	Variables Function Blocks	1
	Name =  *	EDT DDT IODDT
	Name Type	← Comment      ←
		12_01_IN 12_01_OUT
		12_01_IN
		12_01_OUT
	NOC01_IN T_NOC0	
		031] OF BYTE
		1_LS1_IN 1 LS1 OUT
	■ ■ NOC01_L31_C01 I_NOC0	
		OK Cancel
		11.
7	Click <b>OK</b> to add the array to the <b>Connection</b>	n_Health_Bits animation table:
	Connection_Health_Bits	
	Modification Force 7 5 7 5	
	Name   Value	Type - Comment
		ARRAY[031] OF BYTE
	NOC01_IN.HEALTH_BITS_IN[0]     NOC01 IN.HEALTH BITS IN[1]	BYTE
	NOC01_IN.HEALTH_BITS_IN[2]	BYTE
	NOC01_IN.HEALTH_BITS_IN[3]	BYTE
	NOC01_IN.HEALTH_BITS_IN[4]	BYTE
	NOC01_IN.HEALTH_BITS_IN[5]	BYTE
	Keep in mind that each row represents a by	te, which contains eight individual
	connection health bits. When the DTM for th	e Ethernet communication module is
	connected to the physical module, the Value	e field displays a value for the entire
	byte.	
1	- ,	

## Modifying Connection Control Bits in an Animation Table

You can also use an animation table to modify the value of a control bit, toggling it on or off.

**NOTE:** Using control bits to toggle a connection on or off (as described below) is the preferred way of regulating communication with a remote device. Toggling a connection control bit on and off does not affect the address location of I/O items. In either case—on or off—the I/O items remain a part of the configuration at the same address locations.

By contrast, enabling and disabling the **Active Configuration** property for a device or local slave either adds I/O items to, or removes I/O items from, the application. This has the rippling effect of changing the addresses not only for the items of the enabled/disabled device, but also for I/O items relating to other devices in the configuration.

The following example shows you how to add connection control bits to the

**Connection\_Health\_Bits** animation table that you created, above, and use the animation table's **Modification** function to toggle control bits on or off:

Step	Action					
1	With the Connection_Health_Bits animation table open, double-click on the next					
	empty row in the Name column, the	n click the ellipsis but	tton 🛄. The			
	Instance Selection dialog opens.					
2	In the Instance Selection dialog, navigate to and select the entire CONTROL BITS OUT array:					
	Animation Table : Instance Selection		X			
	Name ×	Туре 🗸	Comment -			
	NIC2212_01_IN     NIC2212_01_OUT     NIC2212_01_OUT     NIP2212_01_OUT     NOC01_IN     NOC01_LS1_IN     NOC01_LS1_OUT     NOC01_OUT     ONC01_OUT     ONC01_OUT	T_NIC2212_01_IN T_NIC2212_01_OUT T_NIP2212_01_OUT T_NIP2212_01_OUT T_NOC01_IN T_NOC01_LS1_IN T_NOC01_LS1_OUT T_NOC01_OUT ARRAY[0.31] OF BYTE				
			OK Cancel			

Step	Action							
3	Click <b>OK</b> to add the control bit array to the <b>Connection_Health_Bits</b> animation table:							
	Connection_Health_Bits         Modification       Force       Image       Value       Type       Comment         Image: Nocc1_OUT.conTROL_BITS_OUT       ARRAY[0.31] OF BYTE       Image: Nocc1_OUT.conTROL_BITS_OUT[0]       BYTE       Image: Nocc1_OUT.conTROL_BITS_OUT[1]       BYTE         Image: Nocc1_OUT.conTROL_BITS_OUT[2]       BYTE       Image: Nocc1_OUT.conTROL_BITS_OUT[2]       BYTE       Image: Nocc1_OUT.conTROL_BITS_OUT[2]       BYTE       Image: Nocc1_OUT.conTROL_BITS_OUT[3]       BYTE       Image: Nocc1_OUT.conTROL_BITS_OUT[4]       BYTE       Image: Nocc1_OUT.conTROL_BITS_OUT[							
4	With the DTM for the Ethernet communication module connected to the physical module, double click in the <b>Value</b> column for the row (byte) that contains the control bit you want to toggle.							
5	Type a value that toggles the bit (or bits) in the byte you want to change to on or off. For example, suppose the <b>Value</b> field of the control bit displays an initial value of <b>7</b> . This indicates that the first three (0, 1, and 2) are not established. If you intend to establish the third connection (connection 2), modify the corresponding bit to 0 (type a value of <b>3</b> ).							
	<b>NOTE:</b> When the control bit is 0, the connection is established. When the control bit is 1, the connection is closed.							
6	On your keyboard, press Enter. The control bit for the third connection (i.e.							

# Effect of Activating and De-activating Devices on I/O %MW Memory Addresses

#### Introduction

Unity Pro assigns a located address in %MW memory to each input and output variable for a remote device and local slave, when that device or slave is activated.

In addition, Unity Pro removes from %MW memory each located variable address whenever the related device or slave is de-activated.

In each case, because of the ordered structure of I/O items in PLC memory (see page 203), the activation and de-activation of a single device causes a rippling effect on the address locations of other I/O variables throughout the application.

Because activating and de-activating devices can cause substantial changes to located variable addresses, Schneider Electric recommends the following practices:

- Activate every device and local slave your application is likely to use, and allow these devices to remain activated.
- If it subsequently becomes necessary to disable communications to a device or slave, instead
  of de-activating it, use the appropriate control bits to toggle off all connections to that slave or
  device (see page 208).
- When configuring function blocks in Unity Pro, instead of directly reassigning input and output pins to a specific %MW address, do the following: assign specific input and output pins only to the derived data types and variables automatically created by Unity Pro.

#### The Sample Network

The sample network is a part of the same physical network that has been the subject of our continuing configuration example, and includes:

- the Ethernet communication module, named NOC01
- an STB NIC 2212 EtherNet/IP network interface module with I/O modules, named NIC2212\_01

Note that, when a new network is created, Unity Pro presents three local slave nodes that can be activated and pre-assigns them device numbers 000, 001, and 002. By default, each local slave is not activated. Therefore, each local slave's inputs and outputs are not initially assigned a %MW memory address.

The following example describes the effect of activating a local slave function after another remote device has already been configured and added to the network. In this ca

The sample Ethernet network has been configured as follows:

- Total network inputs and outputs are set in the **Configuration** page of the Ethernet communication module in Unity Pro:
  - 100 input words are reserved, beginning at %MW01
  - 100 output words are reserved, beginning at %MW101
- Connection bits for the project include:
  - 32 input bytes (16 words) for health bits with an instance name of NOC01\_IN
  - 32 output bytes (16 words) for control bits with an instance name of NOC01\_OUT
- Local slave inputs and outputs include:

- 8 input bytes (4 words) are reserved with an instance name of NOC01\_LS1\_IN
- 4 output bytes (2 words) are reserved with an instance name of NOC01\_LS1\_OUT
- Remote EtherNet/IP device inputs and outputs include:
  - 19 input bytes (10 words) are reserved with an instance name of NIC2212\_01\_IN
  - 8 output bytes (4 words) are reserved with an instance name of NIC2212\_01\_OUT

## I/O Assignment Without an Activated Local Slave

When you click the **Update application** button in the Ethernet communication module **Configuration** page, with the local slave de-activated, Unity Pro auto-generates a collection of variables in support of the application's I/O items at the following instance locations:

🚺 Data Edit	or					<u>_     ×</u>
Variables	DDT Types	Function Blocks	DFB 1	Types		
Filter	Name = *				EDT F	
Name	۵.,	Туре	•	Address 🗸	Value	Comment 👻
🕂 🕂 🕂	NOC01_IN	T_NOC01_IN		%MW1		
÷ 📌 🔵	NIC2212_01_IN	T_NIC2212_01_IN		%MW17	<u> </u>	
÷ 🙈 🔵	NOC01_OUT	T_NOC01_OUT		%MW101		
÷	NIC2212_01_OUT	T_NIC2212_01_0	JT	%MW117 📢		
b						
1				,		

Note the address locations of the remote EtherNet/IP device's inputs (%MW17) and outputs (%MW117). As you will see, below, when the local slave is activated, these address locations will change.

## I/O Assignment With an Activated Local Slave

The following example displays input and output variables for the same project. However, in this example the **Active Configuration** setting for the first local slave was set to **Enabled** in the local slave configuration page (*see page 113*), before the input and output variables were created. As a result clicking the **Update application** button in the Ethernet communication module **Configuration** page generated the following collection of variables:

🚺 Data Editor							
	DDT Types	Function Blocks	DFB 1	ypes			
Filter	Name = ×					EDT N	
Name	Δ	Туре	-	Address	-	Value	Comment 👻
🕀 🚓 🗐 NOC	01_IN	T_NOC01_IN		%MW1			
🕀 🔏 🗾 NOC	01_LS1_IN	T_NOC01_LS1	1_IN	%MW17			
🗄 🔏 🗾 NIC2	212_01_IN	T_NIC2212_0*	I_IN	%MW21	+		
E 🔏 🗐 NOC	01_OUT	T_NOC01_OU	Т	%MW101			
E 🔏 🗐 NOC	1_LS1_OUT	T_NOC01_LS1	_OUT	%MW117			
	212_01_OUT	T_NIC2212_01	_OUT	%MW118	+	-	
1							

Notice how the address locations for the remote EtherNet/IP device have shifted:

- inputs (NIC2212 01 IN) have shifted from %MW17 to %MW21
- outputs (NIC2212\_01\_OUT) have shifted from %MW117 to %MW118

This shift of %MW input and output memory address assignments occurs because the local slave was activated, and local slave I/O variables are placed in a located memory address position ahead of remote EtherNet/IP device I/O variables.

A similar shift of addresses would occur—with respect to both local slave and EtherNet/IP device I/O variable addresses—if a Modbus TCP remote device is activated. This is because Modbus TCP device I/O variables are places in a located memory address position ahead of both local slave and EtherNet/IP I/O variables.

As stated above, a way to avoid this shift of I/O memory addresses is to activate every local slave and remote device that your project may require, and then allow them to remain active. To later disable a device, use the appropriate control bits to toggle off every connection to that device.

# **Chapter 5** Optimizing Performance

## **Overview**

This chapter describes how to optimize the performance of your Ethernet network.

# What Is in This Chapter?

This chapter contains the following sections:

Section	Торіс	Page
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5.2	Control Application Design	224
5.3	Projecting Ethernet Network Performance	238

# Section 5.1 Selecting a Switch

#### **Overview**

This section describes how to select an Ethernet switch for your network.

# What Is in This Section?

This section contains the following topics:

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Transmission Speed, Duplex and Auto-Negotiation	216
Quality of Service (QoS)	217
IGMP Snooping	218
Rapid Spanning Tree Protocol (RSTP)	219
Virtual Local Area Network (VLAN)	220
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# Role of a Switch in an Ethernet Network

## **Overview**

Schneider Electric recommends the use of managed switches—not unmanaged switches or hubs—in process control networks. A managed switch provides more functionality than an unmanaged switch, including the ability to:

- turn switch ports on or off
- configure port speed and duplex settings
- · control and monitor message traffic within segments
- prioritize message traffic

# **Recommended Switch Features**

When acquiring an Ethernet switch for your process control network, confirm that the switch includes the following features:

- Multiple speed (10/100/1000 Mbps)
- Full duplex
- QoS
- IGMP snooping
- RSTP
- VLAN support
- Port mirroring
- SNMP agent

# **Transmission Speed, Duplex and Auto-Negotiation**

#### Introduction

Most Ethernet switches support multiple transmission speeds, full- and half-duplex communication, and offer auto-negotiation capability. Hubs, by contrast, are not designed to support full duplex transmissions.

### Duplex

Full duplex enables a switch port to both transmit and receive messages simultaneously, over two dedicated communication channels. Half duplex, by contrast, permits a port to transmit or receive messages in only one direction at a time. Signal collisions are possible in half duplex communications—because messages are transmitted and received over a single channel. Half duplex communications can cause poor performance and message loss.

#### **Auto-Negotiation**

Auto-negotiation permits a switch port—connected to a remote device that also supports autonegotiation—to automatically configure itself for the maximum speed and duplex configuration supported by both devices. However, it may be necessary to manually configure the speed and duplex settings of the switch port, if its peer device does not possess auto-negotiation capability.

#### Recommendation

Schneider Electric recommends that you employ only switches that support:

- both auto-negotiation and manual configuration of speed and duplex settings
- multiple speeds: 10/100/1000 Mbps
- both full duplex and half duplex

# **Quality of Service (QoS)**

### Introduction

A switch that supports QoS packet tagging can be configured to deliver higher priority messages before messages with a lower (or no) priority. This enhances system determinism and increases the timely delivery of prioritized messages.

In the absence of QoS tagging, the switch delivers various application messages on a first-in firstout basis. This can result in poor system performance caused by the long forwarding delay—and late delivery—of high priority application messages, which may be handled after lower priority messages.

# Types of QoS

The tagging types are based on the switch configuration:

Tagging type	Priority mapping rule	Description
Explicit (QoS tag in Ethernet packet)	DSCP or TOS field in IP header	Each IP based Ethernet packet contains a value in the DSCP or TOS field in its IP header, indicating the QoS priority. The switch forwards packets based on this priority.
	VLAN tag in Ethernet header	Each Ethernet packet contains a value in the priority field in the VLAN tag in its Ethernet header, indicating the QoS priority. The switch forwards packets based on this priority.
Implicit	Port based	Switch ports are mapped to different QoS priorities. For example, switch port 1 is mapped to QoS priority 1, switch port 2 is mapped to QoS priority 2, etc.

### Recommendation

Schneider Electric recommends the use of devices—including switches—that support explicit QoS tagging.

**NOTE:** Some switches that support QoS tagging have this feature disabled by default. Confirm that QoS is enabled when deploying each switch.

# **IGMP Snooping**

### **Multicast Messaging**

Internet Group Management Protocol (IGMP) is an essential feature of multicast messaging. IGMP instructs routers and switches to forward Ethernet multicast packets to only those device ports that have requested these packets.

In the absence of IGMP snooping, a switch forwards multicast packets out of all its ports, resulting in greater network traffic, wasted network bandwidth, and degraded network performance.

Configure one Ethernet network switch as the IGMP querier. This switch periodically polls the field devices connected to the network, which causes all connected devices to issue an *IGMP Multicast Group Join* message. The group message is received by all network switches, which update their multicast addressing information databases in response.

Similarly, when an Ethernet device transmits an *IGMP Multicast Group Leave* message, all network switches update their multicast addressing information databases by removing the device from their databases.

Multicast messaging reduces network traffic by:

- · requiring that a message be sent only once
- sending the message only to devices for which the message is intended

#### Recommendation

Schneider Electric recommend the following:

- employ switches that support IGMP V2 or higher
- because IGMP snooping may be disabled by default, enable IGMP snooping for each network switch
- confirm that one switch is configured as the IGMP querier

# Rapid Spanning Tree Protocol (RSTP)

### RSTP

Rapid Spanning Tree Protocol (RSTP) is an OSI layer 2 protocol defined by IEEE 802.1D 2004 that performs the following functions:

- it creates a loop-free logical network path for Ethernet devices that are part of a topology that includes redundant physical paths
- it automatically restores network communication—by activating redundant links—in the event the network experiences a broken link

RSTP software, operating simultaneously in every network switch, obtains information from each switch which enables the software to create a hierarchical logical network topology. RSTP is a flexible protocol that can be implemented on many physical topologies, including ring, mesh, or a combination of ring and mesh.

### Recommendation

Schneider Electric recommends the following practices:

- Use RSTP instead of STP: RSTP provides a faster recovery time than STP NOTE: Recovery time is the time that elapses between the moment a broken link is detected to the moment network service is restored. Recovery time depends on:
- the number of switches in the topology: the more switches, the longer the recovery time
- the processing speed of the switches in the topology: the slower the speed, the longer the recovery time
- the bandwidth, traffic load, and topology pattern
- If the switch is part of a topology with redundant physical paths: enable RSTP.
- If the switch is part of a topology that does not include redundant physical paths: disable RSTP—in this case, disabling RSTP improves network performance.

# Virtual Local Area Network (VLAN)

### Introduction

Use VLANs to divide a larger network into smaller virtual groups of devices, and to split a switch into many virtual network switches. VLANs permit the creation of logically separate groups of network devices, without having to physically re-wire those devices.

When a switch receives a message directed to a specific VLAN, it forwards that message only to the switch ports connected to devices that are members of that VLAN. The switch does not send the message to other ports.

A VLAN reduces network traffic, blocks multicast and broadcast traffic from other VLANs, provides separation between VLANs, and improves system performance.

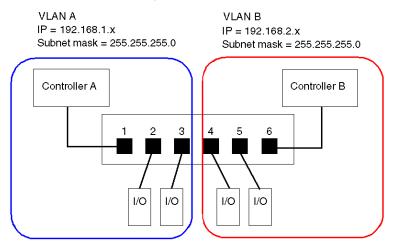
### **VLAN Types**

Depending upon the switch features, there many different ways to define and implement VLANs:

Tagging type	Mapping rule	Description
Explicit (VLAN tag in Ethernet packet)	Tag based	Each VLAN group is assigned a unique VLAN ID, which is included in each Ethernet packet. The switch forwards packets based on VLAN ID.
Implicit (no VLAN tag in Ethernet packet)	Port based	Switch ports are assigned to different VLANs, when the switch is configured (see example, below.)
	MAC based	A switch maps VLAN group membership—and forwards Ethernet frames—based on device MAC address.
	Protocol based	A switch maps VLAN group membership—and forwards Ethernet frames—based on message protocol.
	IP-subnet based	A switch maps VLAN group membership—and forwards Ethernet frames—based on IP subnet portion of the target address.

## Example

In the port-based VLAN example, below, switch ports 1, 2, and 3 are assigned to VLAN A, while switch ports 4, 5, and 6 are assigned to VLAN B:



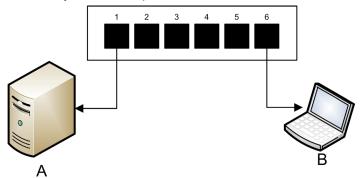
**NOTE:** A single port can be a member of multiple VLANs.

# Port Mirroring

### Introduction

Port mirroring lets you troubleshoot switch port transmissions by copying the traffic that passes through one port (the source or mirrored port) and sending the copied transmission to a second port (the destination or mirror) port, where the packets can be examined.

In the following example, the data packets transmitted over port 1 are copied and sent to port 6. To troubleshoot port 1, a PC with packet sniffing software is used to analyze the traffic on port 6 and thereby troubleshoot port 1.



- A target device of port 1 transmissions
- B PC with packet sniffing software connected to port 6, which mirrors port 1 transmissions

Port mirroring does not affect the normal forwarding behavior of the mirrored port. In many switches, you can configure port mirroring so that you can forward and examine:

- only the incoming packets of a single mirrored port
- only the outgoing packets of a single mirrored port
- both the incoming and outgoing packets of a single mirrored port
- the packets of several mirrored ports-or the whole switch

A packet sniffer's troubleshooting features should include:

- analyzing network performance
- monitoring network activity

#### Recommendation

Schneider Electric recommends implementing port mirroring as follows:

- Use a destination or mirror port only for port mirroring and not for any other purpose. Connect only the PC with packet sniffer to the mirroring port.
- When configuring the switch, confirm that port mirroring is designed to forward packets—e.g., incoming, outgoing, or both—to meet your requirements.
- A packet sniffer's troubleshooting features should include the capabilities of analyzing network performance and monitoring network activity.

# Simple Network Management Protocol (SNMP) Agent

An *SNMP agent* is a software component that responds to queries about the management data of the switch, and reports events to another device acting as an SNMP manager.

The management data for a switch can include:

- operational state information (interface status, mode of operation, etc.)
- configuration parameters (IP address, features enabled / disabled, timer values, etc.)
- performance statistics (frame counters, event logs, etc.)

If a switch is equipped with SNMP agent software, a designated SNMP manager can:

- retrieve management data about the switch
- control the switch by editing its configuration settings
- receive traps—or notices of events—affecting the state of the switch

# Section 5.2 Control Application Design

#### **Overview**

In a control system, control and automation are achieved by processing and delivering various application service messages.

Understanding messages, allocating network bandwidth among messages, and determining the time required for a message to traverse the network are all major performance considerations of your control application design.

### What Is in This Section?

This section contains the following topics:

Торіс	Page
Message Types	225
Message Connection Types	227
TCP and CIP Connections	229
Message Priority	230
Messaging Performance	231
Message Frequency	232
Allocating Network Bandwidth	234
Estimating Message Traverse and Response Times	236

# **Message Types**

### **Overview**

Two types of industrial Ethernet message types are supported by the Ethernet communication module:

Message Type	Includes			
Explicit	<ul><li>Non-time critical management data</li><li>Read/write application data</li></ul>			
Implicit	<ul> <li>Real-time I/O data</li> <li>Real-time control data</li> <li>Real-time synchronization data</li> </ul>			

### **Explicit Messages**

Explicit messages transmit information used for device configuration and diagnostics, and for data collection. In explicit messaging, the client issues a request; the server receives, processes, and sends a response back to the client.

You can specify a response timeout value, indicating how long the client waits for a response from the server. If the client does not receive a response from the server within the response timeout period, the client reissues its request. The length of the response timeout will vary depending on the requirements of your application.

Examples of explicit messages include: SNMP messages, FTP messages, CIP establish connection messages, EtherNet/IP query and response messages, and DHCP messages.

The characteristics of explicit messaging are:

- point-to-point client-server mode
- variable size
- variable frequency
- long response time
- long connection timeout

Explicit messages can be sent as either connected or unconnected, depending on the frequency of your need for data, and on the level of service required:

Message type	Characteristics
Connected	<ul> <li>Begins when an originating device initiates a connection by sending a request to a target device.</li> <li>The connection is established when the originator receives a successful response from the target.</li> <li>A CIP connected message has a higher priority and provides better service, but requires a greater amount of resources from both the target and originator devices.</li> <li>Used for recurring requests, and for high priority parameter monitoring.</li> <li>Typically use short response timeout settings.</li> </ul>
Unconnected	<ul> <li>Less resource intensive.</li> <li>Used for less frequent requests, and for lower priority parameter monitoring.</li> <li>Typically use very long response timeout settings.</li> </ul>

**NOTE:** The response timeout can be configured using the **EM Request Timeout** parameter (located in the **Channel Properties**  $\rightarrow$ **EtherNet/IP** page).

### **Implicit Messages**

Implicit messages consist of packets of data that are time critical. Implicit messages are used for real-time control and synchronization. Examples of implicit messages include: real-time I/O data, motion control data, functional diagnostic data, real-time synchronization data, and network topology management data.

Implicit messages require determinism and high performance in message processing and delivery.

The characteristics of implicit messaging are:

- producer/consumer mode (EtherNet/IP) or client/server mode (Modbus TCP)
- small, fixed data size
- fixed frequency
- short response time
- short connection timeout

# **Message Connection Types**

### Introduction

The transmission of most messages require a point-to-point connection between a transmitter and receiver.

For all types of explicit messages, the connection automatically closes when the communication ends, or is timed-out.

For implicit messages, keep the connection open. If the I/O connection—CIP for EtherNet/IP, TCP for Modbus TCP—the transmission stops. In this case, the scanner employs the TCP implicit messaging connection to dynamically re-establish the CIP connection.

### **Calculating the Connection Timeout**

For CIP connections, you can control the connection timeout setting by specifying both the network multiplier and the requested packet interval (RPI in ms):

#### Timeout = Network Multiplier x RPI

**NOTE:** You can locate and configure these values in the Unity Pro Ethernet Configuration Tool. Open the **DTM Editor** for the Ethernet communication module, then edit the following settings:

- the network multiple is the Time-out Multiplier parameter found in the Device List →<device>
   →<connection> →Connection Settings page, and
- the RPI is the EM Connection RPI parameter found in the Channel Properties 
   —EtherNet/IP
   page

A large timeout value may affect the ability of the network to optimize the availability of connection resources, re-establish connections, and update I/O data when the connection is lost.

A small timeout value may unnecessarily cause the frequent closing and re-establishing of connections.

It is preferable to use a larger timeout value for explicit messaging connections, and a smaller timeout value for implicit messaging connections. The specific value you employ depends on your application requirements.

### **Connection Types and Protocols**

The connection type and transport protocol employed depends upon the message type and message protocol, as follows:

Message Type	Message Protocol	Connection Type	Connection Protocol	
Explicit	EtherNet/IP	CIP, TCP	TCP/IP	
	Modbus TCP	TCP	TCP/IP	
	FTP	TCP	TCP/IP	
	HTML (web)	TCP	TCP/IP	
	SMTP	TCP	TCP/IP	
	SNMP	N/A	UDP/IP	
	SNTP	N/A	UDP/IP	
	DHCP	N/A	UDP/IP	
	BOOTP	N/A	UDP/IP	
Implicit	EtherNet/IP	CIP, TCP	UDP/IP	
	Modbus TCP	TCP	TCP/IP	
	IGMP	N/A	IP	
	RSTP	N/A	Ethernet	

### **Connection- Overhead**

Any message transmission includes overhead, which consumes network bandwidth and processing time. The smaller the size of the data transmitted, the relatively greater the portion of the message allocated to overhead.

Consequently, it makes sense to design your I/O messaging by consolidating data from multiple I/O devices—with similar processing capabilities and performance needs—and transmitting it through a single adapter. This design conserves bandwidth, saves network resources, and improves performance.

# **TCP and CIP Connections**

## **Number of Connections Supported**

The Ethernet communication module employs both TCP and CIP connections to support both implicit and explicit messages, as follows:

Connection Type	Maximum Number of Connections per Module		
CIP	256		
ТСР	128		

# NOTE:

- A single TCP connection can support multiple CIP connections.
- The maximum number of TCP connections does not include connections dedicated to other services, for example, FTP and Web connections.

# **Message Priority**

# QoS

The routers and switches that comprise your network infrastructure cannot distinguish between explicit message and implicit messages. However, these devices—including the Ethernet communication module—can support QoS Ethernet packet tagging (see Quantum, 140 NOC 771 01 Ethernet Communication Module, User Manual).

Using Qos tagging, these devices can handle messages they send and receive according to each message's tagged priority, forwarding higher priority messages before lower priority messages.

# **Messaging Performance**

# Maximum Messaging Load

The Ethernet communication module supports a the following maximum messaging loads:

Message Type	Maximum Messaging Load		
Implicit (EtherNet/IP plus Modbus TCP)	12000 packets per second, with no simultaneous explicit messages		
Explicit (EtherNet/IP plus Modbus TCP)	120 packets per second, with a maximum of 6000 simultaneous implicit messages		

# Message Frequency

### Introduction

The term *message frequency* refers to how often a device transmits a particular type of message. Message frequency directly affects control network load and performance, as well as the CPU capacity of every network device that processes these messages.

Depending on your application requirements, real-time I/O data can be transmitted using implicit messaging as follows:

- on a cyclic basis, at the request packet interval (RPI) rate, or
- upon the occurrence of a change of state event

### Cyclic Real-Time I/O Messaging

Much of the load on an Ethernet control network consists of cyclic real-time I/O data. Consequently, carefully consider how to set the RPI value for transmitting these messages:

- A small RPI value results in more frequent, and more numerous, message transmissions. This
  increases network load, and may waste network resources and degrade system performance.
- Conversely, a larger RPI value—for example, one that is equal (or nearly equal) to the frequency of your application's need for new data—can result in your application not receiving the most current data. Also, if a connection is lost, the time to re-establish the connection will be relatively long, because the connection timeout is proportional to the RPI.

Schneider Electric recommends setting RPI to 50% of the actual frequency by which your application requires data for cyclic real-time I/O messaging.

**NOTE:** The I/O scanner can simultaneously communicate with different I/O adapters at different RPI rates. This enhances the ability of the PLC to control and monitor different devices with varying processing capacities.

### Change of State I/O Messaging

For change of state triggered real-time I/O data messages:

- output transmissions occur at the rate of the PLC controller application cycle time
- input transmissions occur whenever an input event is detected by an input device

Consequently, for an I/O device with a rapid response and transmission time, using a direct connection to the I/O device may be more efficient than using a rack optimized connection. In this design, because only the single device input data is sent, the size of the frequently transmitted message is potentially much smaller than would be the case if the message contained data from every I/O device on the remote island.

**NOTE:** A change of state (versus cyclic) triggered real-time I/O message usually reduces network load. Configure the change of state message with a longer connection timeout value.

### **RSTP and IGMP Messaging**

RSTP and IGMP messages usually consume a very small amount of network bandwidth. Set up the IGMP query period based on your application requirements.

# **Scheduling Certain Explicit Messages**

Depending on your application requirements, you can also configure certain explicit messages to be transmitted either cyclically or upon the occurrence of a change of state event. For example, you can periodically monitor a device using SNMP query, Web pages, EtherNet/IP, and Modbus TCP. The cyclic period should be configured so that the total load consumed by explicit messaging does not exceed 10% of network capacity.

# Allocating Network Bandwidth

### Introduction

Maximum network bandwidth equals your network speed, for example 100 Mbps. When designing your control network, allocate network bandwidth among the control application messages required by your application.

**NOTE:** Schneider Electric recommends you reserve at least the following amounts for processing explicit messaging:

- 10% of network bandwidth
- 10% of CPU processing capacity for each network device

### Message Load and Message Bandwidth

*Message Load*—in packets per second (PPS)—represents the number of packets in a single message that are received and sent within one second. *Message Load* can be estimated as follows:

#### Message Load =

#### (number of packets per connection) x (number of connections) / RPI

The *number of packets per connection* value depends on the capacity of the device, and can be either:

- 1: for connections that support uni-directional communication
- 2: for connections that support input and output (for producer/consumer mode) or request and response (for client/server mode) per one time bi-directional exchange, or

The connection can be used for either explicit or implicit messaging. For UDP-based explicit messaging, assume that each client represents one connection, and that messages are transmitted cyclically.

Message Bandwidth (in bits) can be calculated as follows:

#### Message Bandwidth = message packet size (bits) x Message Load

Based on the portion of network bandwidth you want to allocate to a particular message, you can use the *Message Load* and *Message Bandwidth* formulae to calculate the fastest RPI for the message.

### **Device Load and Device Bandwidth**

*Device Load*—measured in number of packets—represents the load contributed by messages received and sent by a device within one second. *Device Load* is the sum of the *Message Load* values for every message handled by the device.

If the *Device Load* exceeds the device's processing capability, performance of both the device and the network is degraded.

**NOTE:** Schneider Electric recommends that *Device Load* not exceed 90% of CPU processing capacity of each device.

*Device Bandwidth*—measured in bits—is the sum of the *Message Bandwidth* values for messages handled by the device

In your control application design, determine whether the I/O scanner device can handle the load contributed by every I/O adapter device. To do this, perform the following steps:

- 1 Calculate the implicit messaging load and bandwidth for each remote device.
- 2 Sum the load and bandwidth estimates for every remote device.
- **3** Compare the total implicit messaging load and bandwidth against the maximum implicit messaging capacity of the device acting as I/O scanner.

If the projected total load or bandwidth for a communication module acting as an I/O scanner exceeds its implicit messaging load or bandwidth limits, consider one or more of the following corrective actions:

- If the I/O adapter supports rack optimized connections, and if a single rack of digital I/O uses multiple direct connections, replace the direct connections with a single rack optimized connection, if possible.
- Increase the RPI setting for a device where possible.
- Add another communication module to act as an I/O scanner, and re-design the network in order to share the load.

#### Network Load and Network Bandwidth

*Network Load*—measured in number of packets—can be estimated as the sum of the *Device Load* of the adapter devices, or of the scanner devices.

*Network Bandwidth*—measured in bits—can be estimated as the sum of the *Device Bandwidth* of the adapter devices, or of the scanner devices.

**NOTE:** Schneider Electric recommends that *Network Load* not exceed 90% of maximum network bandwidth.

If necessary, you may need to optimize your control application design by:

- adjusting device RPI settings
- changing connection types (e.g., from direct to rack optimized)
- modify the configuration
- change the network topology

# **Estimating Message Traverse and Response Times**

### Message Traverse Time

Message Traverse Time is defined as the time required for a message to travel from its point of origin to its targeted destination over a network path. As the messages travels over the network path, it may pass through—and be forwarded by—a number of intermediate network devices, including switches and routers.

Message Traverse Time is impacted by several factors, including, for example, the following:

- the number of forwarding network devices
- · the transmission delay of each forwarding device
- network load
- message priority

*Message Traverse Time* can be estimated by determining the transmission delay (the store and forward delay) of intermediate network devices and counting the number of such devices. Assuming each forwarding device is a switch, and each switch presents the same transmission delay, the following formula can be used:

#### Message Traverse Time =

#### (Switch Transmission Delay) x (Number of Switches)

Schneider Electric recommends that you estimate a worst-case *Message Traverse Time*, as follows:

Step	Description
1	Determine the worst case network load.
2	Obtain switch performance information, under varying network loads, and use the worst case—i.e., the largest—transmission delay value.
3	Determine the logical network topology that yields the longest path—i.e. the greatest number of switches—through which a message passes.
4	Using the largest transmission delay value and the largest number of forwarding switches, use the formula (above) to calculate a worst-cast <i>Message Traverse Time</i> .

### Message Response Time

After calculating *Message Traverse Time* (above), you can next measure *Message Response Time*, which measures the total time required for:

- a message to travel from a client device over the network to a server
- the message to be processed by the server
- the server response to travel back to the client over the network

Message Response Time can be calculated as follows:

#### Message Response Time =

### (2 x (Message Traverse Time)) + (Server Processing Time)

In the above formula, '2' indicates a round trip required for client/server communication.

After *Message Response Time* is calculated, you can determine and configure the following parameters, both of which are found in the **Channel Properties** —**EtherNet/IP** page of the Unity Pro Ethernet Configuration Tool:

- EM Request Timeout value, and
- EM Connection RPI

# Section 5.3 Projecting Ethernet Network Performance

# Network Load and Bandwidth Calculation Example

### **Network Devices**

This example estimates the performance for an Ethernet network composed of the following devices:

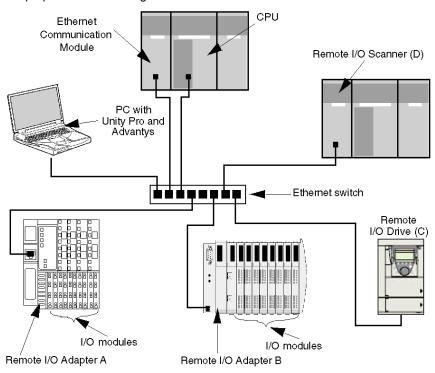
- a PLC that controls 3 remote I/O stations (A, B, and C)
- BMX NOC 0401 Ethernet communication module, acting as the local I/O scanner, installed in the PLC rack
- an 8-port Ethernet managed switch
- a PC running used to obtain diagnostic data via explicit messages running the following software:
  - Unity Pro
  - the Unity Pro Ethernet Configuration Tool
- 4 remote devices, acting as:
  - an I/O adapter (A) for a rack of I/O modules
  - a second I/O adapter (B) for a rack of I/O modules
  - a remote I/O drive (C)
  - a remote I/O scanner (D)

Unity Pro software running in the PC is used to configure the CPU controller.

For programming purposes you need a connection to the PLC either through the CPU's Ethernet port or other supported programming paths.

## **Network Diagram**

The proposed network diagram looks like this:



#### Network Load and Bandwidth Limits

When performing calculations, keep in mind that the Ethernet module and remote devices cannot exceed their implicit messaging and bandwidth limits:

Device	Load Limits	Bandwidth Limits	
Ethernet Communication Module	12000 pps	80 Mbps	
I/O Adapter (A)	8000 pps	70 Mbps	
I/O Adapter (B)	8000 pps	70 Mbps	
I/O Drive (C)	8000 pps	70 Mbps	
I/O Scanner (D)	12000 pps	80 Mbps	
Switch	16000 pps	90 Mbps	

### Remote Device Connections and RPI

For the purpose of this example, it is assumed that the remote devices require the following numbers of CIP connections, and are configured for the stated requested packet interval (RPI) settings:

Device	CIP I/O Connections	RPI Setting	I/O Packet Size	
I/O Adapter (A)	5	20 ms	8000 bits	
I/O Adapter (B)	2	30 ms	4096 bits	
I/O Drive (C)	2	30 ms	8000 bits	
I/O Scanner (D)	2	50 ms	8000 bits	

For the purposes of this example, it is also assumed that every connection is bi-directional.

### **I/O Scanner Calculations**

The Ethernet communication module, acting as local I/O scanner, has to handle the implicit messaging load contributed by the remote devices. Your task is to:

- 1 estimate the implicit messaging load and bandwidth contributed by each remote device
- 2 sum the load and bandwidth values for each remote device
- 3 compare the total load and bandwidth against the maximum implicit messaging capacity of the local I/O scanner

Recall that the implicit messaging load calculation formula for a single remote device is:

#### Load = (number of packets per connection) x (number of connections) / RPI

Because every connection is assumed to be bi-directional, the *number of packets per connection* value is 2. Consequently, the estimated implicit messaging load contributed by each device, and the total implicit messaging load the local I/O scanner has to handle can be estimated as follows:

Load:

Device	Number of packets per connection	x	Number of connections	÷	RPI	=	Load
I/O Adapter (A)	2	Х	5	÷	20 ms	=	500 pps
I/O Adapter (B)	2	Х	2	÷	30 ms	=	134 pps
I/O Drive (C)	2	Х	2	÷	30 ms	=	134 pps
I/O Scanner (D)	2	Х	2	÷	50 ms	=	80 pps
Total				=	848 pps		
Switch				=	848 pps		

Device	Packet size	х	Load	=	Bandwidth
I/O Adapter (A)	8000 bits	Х	500 pps	=	4 Mbps
I/O Adapter (B)	4096 bits	Х	134 pps	=	0.554 Mbps
I/O Drive (C)	8000 bits	Х	134 pps	=	1.07 Mbps
I/O Scanner (D)	8000 bits	Х	80 pps	=	0.64 Mbps
Total					6.26 Mbps
	=	6.26 Mbps			

### Bandwidth:

## Conclusion

The projected total load for the module—848 pps—is within the device implicit messaging limit of 12000 data packets per second. The projected total bandwidth for the communication module— 6.26 Mbps—is also within the device implicit messaging bandwidth limit of 80 Mbps. The projected total load and bandwidth for the remote devices (including the switch) are also within their 90% load and bandwidth limits:

Device	90% of Load Limit	90% of Bandwidth Limit
Ethernet Communication Module	10800 pps	72 Mbps
I/O Adapter (A)	7200 pps	63 Mbps
I/O Adapter (B)	7200 pps	63 Mbps
I/O Drive (C)	7200 pps	63 Mbps
I/O Scanner (D)	10800 pps	72 Mbps

**NOTE:** Although message load contributed by explicit messaging are not included in the above calculations, such load contributions are presumed to be less than 10% of the device load and bandwidth.

# Chapter 6 CIP Objects

### **Overview**

The Ethernet communication module can access CIP data and services located in connected devices. The CIP objects and their content depends on the design of each device.

CIP object data and content are exposed—and accessed—hierarchically in the following nested levels:

Object



NOTE: You can use explicit messaging to access either:

- a collection of instance attributes, by including in the explicit message address only the object's class and instance values, or
- a single attribute, by extending the explicit message address to include not only the object's class and instance values but also a specific attribute value

When the Ethernet communication module's local slave service is activated, remote devices can send explicit messages to the module's CIP object structure and:

- · access module data, or
- execute module commands

This chapter describes the CIP objects the Ethernet communication module exposes to remote devices.

# What Is in This Chapter?

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# **Identity Object**

### **Overview**

The Identity object presents the instances, attributes and services described below.

## **Class ID**

01

### **Instance IDs**

The Identity object presents two instances:

- 0: class
- 1: instance

### **Attributes**

Identity object attributes are associated with each instance, as follows:

Instance ID = 0 (class attributes):

Attribute ID	Description	GET	SET				
01	Revision	х	—				
02	Max Instance	Х	_				
X = supported — = not supported	X = supported — = not supported						

Instance ID = 1 (instance attributes):

Attribute ID		Description	Туре	GET	SET
hex	dec				
01	01	Vendor ID	UINT	Х	—
02	02	Device Type	UINT	Х	—
03	03	Product Code	UINT	Х	—
04	04	Revision	STRUCT	Х	—
		Major	USINT		
		Minor	USINT		
X = sup — = not	ported supported				

Attribute IE	)	Description	Туре	GET	SET			
hex	dec							
05	05	Status bit 2: 0x01=the module is configured bits 4-7: 0x03=no I/O connections established 0x06=at least 1 I/O connection in run mode 0x07=at least 1 I/O connection established, all in IDLE mode	Word	x	_			
06	06	Serial Number	UDINT	Х	—			
07	07	Product Name	STRING	Х	—			
18	24	Modbus Identity	STRUCT	Х	—			
• •	X = supported — = not supported							

# **Services**

The Identity object performs the following services upon the listed object types:

Service ID		Description	Class	Instance	Notes			
hex	dec	-						
01	01	Get_Attributes_All	X	Х	Returns: • all class attributes (instance = 0) • instance attributes 1 to 7 (instance = 1)			
0E	14	Get_Attribute_Single	Х	Х	Returns the value of the specified attribute.			
	X = supported — = not supported							

# **Assembly Object**

### **Overview**

The Assembly object consists of the attributes and services described below.

**NOTE:** You can send an explicit message to the Assembly object only when no other connections have been established that read from or write to this object. For example, you can send an explicit message to the Assembly object if a local slave instance is enabled, but no other module is scanning that local slave.

### **Class ID**

04

# Instance IDs

The Assembly object presents the following instance identifiers:

- 0: class
- 101, 102, 111, 112, 121, 122: instance

### **Attributes**

The Assembly object consists of the following attributes:

Instance ID = 0 (class attributes):

Attribute ID	Description	GET	SET			
01	Revision	Х	_			
02	Max Instance	Х	—			
03	Number of Instances	Х	—			
X = supported — = not supported						

Instance attributes:

Instance ID	Attribute ID	Description	Туре	GET	SET			
101	03	Local slave 1: T->O input data	Array of BYTE	Х	—			
102		Local slave 1: O>T	Array of BYTE	Х	Х			
111		Local slave 2: T->O input data	Array of BYTE	Х	—			
112		Local slave 2: O>T	Array of BYTE	Х	Х			
121		Local slave 3: T->O input data	Array of BYTE	Х	—			
122		Local slave 3: O>T	Array of BYTE	Х	Х			
X = supported — = not suppor	X = supported — = not supported							

# Services

The CIP Assembly object performs these services upon the listed object types:

Servic	e ID	Description	Class Instance		Notes			
hex	dec							
0E	14	Get_Attribute_Single	Х	Х	Returns the value of the specified attribute			
10	16	Set_Attribute_Single <sup>1</sup>		x	Returns these values: 0E=attribute not settable: assembly is not o->T type 0F=permission denied: assembly is being used by an active connection 13=config too small: the Set_Attribute_Single command contains partial data 15=data too big: the Set_Attribute_Single command contains too much data			
X = su	X = supported							

- = not supported

1. When valid, the size of the data written to the Assembly object using the Set\_Attribute\_Single service equals the size of the Assembly object as configured in the target module.

# **Connection Manager Object**

### Overview

The Connection Manager object presents the instances, attributes and services described below.

### **Class ID**

06

### **Instance IDs**

The Connection Manager object presents two instance values:

- 0: class
- 1: instance

# Attributes

Connection Manager object attributes are associated with each instance, as follows:

Instance ID = 0 (class attributes):

Attribute ID	Description	GET	SET			
01	Revision	х	—			
02	Max Instance	Х	—			
X = supported — = not supported						

Instance ID = 1 (instance attributes):

Attribut	te ID	Description	Туре	GET	ET SET	Value		
hex	dec							
01	01	Open Requests	UINT	x	х	Number of Forward Open service requests received		
02	02	Open Format Rejects	UINT	X	x	Number of Forward Open service requests that were rejected due to bad format		
03	03	Open Resource Rejects	UINT	X	x	Number of Forward Open service requests that were rejected due to lack of resources		
	X = supported — = not supported							

Attribute ID		Description	Туре	GET	SET	Value		
hex	dec	_						
04	04	Open Other Rejects	UINT	X	x	Number of Forward Open service requests that were rejected for reasons other than bad format or lack of resources		
05	05	Close Requests	UINT	X	х	Number of Forward Close service requests received		
06	06	Close Format Requests	UINT	X	x	Number of Forward Close service requests that were rejected due to bad format		
07	07	Close Other Requests	UINT	X	x	Number of Forward Close service requests that were rejected for reasons other than bad format		
08	08	Connection Timeouts	UINT	X	x	Total number of connection timeouts that occurred in connections controlled by this connections manager		
09	09	Connection Entry List	STRUCT	х	—	0 (Unsupported optional item		
0B	11	CPU_Utilization	UINT	х	—	0 (Unsupported optional item		
0C	12	MaxBuffSize	UDINT	х	—	0 (Unsupported optional item		
0D	13	BufSize Remaining	UDINT	Х	—	0 (Unsupported optional item		
	pported ot suppo	rted	•					

# Services

The Connection Manager object performs the following services on the listed object types:

Service ID		Description	Class	Instance	Notes		
hex	dec						
01	01	Get_Attributes_All	х	Х	Returns the value of all attributes.		
0E	14	Get_Attribute_Single	х	Х	Returns the value of the specified attribute.		
	X = supported — = not supported						

# **Modbus Object**

### Overview

The Modbus object converts EtherNet/IP service requests to Modbus functions, and Modbus exception codes to CIP General Status codes. It presents the instances, attributes and services described below.

### **Class ID**

44 (hex), 68 (decimal)

### Instance IDs

The Modbus object presents two instance values:

- 0: class
- 1: instance

#### **Attributes**

The Modbus object consists of the following attributes:

Instance ID = 0 (class attributes):

Attribute ID	Description	GET	SET		
01	Revision	х	-		
02	Max Instance	х	—		
X = supported — = not supported					

Instance ID = 1 (instance attributes):

Attribute ID	Description	Туре	GET	SET
_	No instance attributes are supported	—	—	—

The Modbus object performs the following services upon the listed object types:

Service ID		Description	Class	Instance	
hex	dec				
0E	14	Get_Attribute_Single	X	X	
4B	75	Read_Discrete_Inputs	_	Х	
4C	76	Read_Coils	—	X	
4D	77	Read_Input_Registers	—	X	
4E	78	Read_Holding_Registers	—	X	
4F	79	Write_Coils	—	X	
50	80	Write_Holding_Registers	—	X	
51 81 Modbus_Passthrough — X					
X = sup	ported				
— = not	supporte	ed			

# Quality Of Service (QoS) Object

#### Overview

The QoS object implements Differentiated Services Code Point (DSCP or *DiffServe*) values for the purpose of providing a method of prioritizing Ethernet messages. The QoS object presents the instances, attributes and services described below.

#### Class ID

48 (hex), 72 (decimal)

#### Instance IDs

The QoS object presents two instance values:

- 0: class
- 1: instance

#### **Attributes**

The QoS object consists of the following attributes:

Instance ID = 0 (class attributes):

Attribute ID	Description	GET	SET			
01	Revision	х	—			
02	Max Instance	Х	—			
X = supported — = not supported						

Instance ID = 1 (in	stance attributes):
---------------------	---------------------

Attribute ID	Description	Туре	GET	SET	Value
04	DSCP Urgent	USINT	X	X	For CIP transport class 0/1 Urgent priority messages, default value = 55.
05	DSCP Scheduled	USINT	x	X	For CIP transport class 0/1 Urgent priority messages, default value = 47.
06	DSCP High	USINT	x	Х	For CIP transport class 0/1 Urgent priority messages, default value = 43.
07	DSCP Low	USINT	x	X	For CIP transport class 0/1 Urgent priority messages, default value = 31.
08	DSCP Explicit	USINT	x	X	For CIP explicit messages (transport class 2/3 and UCMM), default value = 27.
X = supported — = not supported	orted			- I	

**NOTE:** A change in the instance attribute value takes effect on device re-start, for configurations made from flash memory.

#### **Services**

The QoS object performs the following services upon the listed object types:

Service ID		Description	Class	Instance	
hex	dec				
0E	14	Get_Attribute_Single	Х	Х	
10	16	Set_Attribute_Single	—	х	
X = suppo — = not s			•		

# **TCP/IP Interface Object**

#### **Overview**

The TCP/IP interface object presents the instances, attributes and services described below.

#### **Class ID**

F5 (hex), 245 (decimal)

#### **Instance IDs**

The TCP/IP interface object presents 2 instance values:

- 0: class
- 1: instance

## Attributes

TCP/IP interface object attributes are associated with each instance, as follows:

Instance ID = 0 (class attributes):

Attribute ID	Description	GET	SET		
01	Revision	х	—		
02	Max Instance	х	—		
X = supported — = not supported					

Instance ID = 1 (instance attributes):

Attribute ID	Description	Туре	GET	SET	Value	
01	Status	DWORD	Х	—	0x01	
02	Configuration Capability	DWORD	x	—	0x01 = from BootP 0x11 = from flash 0x00 = other	
03	Configuration Control	DWORD	х	Х	0x01 = out-of-box default	
04	Physical Link Object	STRUCT	Х	—		
	Path Size	UINT				
Path Padded EPATH						
X = supported — = not support	rted					

Attribute ID	Description	Туре	GET	SET	Value
05	Interface Configuration	STRUCT	Х	х	0x00 = out-of-box default
	IP Address	UDINT			
	Network Mask	UDINT			
	Gateway Address	UDINT			
	Name Server	UDINT			
	Name Server 2	UDINT			
	Domain Name	STRING			
06	Host Name	STRING	Х	—	
X = supported — = not suppo	rted				

The TCP/IP interface object performs the following services upon the listed object types:

Service ID		Description	Class	Instance	Notes		
hex	dec						
01	01	Get_Attributes_All	Х	х	Returns the value of all attributes.		
0E	14	Get_Attribute_Single	x	х	Returns the value of the specified attribute.		
10	16	Set_Attribute_Single <sup>1</sup>	_	х	Sets the value of the specified attribute.		
X = sup	X = supported						

— = not supported

1. The Set\_Attribute\_Single service can execute only when these preconditions are satisfied:

• Configure the Ethernet communication module to obtain its IP address from flash memory.

• Confirm that the PLC is in stop mode.

# **Ethernet Link Object**

#### **Overview**

The Ethernet Link object consists of the instances, attributes and services described below.

#### **Class ID**

F6 (hex), 246 (decimal)

#### **Instance IDs**

The Ethernet Link object presents the following instance values:

- 0: class
- 1: port 1
- 2: port 2
- 3: port 3
- 4: port 4
- 5: internal port

#### **Attributes**

The Ethernet Link object presents the following attributes:

Instance ID = 0 (class attributes):

Attribute ID	Description	GET	SET
01	Revision	Х	—
02	Max Instance	Х	—
03	Number of Instances	Х	_
X = supported — = not supported		-	

Instance ID = 1...5 (instance attributes):

Attribute ID		Description	Туре	GET	SET	Value		
hex	dec							
01	01	Interface Speed	UDINT	Х	—	Valid values include: 0, 10000000, 100000000		
	X = supported — = not supported							

Attribute ID		Description	Туре	GET	SET	Value
hex	dec					
02	02	Interface Flags	DWORD	Х	—	Bit 0: Link Status 0 = Inactive 1 = Active
						Bit 1: Duplex Mode 0 = half duplex 1 = full duplex
						Bits 2—4: Negotiation Status 3 = successfully negotiated speed and duplex 4 = forced speed and link
						Bit 5: Manual Setting Requires Reset 0 = automatic 1 = device need reset
						Bit 6: Local Hardware Fault detected 0 = no event 1 = event detected
03	03	Physical Address	ARRAY of 6 USINT	х	—	Module MAC Address
04	04	Interface Counters	STRUCT	Х	—	
		In octets	UDINT			Octets received on the interface
		In Ucast Packets	UDINT			Unicast packets received on the interface
		In NUcast Packets	UDINT			Non-unicast packets received on the interface
		In Discards	UDINT			Inbound packets received on the interface, but discarded
		In Errors	UDINT			Inbound packets that contain detected errors (does not include In Discards)
		In Unknown Protos	UDINT			Inbound packets with unknown protocol
		Out Octets	UDINT			Octets sent on the interface
		Out Ucast Packets	UDINT			Unicast packets sent on the interface
		Out NUcast Packets	UDINT			Non-unicast packets sent on the interface
		Out Discards	UDINT			Outbound packets discarded
		Out Errors	UDINT			Outbound packets that contain detected errors

— = not supported

Attrib	ute ID	Description	Туре	GET	SET	Value
hex	dec					
05	05	Media Counters	STRUCT	Х	—	
		Alignment Errors	UDINT			Frames that are not an integral number of octets in length
		FCS Errors	UDINT			CRC error detected—Frames received with a dtected FCS checksum error
		Single Collisions	UDINT			Successfully transmitted frames that experienced exactly one collision
		Multiple Collisions	UDINT			Successfully transmitted frames that experienced more than one collision
		SQE Test Errors	UDINT			Number of times the SQE test error is detected
		Deferred Transmissions	UDINT			Frames for which first transmission attempt is delayed because the medium is busy
		Late Collisions	UDINT			Number of times a collision is detected later than 512 bittimes into the transmission of a packet
		Excessive Collisions	UDINT			Frames for which transmission is not successful due to excessive collisions
		MAC Transmit Errors	UDINT			Frames for which transmission is not successful due to internal MAC sublayer transmit detected error
		Carrier Sense Errors	UDINT			Times that the carrier sense condition was lost or not asserted when attempting to transmit a frame
		Frame Too Long	UDINT			Frames received that exceed the maximum permitted frame size
		MAC Receive Errors	UDINT			Frames for which reception on an interface is not successful due to an internal MAC sublayer receive detected error

— = not supported

Attrib	ute ID	Description	Туре	GET	SET	Value
hex	dec					
06	06	Interface Control	STRUCT	Х	Х	API of the connection
		Control Bits	WORD			Bit 0: Auto-negotiation 0 = Disabled 1 = Enabled Note: When auto-negotiation is enabled, the detected error 0x0C (Object State Conflict) is returned when attempting to set either: • Forced Interface Speed, or • Forced Duplex Mode
						Bit 1: Forced Duplex Mode (if auto- negotiation bit = 0) 0 = half duplex 1 = full duplex
		Forced Interface Speed	UINT			Valid values include: 10000000, 10000000 <b>Note:</b> Attempting to set any other value returns the detected error 0x09 (Invalid Attribute Value)
10	16	Interface Label	SHORT_S TRING	X	_	A fixed textual string identifying the interface, that should include 'internal' for internal interfaces. Maximum number of characters is 64.
	pported ot suppor	ted	1	1		

The Ethernet Link object performs the following services upon the listed object types:

Service	ID	Description	Class	Instance			
hex	dec						
01	01	Get_Attributes_All	x	Х			
10	16	Set_Attribute_Single	—	Х			
0E	14	Get_Attribute_Single	x	Х			
4C	76	Get_and_Clear	—	Х			
	X = supported — = not supported						

# EtherNet/IP Interface Diagnostics Object

#### Overview

The EtherNet/IP Interface Diagnostics object presents the instances, attributes and services described below.

### **Class ID**

350 (hex), 848 (decimal)

#### **Instance IDs**

The EtherNetP/IP Interface object presents two instance values:

- 0: class
- 1: instance

#### Attributes

EtherNet/IP Interface Diagnostics object attributes are associated with each instance, as follows: Instance ID = 0 (class attributes):

Attribute ID	Description	GET	SET			
01	Revision	Х	—			
02	Max Instance	х	—			
X = supported — = not supported						

Instance ID = 1 (instance attributes):

Attribute ID	Description	Туре	GET	SET	Value	
01	Protocols Supported	UINT	Х	—		
X = supported — = not suppo	X = supported — = not supported					

Attribute ID	Description	Туре	GET	SET	Value
02	Connection Diagnostics	STRUCT	Х	—	
	Max CIP IO Connections opened	UINT			Number of Class 1 connections opened since the last reset
	Current CIP IO Connections	UINT			Number of Class 1 connections currently opened
	Max CIP Explicit Connections opened	UINT			Number of Class 3 connections opened since the last reset
	Current CIP Explicit Connections	UINT			Number of Class 3 connections currently opened
	CIP Connections Opening Errors	UINT			Increments each time a Forward Open is not successful (Originator and Target)
	CIP Connections Timeout Errors	UINT			Increments when a connection times out (Originator and Target)
	Max EIP TCP Connections opened	UINT			Number of TCP connections (used for EIP, as client or server) opened since the last reset
	Current EIP TCP Connections	UINT			Number of TCP connections (used for EIP, as client or server) currently open
03	IO Messaging Diagnostics	STRUCT	Х	Х	
	IO Production Counter	UDINT			Increments each time a Class 0/1 message is sent
	IO Consumption Counter	UDINT			Increments each time a Class 0/1 message is received
	IO Production Send Errors Counter	UINT			Increments each time a Class 0/1 message is not sent
	IO Consumption Receive Errors Counter	UINT			Increments each time a consumption is received with a detected error
04	Explicit Messaging Diagnostics	STRUCT	Х	Х	
	Class 3 Msg Send Counter	UDINT			Increments each time a Class 3 message is sent (client and server)
	Class 3 Msg Receive Counter	UDINT			Increments each time a Class 3 message is received (client and server)
	UCMM Msg Receive Counter	UDINT			Increments each time a UCMM message is sent (client and server)
	UCMM Msg Receive Counter	UDINT			Increments each time a UCMM message is received (client and server)

— = not supported

The EtherNet/IP Interface Diagnostics object performs the following services upon the listed object types:

Service ID		Description	Class Instance		Notes		
hex	dec						
01	01	Get_Attributes_All	Х	Х	Returns the value of all attributes.		
0E	14	Get_Attribute_Single	—	Х	Returns the value of the specified attribute.		
4C	76	Get_and_Clear	-	х	Returns and clears the values of all instance attributes.		
	X = supported — = not supported						

# EtherNet/IP IO Scanner Diagnostics Object

#### Overview

The EtherNet/IP IO Scanner Diagnostics object presents the instances, attributes and services described below.

### **Class ID**

351 (hex), 849 (decimal)

#### **Instance IDs**

The EtherNet/IP IO Scanner Diagnostics object presents two instances:

- 0: class
- 1: instance

#### **Attributes**

EtherNet/IP IO Scanner Diagnostics object attributes are associated with each instance, as follows:

Instance ID = 0 (class attributes):

Attribute ID	Description	GET	SET		
01	Revision	х	-		
02	Max Instance	Х	—		
X = supported — = not supported					

Instance ID = 1 (instance attributes):

Attribute ID	Description	Туре	GET	SET			
01	IO Status Table	STRUCT	Х	_			
	Size	UINT					
	Status	ARRAY of UNINT					
X = supported — = not supported							

The EtherNet/IP IO Scanner Diagnostics object performs the following services upon the listed object types:

Servic	e ID	Description	Class Instance		Notes		
hex	dec						
01	01	Get_Attributes_All	Х	Х	Returns the value of all attributes.		
0E	14	Get_Attribute_Single	Х	Х	Returns the value of the specified attribute.		
	X = supported — = not supported						

# **IO Connection Diagnostics Object**

#### Overview

The IO Connection Diagnostics object presents the instances, attributes and services described below.

### **Class ID**

352 (hex), 850 (decimal)

#### Instance IDs

The IO Connection Diagnostics object presents two instance values:

- 0: class
- 1...256: instance (The instance number is the connection number in the configuration.)

#### **Attributes**

IO Connection Diagnostics object attributes are associated with each instance, as follows: Instance ID = 0 (class attributes):

Attribute ID	Description	GET	SET			
01	Revision	х	—			
02	Max Instance	х	—			
X = supported — = not supported						

Attribute ID	Description	Туре	GET	SET	Value
01	IO Communication Diagnostics	STRUCT	Х	х	
	IO Production Counter	UDINT			Increments at each production
	IO Consumption Counter	UDINT			Increments at each consumption
	IO Production Send Errors Counter	UINT			Increments each time a production is not sent
	IO Consumption Receive Errors Counter	UINT			Increments each time a consumption is received with a detected error
	CIP Connection Timeout Errors	UINT			Increments when a connection times out
	CIP Connection Opening Errors	UINT			Increments each time a connection is unable to open
	CIP Connection State	UINT			State of the Connection Bit
	CIP Last Error General Status	UINT			General status of the last error detected on the connection
	CIP Last Error Extended Status	UINT			Extended status of the last error detected on the connection
	Input Communication Status	UINT			Communication status of the inputs (see table, below)
	Output Communication Status	UINT			Communication status of the outputs (see table, below)
X = supported — = not supported	orted	1	-	-	

Attribute ID	Description	Туре	GET	SET	Value
02	Connection Diagnostics	STRUCT	Х	Х	
	Production Connection ID	UDINT			Connection ID for production
	Consumption Connection ID	UDINT			Connection ID for consumption
	Production RPI	UDINT			RPI for production
	Production API	UDINT			API for production
	Consumption RPI	UDINT			RPI for consumption
	Consumption API	UDINT			API for consumption
	Production Connection Parameters	UDINT			Connection parameters for production
	Consumption Connection Parameters	UDINT			Connection parameters for consumption
	Local IP	UDINT			—
	Local UDP Port	UINT			—
	Remote IP	UDINT			—
	Remote UDP Port	UINT			—
	Production Multicast IP	UDINT			Multicast IP used for production (or 0)
	Consumption Multicast IP	UDINT			Multicast IP used for consumption (or 0)
	Protocols Supported	UDINT			Protocol supported on the connection: 1 = EtherNet/IP

The following values describe the structure of the instance attributes: *CIP Connection State*, *Input Communication Status*, and *Output Communication Status*:

Bit Number	Description	Values
153	Reserved	0
2	Idle	0 = no idle notification 1 = idle notification
1	Consumption inhibited	0 = consumption started 1 = no consumption
0	Production inhibited	0 = production started 1 = no production

The EtherNet/IP Interface Diagnostics object performs the following services upon the listed object types:

Service ID		Description	Class	Instance	Notes		
hex	dec	_					
01	01	Get_Attributes_All	Х	Х	Returns the value of all attributes.		
0E	14	Get_Attribute_Single	—	Х	Returns the value of the specified attribute.		
4C	76	Get_and_Clear	—	х	Returns and clears the values of all instance attributes.		
	X = supported — = not supported						

# EtherNet/IP Explicit Connection Diagnostics Object

#### Overview

The EtherNet/IP Explicit Connection Diagnostics object presents the instances, attributes and services described below.

#### **Class ID**

353 (hex), 851 (decimal)

#### **Instance IDs**

The EtherNet/IP Explicit Connection Diagnostics object presents two instance values:

- 0: class
- 1...*N*: instance (*N* = maximum concurrent number of diagnostic lists)

#### **Attributes**

EtherNet/IP Explicit Connection Diagnostics object attributes are associated with each instance, as follows:

Instance ID = 0 (class attributes):

Attribute ID hex	Description	Value	GET	SET		
01	Revision	1	х	—		
02	Max Instance	0N	Х	—		
X = supported — = not supported						

#### Instance ID = 1 to *N* (instance attributes):

Attribute ID hex	Description	Туре	GET	SET	Value	
01	Originator connection ID	UDINT	х	—	Originator to target connection ID	
02	Originator IP	UDINT	Х	—		
03	Originator TCP Port	UINT	Х	—		
04	Target connection ID	UDINT	Х	—	Target to originator connection ID	
05	Target IP	UDINT	Х	—		
06	Target TCP Port	UINT	Х	—		
X = supported — = not supported						

Attribute ID hex	Description	Туре	GET	SET	Value	
06	Msg Send Counter	UDINT	х	_	Incremented each time a Class 3 CIPMessage is sent on the connection	
07	Msg Receive counter	UDINT	Х	_	Increments each time a Class 3 CIP message is received on the connection	
X = supported — = not supported						

The EtherNet/IP Explicit Connection Diagnostics object performs the following services upon the listed object type:

Service ID		Description	Class Instance		Notes	
hex	dec					
01	01	Get_Attributes_All	Х	X	Returns the value of all attributes.	
X = supported — = not supported						

# EtherNet/IP Explicit Connection Diagnostics List Object

#### Overview

The EtherNet/IP Explicit Connection Diagnostics List object presents the instances, attributes and services described below.

#### **Class ID**

354 (hex), 852 (decimal)

#### **Instance IDs**

The EtherNet/IP Explicit Connection Diagnostics List object presents two instance values:

- 0: class
- 1...N: instance

#### **Attributes**

EtherNet/IP Explicit Connection Diagnostics List object attributes are associated with each instance, as follows:

Instance ID = 0 (class attributes):

Attribute ID	Description	GET	SET		
01	Revision	х	—		
02	Max Instance	х	—		
X = supported — = not supported					

#### Instance ID = 1 to *N* (instance attributes):

Attribute ID	Description	Туре	GET	SET	Value	
01	Number of connections	UINT	Х	—	Total number of opened explicit connections	
X = supported — = not supported						

Attribute ID	Description	Туре	GET	SET	Value
02	Explicit Messaging Connections Diagnostic List	ARRAY of STRUCT	x	-	
	Originator connection ID	UDINT			O->T connection ID
	Originator IP	UDINT			—
	Originator TCP port	UINT			—
	Target connection ID	UDINT			T->O connection ID
	Target IP	UDINT			—
	Target TCP port	UINT			—
	Msg Send counter	UDINT			Increments each time a Class 3 CIP message is sent on the connection
	Msg Receive counter	UDINT			Increments each time a Class 3 CIP message is received on the connection

The EtherNet/IP Explicit Connection Diagnostics object performs the following services upon the listed object types:

Service ID		Description	Class Instance		Notes
hex	dec				
01	01	Get_Attributes_All	Х	_	Returns the value of all attributes.
08	08	Create	х	—	—
09	09	Delete	—	Х	—
4B	75	Explicit_Connections_Di agnostic_Read	—	Х	-
X = sup — = no	oported ot supported	Ŀ			

# Chapter 7 Online Action

#### Overview

The Ethernet communication module supports online actions that let you:

- display CIP objects for the communication module or a remote EtherNet/IP device
- view and edit port configuration parameters for the communication module or a remote EtherNet/IP device
- ping the communication module or a remote EtherNet/IP or Modbus TCP device to confirm it is active on the Ethernet network
- connect to a remote device and then:
  - view the remote device's default parameter settings
  - · view the remote device's current parameter settings
  - · edit and download to the remote device its editable parameter settings

#### What Is in This Chapter?

This chapter contains the following topics:

Торіс	Page
Accessing CIP Objects	276
Editing Port Configuration Properties for Remote EtherNet/IP Devices	278
Pinging a Network Device	281
Viewing and Editing Online Settings for a Remote Device	283

## **Accessing CIP Objects**

#### **Overview**

Use the Module Information page of the Online Action window to:

- retrieve and display current data describing the state of CIP objects for the selected communication module or remote EtherNet/IP device, and
- reset the selected communication module or remote EtherNet/IP device

**NOTE:** Before you can perform online actions for a communication module or remote device, connect its DTM to the physical module or device. To do this, select the module or device node in the **DTM Browser**, then select **Edit**  $\rightarrow$ **Connect**.

The appearance of this page, and the CIP object information you can retrieve, depend upon the operating mode of the Unity Pro software:

In this mode	You can display data for these CIP objects	
Standard mode	Identity object (see page 245)	
Advanced mode (see page 48)	<ul> <li>Identity object</li> <li>Connection Manager object (see page 249)</li> <li>TCP/IP Interface object (see page 256)</li> <li>Ethernet Link object (see Quantum, 140 NOC 771 01 Ethernet Communication Module, User Manual)</li> <li>QoS object (see page 254)</li> </ul>	

The Module Information page looks like this:

Crown/Decomptor	Value	Unit	
Group/Parameter	value	Unit	Refresh
Vendor ID			Object
Product Code			Identity
Revision			
Serial Number			C Connection Manager
Product Name     Status			C TCP/IP
E Coverage C			
Configured			C Ethernet Link
Extended Device Status			
Major Unrecoverable Fault			Instance 1
Major Recoverable Fault			C QoS
Minor Unrecoverable Fault			
Minor Recoverable Fault			
			Reset Device
C Description			

## Retrieve and Display CIP Object Data

To display CIP object data for an EtherNet/IP communication module or remote device:

Step	Action
1	In the <b>DTM Browser</b> , select a communication module.
2	Click the right mouse button, and in the pop-up menu select <b>Device menu</b> $\rightarrow$ <b>Online Action</b> . The <b>Online Action</b> window opens.
3	In the left pane of the <b>Online Action</b> window, select a communication module or EtherNet/IP device.
4	In the right pane, click on the Module Information tab to open that page.
5	If Unity Pro is operating in Advanced Mode <ul> <li>Select one of the following CIP objects:</li> <li>Identity</li> <li>Connection Manager</li> <li>TCP/IP</li> <li>Ethernet Link</li> <li>QoS</li> </ul>
	• If you selected a multi-port module or device in step 3, above, select an <b>Interface</b> , or port, number
	<b>NOTE:</b> If Unity Pro is operating in Standard Mode, it will display data only for the CIP Identity object.
6	Click the <b>Refresh</b> button to update the data displayed.

#### Reset a Communication Module or Remote EtherNet/IP Device

To reset a communication module or remote EtherNet/IP device:

Step	Action
1	In the DTM Browser, select a communication module.
2	Click the right mouse button, and in the pop-up menu select <b>Device menu</b> $\rightarrow$ <b>Online Action</b> . The <b>Online Action</b> window opens.
3	In the left pane of the <b>Online Action</b> window, select a communication module or EtherNet/IP device.
4	In the right pane, click on the Module Information tab to open that page.
5	Click the <b>Reset Device</b> button.

# Editing Port Configuration Properties for Remote EtherNet/IP Devices

#### **Overview**

Use the **Port Configuration** page of the **Online Action** window to view and edit communication port properties for a remote EtherNet/IP device. Specifically, you can use this page to execute a:

- Get command to retrieve port configuration settings from a remote EtherNet/IP device
- Set command that writes all or selected edited values to the same remote EtherNet/IP device

Configuration edits transmitted from this page are sent as EtherNet/IP explicit messages and employ the **Address** and **Messaging** settings configured in the **EtherNet/IP Explicit Messaging** window.

**NOTE:** Before you can perform online actions for a remote device, connect its DTM to the physical device. To do this, select the device node in the **DTM Browser**, then select **Edit**  $\rightarrow$ **Connect**.

The Port Configuration page looks like this:

Group/Parameter	Value	Unit	Physical Interface Instance
Gloup/Farameter	value	Unit	
Startup Configuration		-	<ul> <li>Refresh</li> </ul>
DNS Enable		-	
			<u></u>
Device IP Address			Get Values from Device
New IP Address			
Gateway Address		-	Set All Values to Device
Sub Network Mask		-	Set All values to Device
Primary DNS Server Address			Set Part of Values
Secondary DNS Server		-	Set Part of values
Domain Name			General
Host Name			
Name		-	<ul> <li>TCP/IP Parameters</li> </ul>
Physical Interface			C Host Name
Get: Link Status			
Get: Duplex Mode			<ul> <li>Physical Interface</li> </ul>
Get: Negotiation Status			1
Get: Interface Speed		Mbps	Set Values to Device
Set: 802.3 Link Auto-Negotiation	Disable		
Set: Forced Duplex Mode	Half Duplex		
Set: Forced Interface Speed	Indeterminate	Mbps	
Description			

## Get Port Configuration Settings

To get settings from a remote EtherNet/IP device on the network:

Step	Action
1	In the <b>DTM Browser</b> , select the communication module upstream of the remote EtherNet/IP device.
2	Click the right mouse button, and in the pop-up menu select <b>Device menu</b> $\rightarrow$ <b>EtherNet/IP Explicit Message</b> . The <b>EtherNet/IP Explicit Message</b> window opens.
3	In the EtherNet/IP Explicit Messaging page, complete the <b>Address</b> section. <b>Note</b> : Port configuration explicit messages are sent as unconnected messages.
4	Return to the <b>DTM Browser</b> and again select the communication module upstream of the remote EtherNet/IP device.
5	Click the right mouse button, and in the pop-up menu select <b>Device menu</b> $\rightarrow$ <b>Online Action</b> . The <b>Online Action</b> window opens.
6	In the left pane of the <b>Online Action</b> window, select a remote EtherNet/IP device.
7	In the right pane, click on the <b>Port Configuration</b> tab to open that page.
8	If the remote device consists of more than one port, select the port number in the <b>Physical Interface Instance</b> list.
9	In the <b>Port Configuration</b> page, click the <b>Get Values from Device</b> button. The table displays the returned values of the communication properties for the selected remote device and port.

#### **Edit and Set Port Configuration Settings**

To edit and set port configuration settings that were retrieved using the above-described **Get Port Configuration Settings** process:

Step	Action
1	Double-click the left mouse button in the <b>Value</b> cell for the parameter you want to edit. The cell becomes editable. <b>Note:</b> The page also displays a <b>Description</b> of the selected parameter.
2	Type in, or select, the new value.
3	Repeat steps 1 - 2 for each parameter you want to edit.
4	<ul> <li>Do one of the following:</li> <li>Click the Set All Values to Device to write every value to the remote device - or -</li> <li>if you edited parameters for only one part, or group, of the collection of remote device values, then: <ul> <li>in the Set Part of Values area, select one property group, then</li> <li>click the Set Values to Device button</li> </ul> </li> </ul>
	Unity Pro sends the property value edits to the remote device via an EtherNet/IP explicit message, and displays the results in the <b>Description</b> area.

# **Pinging a Network Device**

#### **Overview**

Use the Unity Pro ping function to send an ICMP echo request to a target Ethernet device to determine:

- if the target device is present, and if so
- the elapsed time to receive an echo response from the target device

The target device is identified by its IP address setting. Unity Pro will verify that the target address is not a:

- loopback address (127.000.000.000 to 127.255.255.255)
- multicast address (224.000.000.000 to 239.255.255.255)
- reserved address (240.000.000.000 to 255.255.255)
- broadcast address

The ping function can be performed in the Ping page of the Online Action window:

Module Information	Port Configuration	Ping	
Address			
IP Address	192.168.1.6		
Ping Ping Repeat (100ms) Stop on Error Clear	Ping Result		

## Pinging a Network Device

To ping a network device:

Step	Action
1	In the <b>DTM Browser</b> , select the communication module upstream of the remote EtherNet/IP device you want to ping.
2	Click the right mouse button and select <b>Device Menu &gt;</b> → <b>Online Action</b> in the pop-up menu. The <b>Online Action</b> window opens.
3	In the <b>Online Action</b> window, select the device you want to ping. The window displays pages containing online information for the selected device.
	<ul> <li>NOTE: The specific collection of displayed pages depends on the type of device selected:</li> <li>the communication module</li> <li>a remote EtherNet/IP device</li> <li>a remote Modbus TCP device</li> </ul>
4	<ul> <li>Select the <b>Ping</b> page. To send</li> <li>a single ping, de-select the <b>Repeat</b> checkbox</li> <li>a series of pings—1 every 100 ms—select <b>Repeat</b> checkbox</li> </ul>
5	(Optional) Select <b>Stop on Error</b> to stop pinging an unsuccessful communication.
6	Click Ping once to begin pinging.
7	Click <b>Ping</b> a second time to stop repeated pinging, where no error has been detected.
8	The <b>Ping Result</b> box displays the ping outcome. Click <b>Clear</b> to empty the <b>Ping Result</b> box.

# Viewing and Editing Online Settings for a Remote Device

#### Introduction

Use the Online Parameters window to:

- view the remote device's default parameter settings
- · view the remote device's current parameter settings
- edit and download to the remote device its editable parameter settings

Parameter setting edits transmitted from this page are sent as EtherNet/IP explicit messages and employ the **Address** and **Messaging** settings configured in the **EtherNet/IP Explicit Messaging** window.

**NOTE:** Before you can view and edit online settings for a remote device, connect its DTM file to the physical device. To do this, select the device node in the **DTM Browser**, then select **Edit**  $\rightarrow$  **Connect**.

Step	Action
1	In the <b>DTM Browser</b> , select the node for a remote device.
2	Click the right mouse button, and in the pop-up menu select <b>Device menu</b> $\rightarrow$ <b>Online Parameters</b> . The <b>Online Parameters</b> window opens for the selected remote device.
3	In the left pane of the <b>Online Parameters</b> window, select a connection node. Unity Pro displays the parameters relating to the selected connection in the right pane.
	<ul> <li>NOTE: The list of parameters displayed in the Online Parameters window depends upon:</li> <li>the device selected in the DTM Browser, and</li> <li>the connection selected in the left pane of the Online Parameters window</li> </ul>

To open the Online Parameters window, follow these steps:

An example of the **Online Parameters** window—in this case for the STB NIC 2212 remote network interface device—looks like this:

	Parameter	Value	Unit	Get Values from EDS
	Input Size	0		
	Output Size	0		
	HMI to PLC Size	0		<b>0</b> 1 1
	PLC to HMI Size	0		Synchronize
	Diagnostic Data Size	20		
Stat	us			

Read-only parameters are identified by a locked icon 🛔 .

Editable parameters are identified by a blue arrowhead **b**.

#### **Displaying Default Parameter Settings**

To view the default parameter settings for the remote device, click the **Get Values from EDS** button. Unity Pro reads the default device values from its EDS file and displays them on-screen.

#### **Displaying Online Parameter Settings**

To view the current parameter settings for the remote device, follow these steps:

Step	Action
1	With a connection selected in the left pane, click the <b>Synchronize</b> button. The <b>Synchronize Action</b> message box opens.
2	<ul> <li>In the message box, select Read values from the device, then click OK.</li> <li>The message box closes. In the Online Parameters window:</li> <li>the Status field displays the results of the read transaction</li> <li>the parameter list displays current values</li> </ul>

## **Editing Online Parameter Settings**

To edit parameter settings for the remote device, follow these steps:

Step	Action
1	<ul> <li>With a connection selected in the left pane, display either:</li> <li>default device settings, or</li> <li>current device settings</li> </ul>
2	In the <b>Value</b> column, type in or select a new value for each setting you want to edit.
	<b>NOTE:</b> When you select a parameter, the <b>Description</b> area displays an explanation of the parameter and its available settings.
3	Click the Synchronize button. The Synchronize Action message box opens.
4	In the message box, select <b>Write data to the device</b> , then click <b>OK</b> . The message box closes. In the <b>Online Parameters</b> window, the <b>Status</b> field displays the results of the write transaction.

# Chapter 8 Explicit Messaging

#### **Overview**

The BMX NOC 0401 Ethernet communication module supports explicit messaging by means of both the EtherNet/IP and Modbus TCP protocols.

To create an explicit message for the EtherNet/IP protocol, use the  ${\tt DATA\_EXCH}$  function block in application logic.

To create an explicit message for the Modbus TCP protocol, use any one of the following function blocks in application logic: DATA\_EXCH, READ\_VAR, or WRITE\_VAR.

**NOTE:** A single Unity Pro application can contain more than 16 explicit messaging blocks, but only 16 explicit messaging blocks can be active at the same time.

This chapter describes how to configure both EtherNet/IP and Modbus TCP explicit messages by using:

- the DATA\_EXCH function block in application logic
- the Unity Pro graphical user interface

#### What Is in This Chapter?

This chapter contains the following sections:

Section	Торіс	Page
8.1	Explicit Messaging Using the DATA_EXCH Block	288
8.2	EtherNet/IP Explicit Messaging Using DATA_EXCH	292
8.3	Modbus TCP Explicit Messaging Using DATA_EXCH	309
8.4	Explicit Messaging via the Unity Pro GUI	317

# Section 8.1 Explicit Messaging Using the DATA\_EXCH Block

#### **Overview**

This section introduces you to the DATA\_EXCH function block, which you can use to configure both EtherNet/IP and Modbus TCP explicit messages.

This section describes how to configure the DATA\_EXCH function block's Management parameter, which is common to both Modbus TCP and EtherNet/IP explicit messaging.

#### What Is in This Section?

This section contains the following topics:

Торіс	Page
Configuring Explicit Messaging Using DATA_EXCH	
Configuring the DATA_EXCH Management Parameter	291

# Configuring Explicit Messaging Using DATA\_EXCH

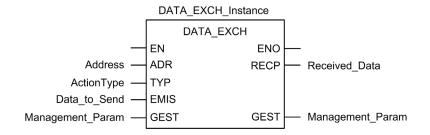
## Overview

Use the DATA\_EXCH function block to configure both Modbus TCP explicit messages and connected and unconnected EtherNet/IP explicit messages.

The Management\_Param, the Data\_to\_Send, and the Received\_Data parameters define the operation.

EN and ENO can be configured as additional parameters.

# **FBD Representation**



## **Input Parameters**

Parameter	Data type	Description
Address	Array [07] of INT	<ul> <li>The path to the destination device, the content of which can vary depending on the message protocol. Use the ADDM function.</li> <li>Refer to a description of the Address parameter for:</li> <li>EtherNet/IP messages (see page 295)</li> <li>Modbus TCP messages (see page 311)</li> </ul>
ActionType	INT	The type of action to perform. For both the EtherNet/IP and Modbus TCP protocols, this setting = 1 (transmission followed by await reception).
Data_to_Send	Array [nm] of INT	The content of this parameter is specific to the protocol, either EtherNet/IP or Modbus TCP. For EtherNet/IP explicit messaging, refer to the to the topic Configuring the Data_To_Send Parameter (see page 295). For Modbus TCP explicit messaging, refer to Unity Pro online help.

# Input/Output Parameters

Parameter	Data type	Description
Management_Param		The management parameter (see page 291), consisting of 4 words.

# **Output Parameters**

Parameter	Data type	Description
Received_Data	Array [nm] of INT	The EtherNet/IP (CIP) response (see page 296) or the Modbus TCP response (see page 312). The structure and content depends upon the specific protocol.

# Configuring the DATA\_EXCH Management Parameter

## Introduction

The structure and content of the management parameter of the DATA\_EXCH block is common to both EtherNet/IP and Modbus TCP explicit messaging.

## **Configuring the Management Parameter**

The management parameter consists of 4 contiguous words, described below:

Data source	Register	Description		
		High Byte (MSB)	Low Byte (LSB)	
Data managed by the system	Management_Param[0]	Exchange number	Two read-only bits: • Bit 0 = Activity bit (see below) • Bit 1 = Cancel bit	
	Management_Param[1]	Operation report (see page 428)	Communication report (see page 427)	
Data managed by the user	Management_Param[2]	<ul> <li>0 = infinite wait</li> <li>other values = timeout x 100 ms, for example:</li> <li>1 = 100 ms</li> <li>2 = 200 ms</li> </ul>		
	Management_Param[3]			

## Activity Bit:

This bit indicates the execution status of the communication function.

It is set to 1 when launched, and returns to 0 when its execution is complete.

It is the first bit of the first element of the table.

Example: if the management table has been declared as follows:

Management\_Param[0] ARRAY [0..3] OF INT,

the activity bit is the bit with the notation Management\_Param[0].0.

**NOTE:** The notation previously used requires configuration of the project properties in such a way as to authorize the extraction of bits on integer types. If this is not the case, Management Param[0].0 cannot be accessed in this manner.

# Section 8.2 EtherNet/IP Explicit Messaging Using DATA\_EXCH

#### **Overview**

This section shows you how to configure the  ${\tt DATA\_EXCH}$  function block for EtherNet/IP explicit messages.

#### What Is in This Section?

This section contains the following topics:

Торіс	Page
Explicit Messaging Services	293
Configuring EtherNet/IP Explicit Messaging Using DATA_EXCH	295
EtherNet/IP Explicit Message Example: Get_Attribute_Single	297
EtherNet/IP Explicit Message Example: Read Modbus Object	301
EtherNet/IP Explicit Message Example: Write Modbus Object	305

# **Explicit Messaging Services**

#### **Overview**

Every explicit message performs a service. Each service is associated with a service code (or number). You will need to identify the explicit messaging service by its name, decimal number, or hexadecimal number.

You can execute explicit messages using either the DATA\_EXCH function block in Unity Pro, or the Unity Pro Ethernet Configuration Tool.

#### **Services**

The services available in Unity Pro include, but are not limited to, the services listed below:

Service Code		Description	Available in		
Hex	Dec	-	DATA_EXCH block	Unity Pro GUI	
0	0	(Reserved)	—	—	
1	1	Get_Attributes_All	х	Х	
2	2	Set_Attributes_All	х	Х	
3	3	Get_Attribute_List	Х	—	
4	4	Set_Attribute_List	х	—	
5	5	Reset	Х	Х	
6	6	Start	х	Х	
7	7	Stop	х	х	
8	8	Create	х	Х	
9	9	Delete	Х	Х	
А	10	Multiple_Service_Packet	х	—	
B-C	11-12	(Reserved)	—	—	
D	13	Apply_Attributes	х	Х	
E	14	Get_Attribute_Single	х	х	
F	15	(Reserved)	—	—	
10	16	Set_Attribute_Single	х	Х	
11	17	Find_Next_Object_Instance	х	Х	
12-13	18-19	(Reserved)	—	—	
14	20	Error Response (DeviceNet only)	—	—	
15	21	Restore	Х	Х	
16	22	Save	Х	Х	
"X" indi	cates the	service is available. "-" indicates th	e service is not av	ailable.	

Service Code		Description	Available in	
Hex	Dec	_	DATA_EXCH block	Unity Pro GUI
17	23	No Operation (NOP)	х	х
18	24	Get_Member	х	Х
19	25	Set_Member	х	х
1A	26	Insert_Member	Х	х
1B	27	Remove_Member	х	х
1C	28	GroupSync	Х	—
1D-31	29-49	(Reserved)	—	—
"X" indicates the service is available. "-" indicates the service is not available.				

# Configuring EtherNet/IP Explicit Messaging Using DATA\_EXCH

## **Configuring the Address Parameter**

To configure the Address parameter, use the ADDM function to convert the character string, described below, to an address:

ADDM('rack.slot.channel{ip\_address}message\_type.protocol'), where:

This field	Represents
rack	the number assigned to the rack containing the communication module
slot	the position of the communication module in the rack
channel	the communication channel—set to a value of <b>0</b>
ip_address	the IP address of the remote device, for example 193.168.1.6
message_type	<ul> <li>the type of message, presented as a three character string—either:</li> <li>UNC (indicating an unconnected message), or</li> <li>CON (indicating a connected message)</li> </ul>
protocol	the protocol type—the three character string CIP

# Configuring the Data\_to\_Send Parameter

The Data\_to\_Send parameter varies in size. It consists of contiguous registers that include—in sequence—both the message type and the CIP request:

Offset (words)	Length (bytes)	Data Type	Description
0	2 bytes	Bytes	Message type: • High byte = size of the request in words • Low byte = EtherNet/IP service code
1	Management_Param[3] (size of Data_to_Send) minus 2	Bytes	The CIP request <sup>1</sup> . <b>NOTE:</b> The structure and size of the CIP request depends on the EtherNet/IP service.
1 Structure the CIP request in little endian order.			

#### Contents of the Received\_Data Parameter

The Received\_Data parameter contains only the CIP response. The length of the CIP response varies, and is reported by Management\_Param[3] after the response is received. The format of the CIP response is described, below:

Offset (words)	Length (bytes)	Data Type	Description
0	2	Byte	<ul> <li>High byte (MSB) = reserved</li> <li>Low byte (LSB): reply service</li> </ul>
1	2	Byte	<ul> <li>High byte (MSB): length of additional status</li> <li>Low byte (LSB): EtherNet/IP general status (see page 431)</li> </ul>
2	length of additional status	Byte array	Additional Status <sup>1</sup>
	Management_Param[3] (size of Received_Data) minus 4, and minus the additional status length	Byte array	Response data

1. Refer to The CIP Networks Library, Volume 1, Common Industrial Protocol at section 3-5.6 Connection Manager Object Instance Error Codes.

NOTE: The response is structured in little endian order.

## Checking the Received\_Data Response for System and CIP Status

Use the contents of the Received\_Data parameter to check both the system status and the CIP status of the Ethernet communication module when handling the explicit message.

**First:** Check the value of the high byte (MSB) of the first response word, positioned at offset 0. If the value of this byte is:

- equal to 0: the system properly handled the explicit message
- not equal to 0: a system-based event occurred Refer to the list of EtherNet/IP Explicit Messaging Event Codes (see page 424) for an explanation of the system-based event code contained in the second response word, positioned at offset 1.

**Next:** If the system properly handled the explicit message, and the high byte of the first response word equals 0, check the value of the second response word, positioned at offset 1. If the value of this word is:

- equal to 0: the explicit message was properly handled by the CIP protocol
- not equal to 0: a CIP protocol-based event occurred Refer to your CIP documentation for an explanation of the CIP status displayed in this word.

# EtherNet/IP Explicit Message Example: Get\_Attribute\_Single

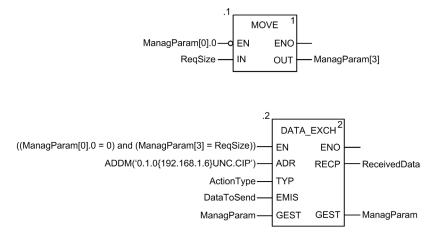
#### **Overview**

The following unconnected explicit messaging example shows you how to use the DATA\_EXCH function block to retrieve diagnostic data from a remote device—in this case an STB NIC 2212 network interface module at IP address 192.168.1.6—using the Get\_Attribute\_Single service.

You can perform the same explicit messaging service using the **EtherNet/IP Explicit Message** window of the Unity Pro Ethernet Configuration Tool (*see page 318*).

#### Implementing the DATA\_EXCH Function Block

To implement the DATA\_EXCH function block, you need to create and assign variables for the following blocks:



#### **Declaring Variables**

In this example, the following variables were defined. You can, of course, use different variable names in your explicit messaging configurations.

In this example, the following variables were defined. You can, of course, use different variable names in your explicit messaging configurations.

1 1	ction Blocks DFB Type	s		
Filter	X			
Name 🏠	Туре 🗸	Value	Comment -	Used 🗸
ActionType	INT	16#01	Transmission followed by await reception	1
DataToSend	ARRAY[03] OF INT			2
🔷 DataToSend[0]	INT	16#030E	Request size in words; Get_Attribute_Single	
🐤 DataToSend[1]	INT	16#0420	Class and Class Segment	
DataToSend[2]	INT	16#6424	Instance and Instance Segment	
DataToSend[3]	INT	16#0330	Attribute and Attribute Segment	6
🖻 🛽 ManagParam	ARRAY[03] OF INT			
	INT		MSB:Exchange #; LSB:bit 1=activity, bit 2=cancel	
🐤 ManagParam[1]	INT		Operation Report, Communication Report	
🔶 ManagParam[2]	INT	2	Function block timeout = 2 (200 ms)	
ManagParam[3]	INT	8	Length of DataToSend parameter, in bytes	2
🖭 🔋 ReceivedData	ARRAY[049] OF INT			2
	INT	8		3

## **Configuring the Address Variable**

The Address variable identifies the explicit message originating device (in this example, the communication module) and the target device. Note that the Address variable does not include the Xway address elements {Network.Station} because we are not bridging through another PLC station. Use the ADDM function to convert the following character string to an address:

ADDM('0.1.0{192.168.1.6}UNC.CIP'), where:

- rack = 0
- module (slot number) = 1
- channel = 0
- remote device IP address = 192.168.1.6
- message type = unconnected
- protocol = CIP

## Configuring the ActionType Variable

The ActionType variable identifies the function type for the DATA EXCH function block:

Variable	Description	Value (hex)
ActionType	Transmission followed by wait for response	16#01

# Configuring the DataToSend Variable

The DataToSend variable identifies the type of explicit message and the CIP request:

Variable	Description	Value (hex)
DataToSend[0]	<ul> <li>CIP request service information:</li> <li>High byte = request size in words: 16#03 (3 decimal)</li> <li>Low byte = service code: 16#0E (14 decimal)</li> </ul>	16#030E
DataToSend[1]	CIP request class information: • High byte = class: 16#04 (4 decimal) • Low byte = class segment: 16#20 (32 decimal)	16#0420
DataToSend[2]	<ul> <li>CIP request instance information:</li> <li>High byte = instance: 16#64 (100 decimal)</li> <li>Low byte = instance segment: 16#24 (36 decimal)</li> </ul>	16#6424
DataToSend[3]	<ul> <li>CIP request attribute information:</li> <li>High byte = attribute: 16#03 (3 decimal)</li> <li>Low byte = attribute segment: 16#30 (48 decimal)</li> </ul>	16#0330

# Viewing the Response

Use a Unity Pro Animation table to display the ReceivedData variable array. Note that the ReceivedData variable array consists of the entire data buffer.

To display the CIP response, follow these steps:

Step	Action		
1	In Unity Pro, select To	ols →Project Browser to open the Project Browser.	
2	In the Project Browser, select the <b>Animation Tables</b> folder, then click the right mouse button. A pop-up menu appears.		
3	Select <b>New Animation Table</b> in the pop-up menu. A new animation table and its properties dialog both open.		
4	In the Properties dialog, edit the following values:		
	Name	Type in a table name. For this example: ReceivedData.	
	Functional module	Accept the default <b><none></none></b> .	
	Comment (Optional) Type your comment here.		
	Number of animated characters         Type in 100, representing the size of the data buffer in words.		

Step	Action			
5	The completed Properties	dialog looks li	ke this:	
	Properties		×	
	Name:	Functional n	nodule:	
	ReceivedData	<none></none>		
	1			
	Comment:			
			<u> </u>	
			-	
	_Extended String Animation			
	Number of animated charact	ers 100	range: (20-300)	
		,		
		ок	Cancel	
	Click OK to close the dialog	g.		
6	In the animation table's Na	me column, ty	pe in the name of t	he variable assigned to
	the RECP pin: ReceivedD			-
	ReceivedData variable.			
7	Expand the ReceivedData	variable to disc	lav its word arrav.	where you can view the
	CIP response contained in	•	•	· · <b>,</b> · · · · · · · ·
	ReceivedData			
	Modification Force	I F I	<i>⊾</i> × ∎ ×	
		-		
	Name	Value		Comment
	ReceivedData     ReceivedData[0]	16#008E	ARRAY[049]OF INT	
	<ul> <li>ReceivedData[1]</li> </ul>	16#0000	INT	
	ReceivedData[2]	16#10A0	INT	
	ReceivedData[3]	16#0000 16#000F	INT INT	
	ReceivedData[4]	16#0000	INT	
	<ul> <li>ReceivedData[6]</li> </ul>	16#0000	INT	
	ReceivedData[7]	16#0000	INT	
	ReceivedData[8]	16#0000	INT	
	ReceivedData[9]	16#0000	INT	
	ReceivedData[10]	16#000F	INT	
	ReceivedData[11]	16#0000	INT	
	ReceivedData[12]	16#0000	INT	<b></b>
	Note: Each array entry pre	sents 2 bytes	of data in little end	ian format, where the
1				
	least significant byte is stor	ed in the small	est memory addres	ss. For example, '8E' in

# EtherNet/IP Explicit Message Example: Read Modbus Object

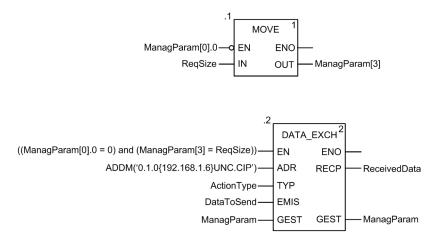
#### **Overview**

The following unconnected explicit messaging example shows you how to use the DATA\_EXCH function block to read data from a remote device—in this case an STB NIC 2212 network interface module at IP address 192.168.1.6—using the Read\_Holding\_Registers service of the Modbus Object.

You can perform the same explicit messaging service using the **EtherNet/IP Explicit Message** window of the Unity Pro Ethernet Configuration Tool (*see page 318*).

## Implementing the DATA\_EXCH Function Block

To implement the DATA\_EXCH function block, you need to create and assign variables for the following blocks:



#### **Declaring Variables**

In this example, the following variables were defined. You can, of course, use different variable names in your explicit messaging configurations.

Variables DDT Types	Function Blocks	DFB T	ypes	
Filter Nan	ne = [*			
Name 🗠	Туре	<b>•</b>	Value	Comment
	INT		16#01	Transmission followed by await reception
🖻 🔋 DataToSend	ARRAY[04] (	OF INT		
— DataToSend[0]	INT		16#024E	HiByte=02 (Path Size); LowByte=4E (Service Code: Read Holding Reg
— State Data Data To Send[1]	INT		16#4420	HiByte=44 (Class); LowByte=20 (Class Segment)
DataToSend[2]	INT		16#0124	HiByte=01 (Instance); LowByte=24 (Instance Segment)
DataToSend[3]	INT		16#0031	Location of first word to READ
DataToSend[4]	INT		16#0001	Number of words to READ (1)
🖃 📗 ManagParam	ARRAY[03] (	OF INT		
- S ManagParam[0]	INT			System Response (MSB:Exchange #; LSB:bit 1=activity, bit 2=cancel)
- S ManagParam[1]	INT			System Response (Operation Report, Communication Report)
ManagParam[2]	INT		2	User Configuration (Function block timeout = 2 (200 ms))
ManagParam[3]	INT		10	Length of DataToSend parameter, in bytes
E ReceivedData	ARRAY[049]	OF INT		
RegSize	INT		10	DataToSend size, in Bytes
-				

## **Configuring the Address Variable**

The Address variable identifies the explicit message originating device (in this example, the Ethernet communication module) and the target device. Note that the Address variable does not include the Xway address elements {Network.Station} because we are not bridging through another PLC station. Use the ADDM function to convert the following character string to an address:

ADDM('0.1.0{192.168.1.6}UNC.CIP'), where:

- rack = 0
- module (slot number) = 1
- channel = 0
- remote device IP address = 192.168.1.6
- message type = unconnected
- protocol = CIP

#### Configuring the ActionType Variable

The ActionType variable identifies the function type for the DATA EXCH function block:

Variable	Description	Value (hex)
ActionType	Transmission followed by wait for response	16#01

# Configuring the DataToSend Variable

The DataToSend variable identifies the type of explicit message and the CIP request:

Variable	Description	Value (hex)
DataToSend[0]	<ul> <li>CIP request service information:</li> <li>High byte = request size in words: 16#02 (2 decimal)</li> <li>Low byte = service code: 16#4E (78 decimal)</li> </ul>	16#024E
DataToSend[1]	<ul> <li>CIP request class information:</li> <li>High byte = class: 16#44 (68 decimal)</li> <li>Low byte = class segment: 16#20 (32 decimal)</li> </ul>	16#4420
DataToSend[2]	<ul> <li>CIP request instance information:</li> <li>High byte = instance: 16#01 (1 decimal)</li> <li>Low byte = instance segment: 16#24 (36 decimal)</li> </ul>	16#0124
DataToSend[3]	Location of first word to be read): • High byte = 16#00 (0 decimal) • Low byte = 16#31 (49 decimal)	16#0031
DataToSend[4]	<ul> <li>Number of words to read:</li> <li>High byte = attribute: 16#00 (0 decimal)</li> <li>Low byte = attribute segment: 16#01 (1 decimal)</li> </ul>	16#0001

# Viewing the Response

Use a Unity Pro Animation table to display the ReceivedData variable array. Note that the ReceivedData variable array consists of the entire data buffer.

To display the CIP response, follow these steps:

Step	Action		
1	In Unity Pro, select To	ols →Project Browser to open the Project Browser.	
2	In the Project Browser, select the <b>Animation Tables</b> folder, then click the right mouse button. A pop-up menu appears.		
3	Select <b>New Animation Table</b> in the pop-up menu. A new animation table and its properties dialog both open.		
4	In the Properties dialog, edit the following values:		
	Name	Type in a table name. For this example: <b>ReceivedData</b> .	
	Functional module	Accept the default <b><none></none></b> .	
	Comment (Optional) Type your comment here.		
	Number of animated characters	Type in <b>49</b> , representing the size of the data buffer in words.	

Step	Action			
5	The completed Properties	dialog looks	like this:	
	Properties		×	
	Name:	Functional		
	ReceivedData	<none></none>		
	ReceivedData	<note></note>	<u> </u>	
	Comment:			
			*	
	]		<u> </u>	
	Extended String Animation		(00.000)	
	Number of animated charac	ters 49	range: (20-300)	
			Concel	
		ОК	Cancel	
	Click OK to close the dialo	g.		
6	In the animation table's Na	me column ty	vpe in the name of	the variable assigned to
Ũ	the RECP pin: ReceivedD		•	-
	ReceivedData variable.			
7				
7	Expand the ReceivedData the CIP response contained			
	ReceivedData			
	Modification Force	1 1 1	<i>⊾</i> ≭ ≣ ≯	H 🛃 🖻
	Name -	Value	Туре 🗸	Comment 🔺
	ReceivedData	40//00000	ARRAY[049]OF IN	Г
	ReceivedData[0]	16#00D0 16#0000	INT INT	
	ReceivedData[1]	16#0000	INT	
	ReceivedData[3]	16#0001	INT	
	ReceivedData[4]	16#0000	INT	
	ReceivedData[5]	16#0000	INT	
	ReceivedData[6]	16#0000	INT	
	ReceivedData[7]	16#0000	INT	
	ReceivedData[8]	16#0000 16#0000	INT INT	
	ReceivedData[9]	16#0000	INT	
	ReceivedData[10]     ReceivedData[11]	16#0000	INT	
	ReceivedData[12]	16#0000	INT	<b>•</b>
	p			
	Note: Each array entry pre	sents 2 huter	of data in little or	idian format where the
	least significant byte is sto			
1	icasi siyiincani uyte is sto		anest memory duu	iess. FUI example, UE
	in word[0] is the lower byte	and '00' in +	a uppor buto	

# EtherNet/IP Explicit Message Example: Write Modbus Object

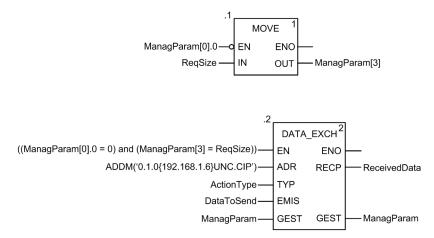
## **Overview**

The following unconnected explicit messaging example shows you how to use the DATA\_EXCH function block to write data to a remote device—in this case an STB NIC 2212 network interface module at IP address 192.168.1.6—using the Write\_Holding\_Registers service of the Modbus Object.

You can perform the same explicit messaging service using the **EtherNet/IP Explicit Message** window of the Unity Pro Ethernet Configuration Tool (*see page 318*).

## Implementing the DATA\_EXCH Function Block

To implement the DATA\_EXCH function block, you need to create and assign variables for the following blocks:



## **Declaring Variables**

In this example, the following variables were defined. You can, of course, use different variable names in your explicit messaging configurations.

Variables DDT Types	Function Blocks DI	FB Types		
Filter				
Name	Туре 🗸	Value	Comment •	
- SctionType	INT	16#01	Transmission followed by await reception	
DataToSend	ARRAY[05] OF INT			
OataToSend[0]	INT	16#0250	HiByte=02 (Path Size); LowByte=50 (Service Code Write Holding Reg	
🔶 DataToSend[1]	INT	16#4420	HiByte=44 (Class); LowByte=20 (Class Segment)	
DataToSend[2]	INT	16#0124	HiByte=01 (Instance); LowByte=24 (Instance Segment)	
🍤 DataToSend[3]	INT	16#0000	Location of first word to write at target (value + %MW1)	
DataToSend[4]	INT	16#0001	Number of words to WRITE (1)	
DataToSend[5]	INT	16#006F	Data to WRITE (the decimal value 111)	
🖻 📗 ManagParam	ARRAY[03] OF INT			
	INT		System Response (MSB:Exchange #; LSB:bit 1=activity, bit 2=cancel	
ManagParam[1]	INT		System Response (Operation Report, Communication Report)	
— 🔶 ManagParam[2]	INT	2	User Configuration (Function block timeout = 2 (200 ms))	
ManagParam[3]	INT	0	Program Action (ReqSize Value MOVE to ManagParam[3]	
🖲 🛽 ReceivedData	ARRAY[049] OF IN	Т		
- 🕏 ReqSize	INT	12	DataToSend size, in Bytes	
b				

#### **Configuring the Address Variable**

The Address variable identifies the explicit message originating device (in this example, the communication module) and the target device. Note that the Address variable does not include the Xway address elements {Network.Station} because we are not bridging through another PLC station. Use the ADDM function to convert the following character string to an address:

ADDM('0.1.0{192.168.1.6}UNC.CIP'), where:

- rack = 0
- module (slot number) = 1
- channel = 0
- remote device IP address = 192.168.1.6
- message type = unconnected
- protocol = CIP

#### Configuring the ActionType Variable

The ActionType variable identifies the function type for the DATA EXCH function block:

Variable	Description	Value (hex)
ActionType	Transmission followed by wait for response	16#01

# Configuring the DataToSend Variable

The DataToSend variable identifies the type of explicit message and the CIP request:

Variable	Description	Value (hex)
DataToSend[0]	<ul> <li>CIP request service information:</li> <li>High byte = request size in words: 16#02 (2 decimal)</li> <li>Low byte = service code: 16#50 (80 decimal)</li> </ul>	16#0250
DataToSend[1]	<ul> <li>CIP request class information:</li> <li>High byte = class: 16#44 (68 decimal)</li> <li>Low byte = class segment: 16#20 (32 decimal)</li> </ul>	16#4420
DataToSend[2]	CIP request instance information: • High byte = instance: 16#01 (1 decimal) • Low byte = instance segment: 16#24 (36 decimal)	16#0124
DataToSend[3]	Location of first word to write (+ %MW1): • High byte = 16#00 (0 decimal) • Low byte = 16#00 (0 decimal)	16#0000
DataToSend[4]	<ul> <li>nd[4] Number of words to write:</li> <li>High byte = attribute: 16#00 (0 decimal)</li> <li>Low byte = attribute segment: 16#01 (1 decimal)</li> </ul>	
DataToSend[5]	Data to write: • High byte = attribute: 16#00 (0 decimal) • Low byte = attribute segment: 16#6F (111 decimal)	16#006F

#### Viewing the Response

Use a Unity Pro Animation table to display the ReceivedData variable array. Note that the ReceivedData variable array consists of the entire data buffer.

To display the CIP response, follow these steps:

Step	Action		
1	In Unity Pro, select To	ols →Project Browser to open the Project Browser.	
2	In the Project Browser, select the <b>Animation Tables</b> folder, then click the right mouse button. A pop-up menu appears.		
3	Select <b>New Animation Table</b> in the pop-up menu. A new animation table and its properties dialog both open.		
4	In the Properties dialog, edit the following values:		
	Name	Type in a table name. For this example: ReceivedData.	
	Functional module	Accept the default <b><none></none></b> .	
	Comment	(Optional) Type your comment here.	
	Number of animated characters	Type in <b>49</b> , representing the size of the data buffer in words.	

Step	Action					
5	The completed <b>Properties</b> dialog looks like this:					
	Properties		×			
	Name:	Functional	module:			
	ReceivedData	<none></none>				
	Comment:					
	Extended String Animation Number of animated charact	ers 49 OK	range: (20-300)			
	Click <b>OK</b> to close the dialog	].				
6	In the animation table's <b>Name</b> column, type in the name of the variable assigned to the RECP pin: <b>ReceivedData</b> and hit <b>Enter</b> . The animation table displays the ReceivedData variable.					
7	Expand the ReceivedData CIP response contained in			, where you can view the		
	ReceivedData					
	Modification Force	1 1 1	<i>⊾</i> ⊁ 🖩 ≯			
	Name 🗸	Value	Туре 🗸	Comment 🔺		
	ReceivedData		ARRAY[049]OF INT			
	ReceivedData[0]	16#00D0	INT			
	ReceivedData[1]	16#0000	INT			
	ReceivedData[2]	16#0000	INT			
	ReceivedData[3]     ReceivedData[4]	16#0001				
	<ul> <li>ReceivedData[4]</li> <li>ReceivedData[5]</li> </ul>	16#0000 16#0000	INT			
	ReceivedData[6]	16#0000	INT			
	ReceivedData[0]     ReceivedData[7]	16#0000	INT			
	<ul> <li>ReceivedData[7]</li> <li>ReceivedData[8]</li> </ul>	16#0000	INT			
	<ul> <li>ReceivedData[9]</li> </ul>	16#0000	INT			
	<ul> <li>ReceivedData[10]</li> </ul>	16#0000	INT			
	ReceivedData[11]	16#0000	INT			
	ReceivedData[12]	16#0000	INT	<b></b>		
	Note: Each array entry pre- least significant byte is store word[0] is the lower byte, a	ed in the sma	llest memory addre			

# Section 8.3 Modbus TCP Explicit Messaging Using DATA\_EXCH

## **Overview**

This section shows you how to configure  ${\tt DATA\_EXCH}$  function block parameters for Modbus TCP explicit messages.

# What Is in This Section?

This section contains the following topics:

Торіс	Page
Modbus TCP Explicit Messaging Function Codes	310
Configuring Modbus TCP Explicit Messaging Using DATA_EXCH	311
EtherNet/IP Explicit Message Example: Read Register Request	313

# Modbus TCP Explicit Messaging Function Codes

## Overview

You can execute Modbus TCP explicit messages using either a Unity Pro DATA\_EXCH function block or the Unity Pro Ethernet Configuration Tool's **Modbus Explicit Message Window**.

**NOTE:** Configuration edits made to an Ethernet communication module from the Unity Pro Ethernet Configuration Tool are not saved to the operating parameters stored in the CPU and, therefore, are not sent by the CPU to the module on startup.

## **Function Codes**

The function codes supported by the Unity Pro graphical user interface include the following standard explicit messaging functions:

Function Code (dec)	Description
1	Read bits (%M)
2	Read input bits (%I)
3	Read words (%MW)
4	Read input words (%IW)
15	Write bits (%M)
16	Write words (%MW)

**NOTE:** You can use the DATA\_EXCH function block to execute any Modbus function, via program logic. Because the available function codes are too numerous to list here, refer instead to the Modbus IDA website for more information about these Modbus functions, at:

http://www.Modbus.org.

# Configuring Modbus TCP Explicit Messaging Using DATA\_EXCH

## Introduction

When you use the DATA\_EXCH block to create an explicit message for a Modbus TCP device, configure this block the same way you would configure it for any other Modbus communication. Refer to the Unity Pro online help for instructions on how to configure the DATA\_EXCH block.

#### **Configuring ADDM Block Unit ID Settings**

When you configure the DATA\_EXCH block, use the ADDM block to set the DATA\_EXCH block's Address parameter. The ADDM block presents the configuration format ADDM('rack.slot.channel[ip\_address}UnitID.message\_type.protocol') where:

The parameter	Represents
rack	the number assigned to the rack containing the communication module
slot	the position of the communication module in the rack
channel	the communication channel—set to a value of 0
ip_address	the IP address of the remote device, for example, 192.168.1.7
Unit ID	the destination node address, also known as the Modbus Plus on Ethernet Transporter (MET) mapping index value
message_type	the three character string TCP
protocol	the three character string MBS

The Unit ID value in a Modbus message indicates the destination of the message. The manner in which the communication module handles the Unit ID value depends upon its role as either a server or a client. When the communication module acts as a:

- server: a message with Unit ID value of 255 is directed to and processed by the communication module itself. Other messages are passed to the CPU.
- **client:** a message with Unit ID value of 255 is directed to and handled by the communication module itself. Other values are passed to the CPU.

# Contents of the Received\_Data Parameter

The Received\_Data parameter contains the Modbus response. The length of the response varies, and is reported by Management\_Param[3] after the response is received. The format of the Modbus response is described, below:

Offset (words)	Length (bytes)	Description
0	2	<ul> <li>First word of the Modbus response:</li> <li>High byte (MSB): <ul> <li>if successful: Modbus Function Code</li> <li>if not: Modbus function code + 16#80</li> </ul> </li> <li>Low byte (LSB): <ul> <li>if successful: depends on the request</li> <li>if not: Modbus exception code</li> <li>(see page 435)</li> </ul> </li> </ul>
1	Length of the Received_Data parameter - 2	Remainder of the Modbus response: depends on the specific Modbus request)

**NOTE:** Structure the response in little endian order.

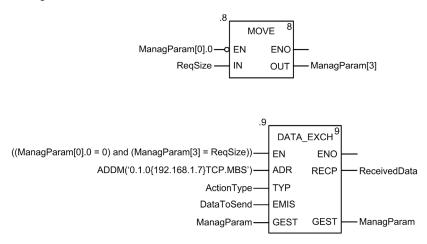
# EtherNet/IP Explicit Message Example: Read Register Request

#### **Overview**

The following example shows you how to use the DATA\_EXCH function block to send an explicit messaging Modbus TCP request to a remote device—in this case an STB NIP 2212 network interface module at IP address 192.168.1.7—to read a single word located in the remote device at register 5391.

## Implementing the DATA\_EXCH Function Block

To implement the DATA\_EXCH function block, you need to create and assign variables for the following blocks:



## **Declaring Variables**

In this example, the following variables were defined. You can, of course, use different variable names in your explicit messaging configurations.

In this example, the following variables were defined. You can, of course, use different variable names in your explicit messaging configurations.

Variables DDT Types	Function Blocks	DFB Type	s	
Filter	Name =  *		EDT DDT	
Name 🔷	Туре 👻	Value	Comment •	Used -
ActionType	INT	16#01	Transmission followed by await reception	1
E DataToSend	ARRAY[02] OF INT			2
DataToSend[0]	INT	16#1503	High byte of register address; Function Code	
DataToSend[1] INT		16#000F	High byte of number of registers to read; Low byte of register address	
DataToSend[2] INT 16#0001 Not used: Low byte of number of registers to read				
🖃 🔋 ManagParam	ARRAY[03] OF INT			6
ManagParam[0]	INT		High byte: Exchange #; Low byte: bit 1 = activity, bit 2 = cancel	
ImanagParam [1]	INT		Operation Report; Communication Report	
🌖 ManagParam[2]	INT	2	Function block timeout = 2 (200 ms)	
ManagParam[3]	INT	6	Length of DataToSend parameter, in bytes	2
🗉 🔋 ReceivedData	ARRAY[01] OF INT			2
ReqSize	INT	6		3
<b>b</b>				

## **Configuring the Address Variable**

The Address variable identifies the explicit message originating device (in this example, the communication module) and the target device. Note that the Address variable does not include the Xway address elements {Network.Station} because we are not bridging through another PLC station. Use the ADDM function to convert the following character string to an address:

ADDM('0.1.0{192.168.1.7}TCP.MBS'), where:

- rack = 0
- module (slot number) = 1
- channel = 0
- remote device IP address = 192.168.1.7
- message type = TCP
- protocol = Modbus

## Configuring the ActionType Variable

The ActionType variable identifies the function type for the DATA EXCH function block:

Variable	Description	Value (hex)
ActionType	Transmission followed by wait for response	16#01

# Configuring the DataToSend Variable

The DataToSend variable contains the target register address and the number of registers to read:

Variable	Description	Value (hex)
DataToSend[0]	<ul> <li>High byte = Most significant byte (MSB) of register address 16#15 (21 decimal)</li> <li>Low byte = function code: 16#03 (03 decimal)</li> </ul>	16#1503
DataToSend[1]	<ul> <li>High byte = Most significant byte (MSB) of the number of registers to read: 16#00 (0 decimal)</li> <li>Low byte = Least significant byte (LSB) of register address: 16#0F (15 decimal)</li> </ul>	16#000F
DataToSend[2]	<ul> <li>CIP request instance information:</li> <li>High byte = not used: 16#00 (0 decimal)</li> <li>Low byte = Least significant byte (LSB) of the number of registers to read: 16#01 (1 decimal)</li> </ul>	16#0001

## Viewing the Response

Use a Unity Pro Animation table to display the ReceivedData variable array. Note that the ReceivedData variable array consists of the entire data buffer.

To display the Modbus TCP response, follow these steps:

Step	Action		
1	In Unity Pro, select <b>Tools</b> — <b>Project Browser</b> to open the Project Browser.		
2	In the Project Browser, select the <b>Animation Tables</b> folder, then click the right mouse button. A pop-up menu appears.		
3	Select <b>New Animation Table</b> in the pop-up menu. A new animation table and its properties dialog both open.		
4	In the Properties dialog, edit the following values:		
	Name Type in a table name. For this example: ReceivedData		
	Functional module	Accept the default <b><none></none></b> .	
	Comment (Optional) Type your comment here.		
	Number of animated characters	Type in <b>100</b> , representing the size of the data buffer in words.	

Step	Action
5	The completed <b>Properties</b> dialog looks like this:
	Properties
	Name: Functional module:
	ReceivedData
	Comment:
	-1
	Extended String Animation
	Number of animated characters 100 range: (20-300)
	OK Cancel
	Click <b>OK</b> to close the dialog.
6	In the animation table's <b>Name</b> column, type in the name of the variable assigned to the databuffer: <b>ReceivedData</b> and hit <b>Enter</b> . The animation table displays the ReceivedData variable.
7	Expand the ReceivedData variable to display its word array, where you can view the
	CIP response contained in the ReceivedData variable:
	ReceivedData
	Modification Force 7 5 7 1 5 5 1 1 5 1 1 5 1 1 5 1 1 5 1 1 5 1 1 5 1 1 5 1 1 5 1 1 5 1
	Name     Value     Type     Comment       Image: Comment     Image: Comment     Image: Comment
	ReceivedData[0] 16#0203 INT Number of bytes; Function Code
	ReceivedData[1] 16#1234 INT Value of register 5391
	<b>Note:</b> Each array entry presents 2 bytes of data in little endian format. For example, '03' in word[0] is the low byte, and '02' is the high byte.

# Section 8.4 Explicit Messaging via the Unity Pro GUI

# What Is in This Section?

This section contains the following topics:

Торіс	Page
Sending Explicit Messages to EtherNet/IP Devices	318
Sending Explicit Messages to Modbus TCP Devices	321

# Sending Explicit Messages to EtherNet/IP Devices

#### Overview

Use the **EtherNet/IP Explicit Message** window to send an explicit message from Unity Pro to an EtherNet/IP module or device on the network.

An explicit message can be sent as either a connected, or an unconnected message:

- an unconnected message requires path or addressing information identifying the destination device and, optionally, device attributes
- a connected explicit message contains both path information and a connection identifier to the target device

You can use explicit messaging to perform many different services. Not every EtherNet/IP device supports every service.

**NOTE:** Before you can perform explicit messaging, connect the DTM for the upstream communication module to the module itself. To do this, select the module node in the **DTM Browser**, then select **Edit**  $\rightarrow$ **Connect**.

The **EtherNet/IP Explicit Message** window, below, presents an example of both the configuration of an EtherNet/IP explicit message and the response. The explicit message is addressed to a remote STB NIC 2212 network interface module to obtain diagnostic information.

Address	Servio	ce	Data(hex)
IP Address 192	. 168 . 1 . 6 Numl	per 14	
Class 4	Name	e Get_Attribute_Single •	
Instance 100		Enter Path (hex) 04 24 64 30 03	
I Attribute 3	] 20	04 24 04 30 03	
	1 8	Send to Device	Messaging C Connected
		□ Repeat (500ms)	<ul> <li>Unconnected</li> </ul>
Response(hex)			
	0.00		*
A0 10 00 00 0F 00 0 00 00 00 00 00 00 00 0	0 00;		
OF 00 00 00	;		
			<u>_</u>
Status			
Status = 0(0x00), Sta	atus EtherNet/IP = 0(0x00)		

# Sending Explicit Messages

The following steps explain how to execute the EtherNet/IP explicit message, depicted above:

Step	Action			
1	In the <b>DTM Browser</b> , select the communication module that is upstream of the target device.			
2	Message.	right mouse button, and in the pop-up menu select <b>Device menu EtherNet/IP Explicit</b> e. The <b>EtherNet/IP Explicit Message</b> window opens.		
3	Configure the explicit message using the following fields:			
	IP Address	The IP address of the target device, used to identify the target of the explicit message. In the above example: <b>192.168.1.6</b> .		
	Class	The class identifier of the target device, used in the construction of the message path. An integer from 1 to 65535. In this example: <b>4</b> .		
	Instance	The class instance of the target device, used in the construction of the message path. An integer from 0 to 65535. In this example: <b>100</b> .		
	Attribute	(Optional) The specific device attribute — or property — that is the target of the explicit message, used in the construction of the message path. An integer from 0 to 65535. In this example: <b>3</b>		
		NOTE: Select the check box to enable this field.		
	NOTE: Refer to your	EtherNet/IP device user manual for class, instance and attribute values.		
	Number	The integer associated with the service to be performed by the explicit message. An integer from 1 to 127.		
		<b>NOTE:</b> If you select <b>Custom Service</b> as the named service, type in a service number. This field is read-only for all other services.		
	Name	Select the service the explicit message is intended to perform. In this example: <b>Get_Attribute_Single</b> .		
	Enter Path	(Optional) Select this check box to enable the message path field, where you can manually enter the entire path to the target device. In this example, the path is not manually entered.		
		NOTE: Displayed only when Advanced Mode is enabled.		
	Data	The data to be sent to the target device, for services that send data. In this example, leave blank.		
	Messaging	Select the type of explicit message to send: • Connected • Unconnected		
		In this example, select Unconnected.		
	Repeat 500 ms	Select this check box to re-send the explicit message every 500 ms. In this example, leave this blank.		

Step	Action
4	After your explicit message is configured, click <b>Send to Device</b> . The <b>Response</b> area displays the data sent to the configuration tool by the target device in hexadecimal format. The <b>Status</b> area displays messages indicating whether or not the explicit message has succeeded.
5	Click <b>Close</b> to close the window.

# Sending Explicit Messages to Modbus TCP Devices

#### **Overview**

Use the **Modbus Explicit Message** window to send an explicit message from Unity Pro to a Modbus TCP module or device on the network.

You can use explicit messaging to perform many different services. Not all Modbus TCP devices support all services.

**NOTE:** Before you can perform explicit messaging, connect the DTM for the upstream communication module to the module itself. To do this, select the module node in the **DTM Browser**, then select **Edit**  $\rightarrow$ **Connect**.

The **Modbus TCP Explicit Message** window, below, presents an example of both the configuration of a Modbus TCP explicit message, and the response. In this example, the explicit message is used to read 2 registers in the remote STB NIP 2212 network interface module, starting at offset 5391.

Address	Service						
IP Address 192 . 168 . 1 . 7	Number 3						
Start Address 5391	Name ReadHoldingRegisters						
Quantity 2							
Read Device Id Code Basic Device Identity	×						
Object Id 0							
Unit ID 255	Send to Device						
	💾 📃 🔲 Repeat (500ms)						
Response							
00 06 00 00 :							
	×						
Status							
Status = 0(0x0), description:ModbuxNoError							

# Sending Explicit Messages

To send an explicit message to a target Modbus TCP device:

Step	Action			
1	In the <b>DTM Browser</b> , select the communication module that is upstream of the target device.			
2	Click the right mouse button, and in the pop-up menu select <b>Device menu</b> <b>Modbus Explicit Message</b> . <b>Result</b> : The <b>Modbus Explicit Message</b> window opens.			
3	Configure the explicit message using the following fields:			
	IP Address	The IP address of the target device, used to identify the target of the explicit message. In this example: <b>192.168.1.7</b> .		
	Start Address	A component of the addressing path. In this example <b>5391</b> .		
	Quantity	A component of the addressing path. In this example 2.		
	Read Device Id Code	(read-only) The service the explicit message is intended to perform. In this example <b>Basic Device Identity</b> . Not used in this example.		
	Object Id	(read-only) Specify the object the explicit message is intended to access. In this example <b>0</b> . Not used in this example.		
	Refer to your Modbus TCP device user manual for Start Address, Quantity, Read Device Id Code, and Object Id values.			
	Unit Id	<ul> <li>The number of the device, or module, that is the target of the connection. A value of:</li> <li>255 (the default) used to access the Ethernet communication module itself</li> <li>0254 identifies the device number of the target device, behind a Modbus TCP to Modbus gateway</li> </ul>		
	Number	(read-only) The integer associated with the service to be performed by the explicit message. An integer from 0255.		
	Name	Select the service the explicit message is intended to perform. In this example <b>ReadHoldingRegisters</b>		
	Repeat 500ms	Select this check box to re-send the explicit message every 500 ms. Leave this check box de-selected.		
4	After your explicit message is configured, click <b>Send to Device</b> . The <b>Response</b> area displays any data sent to the configuration tool by the target device in hexadecimal format. The <b>Status</b> area displays messages indicating whether or not the explicit message has succeeded.			
		Click Close to close the window.		

# Chapter 9 Diagnostics

## **Overview**

This chapter describes methods of diagnosing the condition of the Ethernet communication module provided by the:

- Ethernet communication module hardware, and
- Unity Pro configuration software

# What Is in This Chapter?

This chapter contains the following sections:

Section	Торіс	Page
9.1	Module Hardware Diagnostics	324
9.2	Unity Pro Software Diagnostics	326
9.3	CPU I/O Block Diagnostics	354

# Section 9.1 Module Hardware Diagnostics

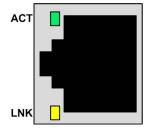
# LED Indicators for the BMX NOC 0401

# **LED Indicators**

The BMX NOC 0401 module displays the following indicators in the LED display area:



The module also displays the following LED indicators next to each Ethernet port connector:



# **LED Descriptions**

Use the LED display to diagnose the state of the module, as follows:

LED	Color	Description
RUN	Green	<ul> <li>Off: Indicates that the module is not communicating with the CPU over the backplane.</li> <li>Steady Green: Indicates that the module: <ul> <li>has just been turned on and has not yet started the LED power-up test, or</li> <li>is communicating with the CPU over the backplane</li> </ul> </li> </ul>
ERR	Red	<ul> <li>Off: The module is operating normally.</li> <li>Blinking Red: The module is not configured (or the configuration is in progress), or backplane communication has stopped.</li> <li>Steady Red: The module has detected an event.</li> </ul>
MS (Module Status)	Green/ Red	<ul> <li>Off: Power is not being supplied to the module.</li> <li>Steady Green: The module is operating normally.</li> <li>Blinking Green: The module has not been configured.</li> <li>Steady Red: The module has detected a major event.</li> <li>Blinking Red: The module has detected a recoverable event.</li> </ul>
NS (Network Status)	Green/ Red	<ul> <li>Off: Power is not being supplied to the module, or the module has not been assigned an IP address.</li> <li>Steady Green: The module has established at least one CIP connection.</li> <li>Blinking Green: The module has obtained an IP address but has not established any CIP connections.</li> <li>Steady Red: The module has detected that its IP address is a duplicate IP address.</li> <li>Blinking Red: One or more CIP connection (with the module as target) have timed out.</li> </ul>
ETH STS (Ethernet Status)	Amber	<ul> <li>Off: No power is supplied to the module.</li> <li>Steady Amber: Indicates that the module is operating normally.</li> <li>Four flashes: The module has detected a duplicate IP address.</li> <li>Five flashes: The module is waiting for a served IP address.</li> <li>Six flashes: The module is using its default IP address.</li> <li>Seven flashes: The module has detected a configuration error.</li> </ul>
		<b>NOTE:</b> If more than one diagnostic condition exists simultaneously, the Ready LED displays the shortest flash sequence.
LNK (Link)	Yellow/ Green	<ul> <li>Off: An Ethernet link has not been established.</li> <li>Yellow: A 10 Mbit Ethernet link has been established</li> <li>Green: A 100 Mbit Ethernet link has been established</li> </ul>
ACT (Activity)	Green	<ul> <li>Off: There is no receive or transmit activity.</li> <li>Flashes Green: Indicates activity.</li> </ul>

# Section 9.2 Unity Pro Software Diagnostics

### **Overview**

This section describes the diagnostic tools, provided by the Unity Pro configuration software, that you can use to monitor the condition of the Ethernet communication module.

### What Is in This Section?

This section contains the following topics:

Торіс	Page
Using the Diagnostic Window	327
Ethernet Port Diagnostics	330
Bandwidth Diagnostics	334
Email Diagnostics	337
Network Time Service Diagnostics	340
Communication Module RSTP Diagnostics	343
Local Slave / Connection Diagnostics	346
Local Slave or Connection I/O Value Diagnostics	350
Logging	352

# **Using the Diagnostic Window**

### Introduction

Use the **Diagnostic** window to display:

- LED icons (in the left pane of the window) that indicate the operating status of modules, devices and connections
- pages (in the right pane of the window) that present diagnostic data for the following:
  - the communication module
  - local slave nodes activated for the communication module
  - EtherNet/IP connections between the communication module and a remote EtherNet/IP device

**NOTE:** Before you can open the **Diagnostic** window, connect the DTM for the target communication module to the physical module itself. To do this, select the module node in the **DTM Browser**, then select **Edit**  $\rightarrow$ **Connect**.

The **Diagnostic** window looks like this:

M_NOC0401 Communication NOC01	Schneider Electric
M_NOC0401     Jocal Slave 1     [003] NIC2212_01 <eip: 192.168.1.6="">     Read Input / Write Output Data</eip:>	Ethernet Diagnostic Bandwidth Diagnostic
<ul> <li>(004) NIP2212_01 <mdb: 192.168.1.7=""></mdb:></li> <li>Request 1</li> <li>Logging</li> </ul>	Group / Parameters       Port 1         General       Interface Speed         Interface Flags       Duplex mode         Duplex mode       Negotiation Status         Manual Settings Require Reset       Local Hardware Fault         Physical Address       Input         Octets       Unicast Packets         Discards       Errors         Unicast Packets       Output         Octets       Unicast Packets         Discards       Errors         Unicast Packets       Verticast Packets         Discards       Verticast Packets         Discards       Verticast Packets         Discards       Verticast Packets         Discards       Verticast Packets         Duricast Packets       Verticast Packets         Unicast Packets       Verticast Packets         Doctets       Verticast Packets         Verticast Packets       Verticast Packets
Help	Close

## To open the **Diagnostic** window:

Step	Action
1	In the <b>DTM Browser</b> , select the communication module and click the right mouse button. A pop-up menu opens.
2	In the menu, select <b>Device menu</b> → <b>Diagnostic</b> .

### **Diagnostic LED Icons**

During the time that a communication module DTM is connected to the physical communication module, Unity Pro sends an explicit message request once per second to detect the state of the communication module and the states of the remote devices and EtherNet/IP connections linked to that module.

Unity Pro places one of the following status icons over the module, device or connection nodes in the left pane of the **Diagnostic** window to indicate its current status:

This	Indicates the following state for a			
icon	Communication module	Connection to a remote device		
•	Run state	The health bit for every EtherNet/IP connection and Modbus TCP request, to a remote device or to a sub-device or module, is set to active (1).		
•	One of the following: • unknown • started • stopped • not connected	The health bit for at least one EtherNet/IP connection or Modbus TCP request, to a remote device or to a sub-device or module, is set to inactive (0).		

# **Ethernet Port Diagnostics**

#### Introduction

Use the **Ethernet Diagnostic** page to display either dynamically generated or static data for the communication module's Ethernet port(s). The page displays five columns of data, as follows:

- one column for an module's Internal Port, and
- up to four columns for the enabled external Ethernet ports (ports 1, 2, 3 and 4

Use the **Refresh Every 500ms** checkbox to display static or dynamic data, as follows:

When the checkbox is	This page
Selected	<ul> <li>Displays data that is dynamically updated every 500 ms, and</li> <li>Increments the number at the top of the table each time data is refreshed</li> </ul>
De-selected	<ul> <li>Displays static data, and</li> <li>Does not Increment the number at the top of the table, which instead displays a constant value</li> </ul>

**NOTE:** Before you can open the **Diagnostic** window, connect the DTM for the target communication module to the physical module itself. To do this, select the module node in the **DTM Browser**, then select **Edit**  $\rightarrow$ **Connect**.

The Ethernet Diagnostic page looks like this:

4	Group / Parameters	Port 1	Port 2	Port 3	Port 4	Internal Port	^
	General						
	Interface Speed	100	100	100	100	100	
	Interface Flags	Active link	Active link	Inactive link	Inactive link	Active link	
	Duplex mode	Full duplex	Full duplex	Indetermined	Indetermined	Full duplex	
	Negotiation Status	Successfully n	Successfully n	Auto-negotiat	Auto-negotia	Successfully n	
	Manual Settings Require Reset	Interface can a	Interface can a	Interface can a	Interface ca	Interface can	
	Local Hardware Fault	No	No	No	No	No	
	Physical Address	08-80-F4-01-FC	08-80-F4-01-F	08-80-F4-01-F	08-80-F4-01-	08-80-F4-01-	
	Input						
	Octets	11620142	17820149	24183465	23657898	6687904	
	Unicast Packets	52909	72907	654879	8994	546756	
	Non-Unicast Packets	103124	33	36	37180	658112	
	Discards	0	0	3680	0	0	
	Errors	0	0	0	0	0	
	Unknown Protocols	0	0	0	0	0	
	Output						
	Octets	41311209	5467812	6454123	4131129	7181139	
	Unicast Packets	53514	67345	75698	96123	73575	
	Non-Unicast Packets	40	125	215	23546	3122	•

To open this page:

Step	Action
1	In the <b>DTM Browser</b> , select the communication module and click the right mouse button. A pop-up menu opens.
2	In the menu, select Device menu →Diagnostic.
3	In the left pane of the <b>Diagnostic</b> window, select the communication module node.
4	Click on the Ethernet Diagnostic tab to open that page.

### **Ethernet Diagnostic Parameters**

The **Ethernet Diagnostic** page displays the following parameters for each communication module port:

Parameter	Description		
General parameters:			
Interface Speed	Valid values include: 0, 10, 100 Mbits/second		
Interface Flags	Bit 0—Link Status: 0 = Inactive; 1 = Active		
	Bit 1—Duplex Mode (see below)		
	Bits 24—Negotiation Status (see below)		
	Bit 5—Manual Setting Requires Reset (see below)		
	Bit 6—Local Hardware Fault detected (see below)		
Duplex Mode	0 = half duplex; 1 = full duplex		
Negotiation Status	<ul><li>3 = successfully negotiated speed and duplex</li><li>4 = forced speed and link</li></ul>		
Manual Setting Requires Reset	0 = automatic; 1 = device requires reset		
Local Hardware Fault	0 = no event; 1 = event detected		
Physical Address	Module MAC Address		
Input parameters:			
Octets	Octets received on the interface		
Unicast Packets	Unicast packets received on the interface		
Non-Unicast Packets	Non-unicast packets received on the interface		
Discards	Inbound packets received on the interface, but discarded		
Errors	Inbound packets that contain detected errors (does not include In Discards)		
Unknown Protocols	Inbound packets with unknown protocol		
Output parameters:			
Octets	Octets received on the interface		
Unicast Packets	Unicast packets received on the interface		
Non-Unicast Packets	Non-unicast packets received on the interface		
Discards	Inbound packets received on the interface, but discarded		
Errors	Outbound packets that contain detected errors (does not include In Discards)		
Unknown Protocols	Outbound packets with unknown protocol		
Error counter paramete	rs:		
Alignment Errors	Frames that are not an integral number of octets in length		

Parameter	Description
FCS Errors	Frames received with a detected FCS checksum error
Single Collisions	Successfully transmitted frames that experienced exactly one collision
Multiple Collisions	Successfully transmitted frames that experienced more than one collision
SQE Test Errors	Number of times the SQE test error is detected
Deferred Transmissions	Frames for which first transmission attempt is delayed because the medium is busy
Late Collisions	Number of times a collision is detected later than 512 bittimes into the transmission of a packet
Excessive Collisions	Frames for which transmission is not successful due to excessive collisions
MAC Transmit Errors	Frames for which transmission is not successful due to internal MAC sublayer transmit error
Carrier Sense Errors	Times that the carrier sense condition was lost or not asserted when attempting to transmit a frame
Frame Too Long	Frames received that exceed the maximum permitted frame size
MAC Receive Errors	Frames for which reception on an interface is not successful due to an internal MAC sublayer receive detected error

# **Bandwidth Diagnostics**

### Introduction

Use the **Bandwidth Diagnostic** page to display either dynamically generated or static data for the communication module's bandwidth usage.

Use the Refresh Every 500ms checkbox to display static or dynamic data, as follows:

When the checkbox is	This page
Selected	<ul> <li>Displays data that is dynamically updated every 500 ms, and</li> <li>Increments the number at the top of the table each time data is refreshed</li> </ul>
De-selected	<ul> <li>Displays static data, and</li> <li>Does not Increment the number at the top of the table, which instead displays a constant value</li> </ul>

**NOTE:** Before you can open the **Diagnostic** window, connect the DTM for the target communication module to the physical module itself. To do this, select the module node in the **DTM Browser**, then select **Edit**  $\rightarrow$ **Connect**.

I/O - Scanner EtherNet/IP Sent EtherNet/IP Received Modbus/TCP Sent Modbus/TCP Received	0 0	Packets/s
EtherNet/IP Received Modbus/TCP Sent	0	
Modbus/TCP Sent		<b>B</b> 1 7 7
		Packets/s
Modbus/TCP Received	16	Packets/s
	16	Packets/s
I/O - Adapter		
EtherNet/IP Sent	0	Packets/s
EtherNet/IP Received	0	Packets/s
I/O - Module		
Module Capacity	12000	Packets/s
Module Utilization	0	%
Messaging - Client		
EtherNet/IP Activity	0	Packets/s
Modbus/TCP Activity	0	Packets/s
Messaging - Server		
EtherNet/IP Activity	7	Packets/s
Modbus/TCP Activity	1	Packets/s
Module		
Processor Utilization	14	%

The Bandwidth Diagnostic page looks like this:

## To open this page:

Step	Action
1	In the <b>DTM Browser</b> , select the communication module and click the right mouse button. A pop-up menu opens.
2	In the menu, select <b>Device menu</b> → <b>Diagnostic</b> . The <b>Diagnostic</b> window opens.
3	In the left pane of the <b>Diagnostic</b> window, select the communication module node.
4	Click on the Bandwidth Diagnostic tab to open that page.

### **Bandwidth Diagnostic Parameters**

The **Bandwidth Diagnostic** page displays the following parameters for the communication module:

Parameter	Description	
I/O - Scanner:		
EtherNet/IP Sent	The number of EtherNet/IP packets the module has sent, since the last reset, in packets/second.	
EtherNet/IP Received	The number of EtherNet/IP packets the module has received, since the last reset, in packets/second.	
Modbus TCP Requests	The number of Modbus TCP requests the module has sent, since the last reset, in packets/second.	
Modbus TCP Responses	The number of Modbus TCP responses the module has received, since the last reset, in packets/second.	
I/O - Adapter:		
EtherNet/IP Sent	The number of EtherNet/IP packets the module has sent—in the role of a local slave—since the last reset, in packets/second.	
EtherNet/IP Received	The number of EtherNet/IP packets the module has received—in the role of a local slave—since the last reset, in packets/second.	
I/O - Module		
Module Capacity	The maximum number of packets that the module can process, in packets per second.	
Module Utilization	The percentage of communication module capacity being used by the application.	
Messaging - Client:		
EtherNet/IP Activity	The number of I/O messages sent by the module—using the EtherNet/IP protocol—since last reset, in packets per second.	
Modbus TCP Activity	The number of I/O messages sent by the module—using the Modbus TCP protocol—since last reset, in packets per second.	
Messaging - Server:		
EtherNet/IP Activity	The number of I/O messages received by the module—using the EtherNet/IP protocol—since last reset, in packets per second.	
Modbus TCP Activity	The number of I/O messages received by the module—using the Modbus TCP protocol—since last reset, in packets per second.	
Module:		
Processor Utilization	The percent of Ethernet communication module processor capacity used by the present level of communication activity.	

# **Email Diagnostics**

### **Diagnosing SMTP Transmissions**

Use the **Email Diagnostic** page to display dynamically generated data describing the communication module's Email message transmissions.

**NOTE:** Before you can open the **Diagnostic** window, connect the DTM for the target communication module to the physical module itself. To do this, select the module node in the **DTM Browser**, then select **Edit**  $\rightarrow$ **Connect**.

Ethernet Diagnostic Ba	ndwidth Diagnostic	RSTP Diagnostic	Email Diagnostic	Network Time Service Diagnostic
Refresh Ever     Email Diagnostics	y 500ms	192		
Email Service	٥			
Remote Email Server Sta	tus 🥝			
SMTP Server IP Address	192 . 16	88.1.10		
Last Email Header Use	d			
Sender	operator1@compar	ıy.com		
Receivers	merle@mainoffice.c	com		
Subject	Pump#1 pumping m	nud, Merle, shut her dov	wn	
Number of Emails Sent:	2		Number of Errors:	0
Time Since Last Email:	280	Secs	Email Server Not Reachable	0 Times
Last Error:	16#5104		Reset Counter	

The Email Diagnostic page looks like this:

Click the  $\ensuremath{\textbf{Reset}}$   $\ensuremath{\textbf{Counter}}$  button to reset the counting statistics on this page to 0.

To open this page:

Step	Action
1	In the <b>DTM Browser</b> , select the communication module and click the right mouse button. A pop-up menu opens.
2	In the menu, select <b>Device menu</b> → <b>Diagnostic</b> . The <b>Diagnostic</b> window opens.
3	In the left pane of the <b>Diagnostic</b> window, select the communication module node.
4	Click on the Email Diagnostic tab to open that page.

## **Email diagnostic Parameters**

Email service parameters include the following:

Parameter	Description
Refresh Every 500ms	Select this to dynamically update this page every 500ms. The number of times this page has been refreshed appears immediately to the right (in this example, 192.
Email Service	<ul> <li>The status of this service in the Ethernet communication module:</li> <li>green = operational (OK)</li> <li>orange = not operational (NOK)</li> </ul>
Remote Email Server Status	<ul> <li>The connection status between Ethernet communication module and the SMTP server:</li> <li>green = operational (OK)</li> <li>red = not operational (NOK)</li> </ul>
	<b>NOTE:</b> Status is checked at start-up and at least every 30 minutes after start-up.
SMTP Server IP Address	IP address of the SMTP server
Sender	The three header fields of the last Email message sent.
Receivers	
Subject	
Number of Emails Sent	Total number of emails sent and successfully acknowledged by the SMTP server.
Time Since Last Email	Counts the number of seconds since the last email was successfully sent.
Last Error	Hexadecimal code describing the reason for the last unsuccessful Email transmission ( <i>see page 437</i> ). The value "0" indicates no unsuccessful transmissions.
Time Since Last Email	Counts the number of seconds since the last email was successfully sent.
Number of Errors	<ul> <li>Total number of emails that either:</li> <li>could not be sent</li> <li>were sent but were not successfully acknowledged by the SMTP server</li> </ul>
Email Service Not Reachable	Number of times the SMTP server could not be reached. (Link checked every 30 minutes.)

# **Network Time Service Diagnostics**

#### **Diagnosing the Network Time Service**

Use the **Network Time Service Diagnostic** page to display dynamically generated data describing the operation of the network time protocol (NTP) service that you configured in the Network Time Service page (*see page 103*) in Unity Pro.

**NOTE:** Before you can open the **Diagnostic** window, connect the DTM for the target communication module to the physical module itself. To do this, select the module node in the **DTM Browser**, then select **Edit**  $\rightarrow$ **Connect**.

The Network Time Service Diagnostic page looks like this:

Ethernet Diagnostic	Bandwidth Diagnostic	RSTP Diagnostic	Email Diagnostic	Network Time Service Diagnostic			
🔽 Refre	sh Every500ms	785					
Status —							
Network Time Se	Network Time Service Seconds						
Network Time Se	Network Time Server Status 🥥						
Current Date:	21-Oct-2011 Cu	rrent Time: 14:27:	53				
DST Status:	ON Qu	ality: 0	Microseconds	s/Second			
Requests:	0 Re	sponses: 0					
Errors:	0 Las	st Error: 16#0	Reset 0	Counter			
Server Informatio	n						
Primary NTP Se	rver IP: 192 . 168 .	. 1 . 1 🥥					
Secondary NTP	Server IP: 192 . 168 .	. 1 . 2	Polling Peri	od: 20 Seconds			
Daylight Saving S	ettings						
DST Start: M	Month: March	Day of Week: S	unday Wee	≥k#: 1			
DST End:	Month: March	Day of Week: S	unday Wee	sk#: 1			
Time Zone:	(GMT) Greenwic	h Mean Time (Dublir	Edinburgh Lisbon Lo	ndon)			
Offset:	360 N	/lins Auto Adjust	Clock for Daylight Sav	ings: Enabled			

Click the **Reset Counter** button to reset the counting statistics on this page to 0.

To open this page:

Step	Action
1	In the <b>DTM Browser</b> , select the communication module and click the right mouse button. A pop-up menu opens.
2	In the menu, select <b>Device menu</b> → <b>Diagnostic</b> . The <b>Diagnostic</b> window opens.
3	In the left pane of the <b>Diagnostic</b> window, select the communication module node.
4	Click on the NTP Diagnostic tab to open that page.

### **Network Time Service Diagnostic Parameters**

Time synchronization service parameters are in the table:

Parameter	Description	
Refresh Every 500ms	Select this to dynamically update this page every 500ms. The number of times this page has been refreshed appears immediate to the right (in this example, 785).	
Network Time Service	<ul> <li>Operational status of the service in the module:</li> <li>green = operational</li> <li>orange = not operational</li> </ul>	
Network Time Server Status	Communication status of the NTP server: • green = the NTP server is reachable • red = the NTP server is not reachable	
Last Update	Elapsed time, in seconds, since the most recent NTP server update.	
Current Date	System date	
Current Time	System time in hh:mm:ss format	
DST Status	<ul> <li>The actual working status of the automatic daylight savings service:</li> <li>ON = automatic adjustment of daylight savings is enabled and the current date and time reflect the daylight savings time adjustment</li> <li>OFF = automatic adjustment of daylight savings is disabled; or automatic adjustment of daylight savings is enabled, but the current date and time may not reflect the daylight savings time adjustment</li> </ul>	
Quality	The correction, in seconds, applied to the local counter at every NTP server update.Numbers greater than 0 indicate increasingly excessive traffic condition or NTP server overload.	
Requests	Total number of client requests sent to the NTP server	
Responses	Total number of server responses sent from the NTP server	
Errors	Total number of unanswered NTP requests	

Parameter	Description		
Last Error	<ul> <li>Last detected error code received from the NTP client:</li> <li>0: good NTP configuration</li> <li>1: late NTP server response (can be caused by excessive network traffic or server overload)</li> <li>2: NTP not configured</li> <li>3: invalid NTP parameter setting</li> <li>4: NTP component disabled</li> <li>7: unrecoverable NTP transmission</li> <li>9: invalid NTP server IP address</li> <li>15: invalid syntax in the custom time zone rules file</li> </ul>		
Primary / Secondary NTP Server IP	The IP address of the primary and the secondary NTP server <b>NOTE:</b> A green LED to the right of the primary or secondary NTP server IP address identifies the currently active server.		
Auto Adjust Clock for Daylight Savings	The configuration setting of the daylight savings adjustment service: • enabled • disabled		
DST Start / DST End	Specifies the day that daylight savings time begins and ends:		
	Month	The month daylight savings time starts or ends	
	Day of Week	The day of the week daylight savings time starts or ends	
	Week#	The occurrence of the specified day within the specified month.	
Time Zone	Time zone plus or minus Universal Time, Coordinated (UTC)		
Offset	The time, in minutes, to be combined with the selected Time Zone selection to produce the system time.		
Polling Period	The frequency the NTP client requests time updates from the NTF server		

# **Communication Module RSTP Diagnostics**

### Introduction

Use the **RSTP Diagnostic** page to display either dynamically generated or static data for a BMX NOC 0401 (M340) communication module's RSTP service.

Use the Refresh Every 500ms checkbox to display static or dynamic data, as follows:

When the checkbox is	This page
Selected	<ul> <li>Displays data that is dynamically updated every 500 ms, and</li> <li>Increments the number at the top of the table each time data is refreshed</li> </ul>
De-selected	<ul> <li>Displays static data, and</li> <li>Does not Increment the number at the top of the table, which instead displays a constant value</li> </ul>

**NOTE:** Before you can open the **Diagnostic** window, connect the DTM for the target communication module to the physical module. To do this, select the module node in the **DTM Browser**, then select **Edit**  $\rightarrow$ **Connect**.

Group / Parameter	Value	Unit	<u> </u>
Bridge RSTP Diagnostic			
Bridge ID	0		
MAC Address	00-00-00-00-00		
Designated Root ID	0		
Root Path Cost	0		
Default Hello Time	2	sec	
Learned Hello Time	0	sec	
Configured Max Age	40	sec	
Learned Max Age	0	sec	
Total Topology Changes	0		
Port 3 RSTP Statistics			
Status	Disabled		
Role	Unknown (0)		
Cost	0		
 STP Packets	0		
Port 3 RSTP Statistics			
Status	Disabled		
Role	Unknown (0)		
Cost	0		-

The RSTP Diagnostic page looks like this:

To open this page:

Step	Action
1	In the <b>DTM Browser</b> , select the communication module and click the right mouse button. A pop-up menu opens.
2	In the menu, select Device menu →Diagnostic.
3	In the left pane of the <b>Diagnostic</b> window, select the communication module node.
4	Click on the <b>RSTP Diagnostic</b> tab to open that page.

### **RSTP Diagnostic Parameters**

The **RSTP Diagnostic** page displays the following parameters for each communication module port:

Parameter	Description				
Bridge RSTP Diagnosti	Bridge RSTP Diagnostic:				
Bridge ID	<ul> <li>An 8-byte bridge identification field is comprised of a 2 sub-fields:</li> <li>Bridge Priority: a 2-byte value from 0 to 65535—with a default of 32768—assigned to the module's embedded Ethernet switch</li> <li>MAC Address (see below)</li> </ul>				
MAC Address	The Media Access Control address of a device, found on the front of the module.				
Designated Root ID	The Bridge ID of the root switch.				
Root Path Cost	The aggregate cost of port costs from this switch back to the root switch.				
Default Hello Time	The interval at which Configuration BPDU messages will be transmitted during a network convergence. For RSTP this is a fixed value of 2 seconds.				
Learned Hello Time	The current Hello Time value learned from the root switch.				
Configured Max Age	The value that other switches use for MaxAge when this switch is acting as the root. Valid range: 6 to 40				
Learned Max Age	The maximum age learned from the root switch. This is the actual value currently used by this switch.				
Total Topology Changes	The total number of topology changes detected by this switch since the management entity was last reset or initialized.				
Ports 3 and 4 RSTP Statistics:					
Status	The port's current state as defined by RSTP Protocol. This state controls the action the port takes when it receives a frame. Possible values are: disabled, discarding, learning, forwarding.				
Role:	The port's current role per RSTP protocol. Possible values are: root port, designated port, alternate port, backup port, disabled port.				
Cost	The logical cost of this port as a path to the root switch. If this port i configured for AUTO then the cost is determined based on the connection speed of the port.				
STP Packets	A value in this field indicates that a device on the network has the STP protocol enabled.				
	<ul> <li>NOTE:</li> <li>Other devices, with STP enabled, can severely affect the network convergence times. Schneider Electric recommends the STP protocol (but not the RSTP protocol) be disabled on every network device capable of supporting it.</li> <li>The communication module does not support the STP protocol. The module's embedded switch ignores ignore STP packets.</li> </ul>				

# Local Slave / Connection Diagnostics

### Introduction

The Local Slave Diagnostic page and the EIP Connection Diagnostic page present common information. Use the:

- Local Slave Diagnostic page to display I/O status and production/consumption information for a selected local slave
- EIP Connection Diagnostic page to display I/O status and production/consumption information for a connection of a remote EtherNet/IP device

Use the Refresh Every 500ms checkbox to display static or dynamic data, as follows:

When the checkbox is	This page
Selected	<ul> <li>Displays data that is dynamically updated every 500 ms, and</li> <li>Increments the number at the top of the table each time data is refreshed</li> </ul>
De-selected	<ul> <li>Displays static data, and</li> <li>Does not Increment the number at the top of the table, which instead displays a constant value</li> </ul>

**NOTE:** Before you can open the **Diagnostic** window, connect the communication module or remote device DTM to the physical module or device. To do this, select the appropriate node in the **DTM Browser**, then select **Edit**  $\rightarrow$ **Connect**.

The following figure presents an example of the **EIP Connection Diagnostic** page. (Except for the title, the **Local Slave Diagnostic** page is the same.)

Group / Parameter	Value	Unit		Refresh Every 500ms
🖃 🦲 Status				,
🖳 🛱 Input	68			
🛱 Output	68			
🦾 🛺 General	208			
Extended	1			
Counter				
- B Frame Error	0			
Time-Out	0			
Refused	0			
Production	0			
Consumption	0			
Production Byte	0			
Consumption Byte	0			
骨 Theoretical Packet/s	66			
🔚 💾 Real Packet/s	0			
🖃 🦲 Diagnostic				
Production Connection ID	0			
Consumption Connection ID	0			
🚰 O -> T API	0		-	
cription				
		-		

To open this page:

Step	Action
1	In the <b>DTM Browser</b> , select the communication module and click the right mouse button. A pop-up menu opens.
2	In the menu, select <b>Device menu</b> → <b>Diagnostic</b> .
3	<ul> <li>In the left pane of the <b>Diagnostic</b> window, click on one of the following:</li> <li>for local slave diagnostics, select the communication module node</li> <li>for remote device connection diagnostics, select a remote device connection</li> </ul>
4	Depending upon you selection in step 3, above, click on either the <b>Local Slave Diagnostic</b> tab or the <b>EIP Connection Diagnostic</b> tab to open that page.

# **Diagnostic Parameters**

This page displays the following diagnostic parameters for the selected local slave or connection:

Parameter	Description				
Status (see page 349	Status (see page 349):				
Input	An integer representing input status.				
Output	An integer representing output status.				
General	An integer representing basic connection status.				
Extended	An integer representing extended connection status.				
Counter:					
Frame Error	Increments each time a frame is not sent by missing resources or is impossible to send.				
Time-Out	Increments each time a connection times out.				
Refused	Increments when connection is refused by the remote station.				
Production	Increments each time a message is produced.				
Consumption	Increments each time a message is consumed.				
Production Byte	Total of produced messages, in bytes, since the communication module was last reset.				
Consumption Byte	Total of consumed messages, in bytes, since the communication module wa last reset.				
Theoretical Packets per second	Packets per second calculated sing current configuration value.				
Real Packets per second	Actual number of packets per second generated by this connection.				
Diagnostic:					
Production Connection ID	The connection ID.				
Consumption Connection ID	The connection ID.				
0 -> T API	Accepted packet interval (API) of the output connection.				
T -> O API	Accepted packet interval (API) of the input connection.				
0 -> T RPI	Requested packet interval (RPI) of the output connection.				
T -> 0 RPI	Requested packet interval (RPI) of the input connection.				
Socket Diagnostics:	Socket Diagnostics:				
Socket ID	Internal Identification of the socket.				
Remote IP Address	IP address of the remote station, for this connection.				
Remote Port	Port number of the remote station, for this connection.				
Local IP Address	IP address of the communication module, for this connection.				
Local Port	Port number of the communication module, for this connection.				

## **Connection Status Codes**

The Input and Output Status diagnostic parameters *(see page 348)*, in the preceding table, can present the following values:

Input/Output Status (dec)	Description
0	ОК
33	Time-out
53	IDLE
54	Connection established
58	Not connected (TCP)
65	Not connected (CIP)
68	Connection establishing
70	Not connected (EPIC)
77	Scanner stopped

# Local Slave or Connection I/O Value Diagnostics

#### Introduction

Use the **I/O Values** page to display both the input data image and output data image for the selected local slave or connection.

Use the Refresh Every 500ms checkbox to display static or dynamic data, as follows:

When the checkbox is	This page
Selected	<ul> <li>Displays data that is dynamically updated every 500 ms, and</li> <li>Increments the number at the top of the table each time data is refreshed</li> </ul>
De-selected	<ul> <li>Displays static data, and</li> <li>Does not Increment the number at the top of the table, which instead displays a constant value</li> </ul>

**NOTE:** Before you can open the **Diagnostic** window, connect the communication module or remote device DTM to the physical module or device. To do this, select the appropriate node in the **DTM Browser**, then select **Edit**  $\rightarrow$ **Connect**.

To open this page:

Step	Action
1	In the <b>DTM Browser</b> , select the communication module and click the right mouse button. A pop-up menu opens.
2	In the menu, select Device menu ->Diagnostic.
3	<ul> <li>In the left pane of the <b>Diagnostic</b> window, click on one of the following:</li> <li>the communication module node, or</li> <li>a connection node</li> </ul>
4	Click on the I/O Values tab to open that page.

EIP Connection Diagnostic	I/O Values				
Refresh every 500 ms					
Refresh every 500 ms					
00 00 00 00 00 00	;	<u>^</u>	Length	6	bytes
			Status	68	
		-			
Output					
Output	;	<u>^</u>	Length	6	bytes
	,		Lengui	1.	bytoo
			Status	68	
		-			

The following example depicts the I/O Values page for a remote device connection:

### Local Slave / Connection I/O Values

This page displays the following parameters for either a local slave or a remote device connection input and output values:

Parameter	Description
Input/Output data display	A display of the local slave or remote device input or output data image.
Length	The number of bytes in the input or output data image.
Status	The Scanner Diagnostic object's scanner status (see page 265), with respect to the read of the input or output data image.

# Logging

### Description

Unity Pro maintains a log of events for:

- the Unity Pro embedded FDT container
- each Ethernet communication module DTM, and
- each EtherNet/IP remote device DTM

Events relating to the Unity Pro FDT container are displayed in the **FDT log event** page of the **Output Window**.

Events relating to a communication module or remote EtherNet/IP device are displayed:

- in configuration mode: in the **Device Editor**, by selecting the **Logging** node in the left pane
- in diagnostic mode: in the **Diagnostics** window, by selecting the **Logging** node in the left pane

The following is a sample of the events log displayed in the **Diagnostics** window:

Date / Time	Log Level	Message	Detail Message
2009-09-25 08:57:23	Error	Communication error occurred.	Unknown status!
2009-09-25 08:56:45	Information	The FDT Frame Application has	
2009-09-25 08:55:14	Information	IP Address of slave device succe	192.168.1.1 -> 192
2009-09-25 08:52:56	Information	The FDT Frame Application has	
2009-09-25 08:52:17	Information	DTM is offline.	
2009-09-25 08:50:44	Information	DTM is offline.	
2009-09-25 08:49:12	Information	The FDT Frame Application has	
2009-09-25 08:48:52	Information	The FDT Frame Application has	
2009-09-25 08:46:56	Information	The FDT Frame Application has	
2009-09-25 08:45:17	Warning	The persisted network interface c	
2009-09-25 08:43:44	Information	DTM is offline.	
2009-09-25 08:42:12	Information	The FDT Frame Application has	
2009-09-25 08:40:52	Information	The FDT Frame Application has	
•			<u> </u>

### Logging Attributes

The **Logging** window displays the result of an operation or function performed by Unity Pro. Each log entry includes the following attributes:

Attribute	Description			
Date/Time	The time the event occurred, displayed in the format: yyyy-mmdd hh:mm:ss			
Log Level	The level of event importance. Values include:			
	Information	A successfully completed operation.		
	Warning	An operation that Unity Pro completed, but which may lead to a subsequent detected error.		
	Error	An operation that Unity Pro was unable to complete.		
Message	A brief description of the core meaning of the event.			
Detail Message	A more detailed description of the event, which may include parameter names, location paths, etc.			

# Section 9.3 CPU I/O Block Diagnostics

#### **Overview**

The CPU's I/O Block contains diagnostic information relating to the operation of the BMX NOC 0401 Ethernet communication module. This information can be accessed in Unity Pro at runtime. This section describes the available I/O Block data, and how to access it.

### What Is in This Section?

This section contains the following topics:

Торіс	Page
Accessing the Unity Pro Diagnostic Tools	355
Communication Channel Diagnostics in Unity Pro	358
Communication Module Diagnostics in Unity Pro	361

# Accessing the Unity Pro Diagnostic Tools

### Overview

The Unity Pro software provides diagnostic tools that let you view the:

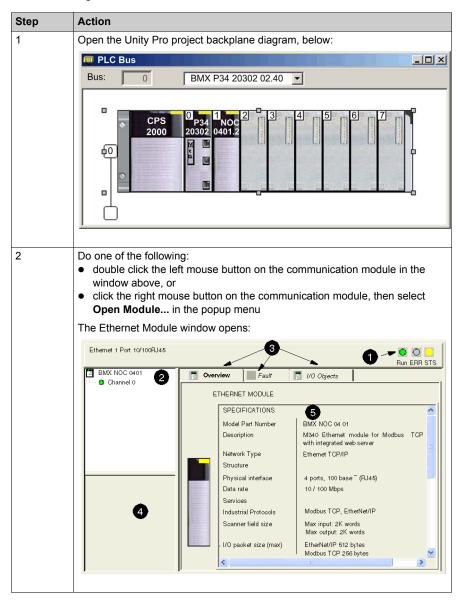
- communication module status
- communication module's:
  - detected faults
  - I/O objects
- communication channel's:
  - MAC Address
  - IP Address settings
  - detected faults

These Unity Pro diagnostic tools are available in the BMX NOC 0401 **Module Properties** window, only when Unity Pro is operating online.

**NOTE:** If the module and software are disconnected, use the Master DTM diagnostic screen in Unity Pro to check the I/O status.

### **Accessing Unity Pro Diagnostic Tools**

To access diagnostic tools for the Ethernet communication module:



Step	Action		
3	Navigate the Ethernet Module window using the following features:		
	1 Module status icons	These three indicators display the module's status in online mode.	
	2 Channel area	<ul><li>Select a node to display parameters for either:</li><li>the communication module, or</li><li>a communication channel</li></ul>	
	3 Page tabs	Select a page to display module or channel properties: • for the communication module: • Overview • Fault • I/O Objects • for a communication channel: • Configuration • Debug • Fault	
	4 General parameters	<ul> <li>View communication channel parameters:</li> <li>Function displays the configured communication function and is read-only.</li> <li>Task displays the task (configured MAST) and is read-only.</li> </ul>	
	5 Mode parameters	Displays parameters for the mode you select by opening a page.	

# **Communication Channel Diagnostics in Unity Pro**

#### Overview

Select a communication channel in the **Channel area** to access the:

- Configuration page, where you can:
  - edit the EtherNet/IP Module name
  - edit input and output data size and location settings
  - launch the Unity Pro EtherNet/IP configuration tool

Refer to the description of the **Configuration** page (see page 36) for more information.

- **Debug** page, which displays the communication module's:
  - MAC Address
  - IP Address settings
- Fault page, which displays active detected faults for the communication channel

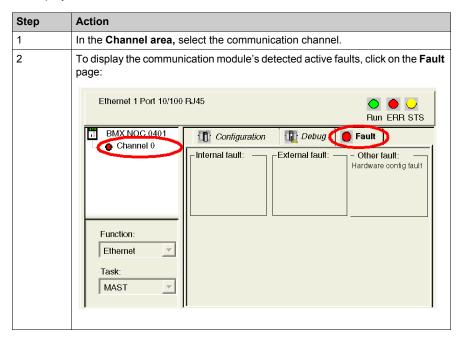
### MAC Address

To display the MAC Address of the communication module:

Step	Action
1	In the <b>Channel area</b> , select the communication channel. The following pages are displayed: • Configuration • Debug • Default
2	To display the communication module's MAC Address and IP Address settings, click on the <b>Debug</b> page:
	Ethernet 1 Port 10/100 RJ45
	BMX NOC 0401 Configuration Debug Fault
	Channel 0 Address Information
	MAC Address 12.34.56.78.90.12
	IP Address 192.168.001.004
	Subnetwork mask 255.255.255.000
	Gateway address 000.000.000
	Function: Ethernet Task: MAST

### **Channel Detected Faults**

To display the active faults detected on the communication channel:



**NOTE:** You can also access the channel detected error bit (CH\_ERROR) by using the Unity Pro **Animation Table** to display the **%Ir.m.ch.ERR** object.

# **Communication Module Diagnostics in Unity Pro**

## **Overview**

Use the Ethernet Module window in Unity Pro to diagnose the BMX NOC 0401 Ethernet communication module. In this window, you can access:

- three icons that reflect the current status of selected LEDs
- the **Overview** page, where you can view a description of the module
- Fault page, which displays detected active faults for the communication module
- I/O Objects page, where you can view and manage I/O objects for the module

## **Module Status Icons**

The Ethernet Module window displays three icons that reflect the current status of the following LEDs:

- Run
- ERR
- STS

Refer to the description of LED indicators (see page 324) for information on how to use these icons.

# **Accessing Module Detected Faults**

To display the detected active faults on the communication module:

Step	Action
1	In the <b>Channel area</b> , select the communication module. The following pages are displayed: • Overview • Fault • I/O Objects
2	To display the communication module's active detected faults, click on the Fault page:
	Ethernet 1 Port 10/100 RJ45
	BMX NOC 0401       Image: Overview       Fault       I/O Objects         Internal fault:       External fault:       Other fault:       - Faulty channel(s)         Function:       Image: Task:       Image: Task:       Image: Task:       Image: Task:         MAST       Image: Task:       Image: Task:       Image: Task:       Image: Task:       Image: Task:

**NOTE:** You can also access the module detected error bit by using the Unity Pro **Animation Table** to display the **%Ir.m.MOD.ERR** object.

### Managing I/O Objects

Use the I/O Objects page to view module I/O objects, and to manage the association of these objects with variables.

Open the **I/O Objects** page by selecting the **I/O Objects tab**, after the communication module has been selected in the **Channel area**:

Ethernet 1 Port 10/100	) RJ45	O O Run ERR STS
El BMX NOC 101	Overview       Fault       VO Objects         I/O Variable Creation       Prefix for name:         Type:       Create         Comment:       Create         Conment:       Create         VO Objects       Channel:         VO Chiguration:       %KW         System:       %MW         Status:       %MW         Unselect all         Parameter:       %MW         %MW       %MF         Command:       %MW         %MW       %IF         Update       Update Grid	Address Name Type Comment
	Filter on usage	

# NOTE:

- The BMX NOC 0401 communication module supports only Channel, System, and Status I/O Objects. Not every bit is used.
- Refer to the Unity Pro help for instructions on how to use the **I/O Objects** page.

# Reading I/O Objects

Use a READ\_STS function block in Unity Pro to update each of the following types of data:

- module data
- channel data

# Updating module data:

To display module information, follow these steps:

Step	Action		
1	Configure the READ_STS function block, as follows:		
		READ_STS	
	%CHr.m.MOD—	СН	
	Where:		
	r = rack or station n	umber	
	m = module or slot	number	
	MOD = a constant i	ndicating module data	
2		dated by the READ_STS function block, enter the corresponding the Unity Pro Animation table, or use them in your program logic:	
	Object	Description	
	%lr.m.MOD.ERR	Module detected error bit %Ir.m.MOD.ERR is implicitly updated based on %Ir.m.0.ERR	
	%MWr.m.MOD.0	Exchange Status: Bit 0: reading of module status in progress	
	%MWr.m.MOD.1	Exchange Report: Bit 0: detected error while reading module status	
	%MWr.m.MOD.2	Bit 0: internal fault detected	
		Bit 1: operational fault detected	
		Bit 2: not used	
		Bit 3: self test	
		Bit 4: not used	
		Bit 5: configuration fault detected	
		Bit 6: missing module or off	
		Bit 7: not used	

# Updating channel data:

To display channel information, follow these steps:

Step	Action
1	Configure the READ_STS function block, as follows:
	READ_STS
	%CHr.m.ch— CH
	Where:
	r = rack, or station, number
	m = module, or slot, number
	ch = channel number—set to 0 for ETC transactions

Step	Action		
2	To view the data updated by the READ_STS function block, enter the corresponding direct addresses in the Unity Pro Animation table, or use them in your program logic:		
	Object	Description	Standard Symbol
	%Ir.m.ch.ERR	Channel detected error bit	CH_ERROR
	%lr.m.ch.0	Status of Ethernet services:	—
		Bit 0: EIP Scanner (0 = OK, 1 = NOK)	—
		Bit 1: EIP Adapter (0 = OK, 1 = NOK)	—
		Bit 2: EIP Client (0 = OK, 1 = NOK)	—
		Bit 3: EIP Server (0 = OK, 1 = NOK)	—
		Bit 4: Modbus scanner (0 = OK, 1 = NOK)	—
		Bit 5: Modbus TCP Client (0 = OK, 1 = NOK)	—
		Bit 6: Modbus TCP Server (0 = OK, 1 = NOK)	—
		Bit 7: FDR Server (0 = OK, 1 = NOK)	—
		Bit 8: RSTP (0 = OK, 1 = NOK)	—
		Bit 9–Bit 15: reserved	—
	%MWr.m.ch.0	Exchange Status:	EXCH_STS
		Bit 0: reading of status words of the channel in progress	STS_IN_PROG
		Bit 1: command write in progress	CMD_IN_PROG
	%MWr.m.ch.1	Exchange Report:	EXCH_RPT
		Bit 0: detected error while reading channel status	STS_ERR
		Bit 1: detected error while writing a command to the channel	CMD_ERR

Step	Action		
2	%MWr.m.ch.2	Standard channel status (low byte):	_
cont'd		Bits 03: reserved (0)	_
		Bit 4: internal fault detected	_
		Bit 5: not used (0)	—
		Bit 6: X-Bus communication fault detected	—
		Bit 7: application fault detected (conf fault detected)	—
		High byte:	—
		Bits 07: reserved (0)	—
	%MWr.m.ch.3	Ethernet Port Global Status:	ETH_PORT_STATU S
		Bit 0: detected configuration error	—
		Bit 1: the Ethernet interface is disabled	—
		Bit 2: duplicate IP address detected	—
		Bit 3: configuration mismatch	—
		Bit 4: reserved	—
		Bit 5: the module is in the process of obtaining an IP address	—
		Bits 615: reserved	—
	%MWr.m.ch.4	IP address (IP_ADDR):	IP_ADDR
		<ul> <li>During normal operation, the double word %MDr.m.c.4 contains the IP address configured or served to the module.</li> </ul>	_
		<ul> <li>In No Configuration state, the double word %MDr.m.c.4 contains the default IP address of the module.</li> </ul>	—
		• In Configuration Error detected state, the double word %MDr.m.c.4 contains the default IP address of the module.	-
			• When a duplicate IP address is detected, the double word %MDr.m.c.4 contains the served or configured duplicate IP address.
		• When the module is waiting for a BOOTP response, the double word %MDr.m.c.4 contains the IP address 0.0.0.0.	_

# **Chapter 10** Replacing the Ethernet Communication Module

# **Replacing the Ethernet Communication Module**

## Overview

Replacing The module involves removing the old module and mounting a new one in its place

#### When to Replace

You can replace the communication module at any time using another module with compatible firmware. A module can be replaced when power to the module is either:

- off (cold swap), or
- on (hot swap)

The replacement module obtains its operating parameters over the backplane connection from the CPU. The transfer occurs either immediately (hot swap) or when power is next cycled to the device (cold swap).

**NOTE:** Operating parameters, that were added to the configuration using explicit messaging "SET" commands, are not included in the parameters that the CPU sends to a replacement module.

To install the replacement module, follow the instructions in the module mounting procedure *(see page 21)*.

# Chapter 11 Embedded Web Pages

## **Overview**

This chapter describes the embedded web pages for the BMX NOC 0401 Ethernet communication module.

The communication module includes a Hypertext Transfer Protocol (HTTP) server. The server transmits web pages for the purpose of monitoring, diagnosing, and controlling remote access to the communication module. The server provides easy access to the communication module from standard internet browsers, including—but not limited to—Internet Explorer.

# What Is in This Chapter?

This chapter contains the following sections:

Section	Торіс	Page
11.1	Accessing the Embedded Web Server	372
11.2	Monitoring the Unity Pro Application	380
11.3	Diagnostics	393

# Section 11.1 Accessing the Embedded Web Server

#### Introduction

This section introduces the BMX NOC 0401 communication module's embedded web server, and describes how to access—and to control access to—the web pages.

#### What Is in This Section?

This section contains the following topics:

Торіс	Page
Introducing the Embedded Web Pages	373
Accessing the Home Page	
Using and Editing a Username and Passwords	375
Configuring Port Mirroring	

# Introducing the Embedded Web Pages

## Introduction

Use the BMX NOC 0401 Ethernet communication module's embedded web server pages to:

- display real-time diagnostic data for both the module and other networked devices
- read the values of—and write values to—Unity Pro application variables
- manage and control access to the embedded web pages by assigning separate passwords for:
  - viewing the diagnostic web pages, and
  - using the Data Editor to write values to Unity Pro application variables

## Requirements

The embedded web server presents module data in the form or standard HTML web pages. Access the embedded web pages using Internet Explorer version 4.0 or higher, running the Java Runtime Environment (JRE) version 1.6 or higher.

# Accessing the Home Page

### On First Use

Before you begin to use the BMX NOC 0401 communication module's embedded web pages, you need to:

- · navigate to the web server
- access web page content by inputting the default username and password (see page 375) combination
- change passwords (see page 376) that are required for:
  - accessing web pages, and
  - writing data values using the Data Editor

## Navigating to the Web Server

To access the embedded web server, open an Internet browser, then enter the IP address *(see page 67)* of the Ethernet communication module in the format: *http://IP address*, then click **Enter**.

**NOTE:** If a DNS name has been assigned to the module, the DNS name can be used instead of the IP address.

The web server opens, displaying the Home page:



Use the **Home** page as the point of entry to the communication module's embedded web server. From here, you can navigate to every other web page.

# Using and Editing a Username and Passwords

#### Inputting the Username and Web Page Access Password

A username and password are required to access web page content and edit application data. All username and password settings are case sensitive.

The embedded web pages support the use of a single, editable username for both web page access and data editing. The factory-default username setting is **USER**.

The embedded web pages require two different passwords, as follows:

- an HTTP access password, which grants read-only access to web page content
- a data editor write password, which permits the editing of data values using the Data Editor

Each password can be edited. The factory default setting for each password is USER.

To input a username and password combination

Step	Description
1	After navigating to the embedded web server <i>(see page 374)</i> , select one of the main menu selections (for example, <b>Setup</b> ).
2	Select a page name from the list of pages on the left side of the page (for example, <b>Security</b> ). The following dialog opens:
	Connect to 192.168.1.4  Connect to 192.168.1.4  The server 192.168.1.4 at Schneider Web requires a username and password.  Warning: This server is requesting that your username and password be sent in an insecure manner (basic authentication without a secure connection).  User name:  USER Password:  CK Cancel
3	Type in the required <b>Username</b> and <b>Password</b> combination, then click <b>OK</b> . <b>NOTE:</b> In the above example, the settings for both the Username and Password remain set to the default setting of USER.

# Editing the Username and Passwords

The single username and both passwords can be edited in the **Security** web page. To edit username and passwords, follow these steps:

Step	Description
1	Navigate to and open the web server, <i>(see page 374)</i> using the IP address of the communication module. The <b>Home</b> page opens.
2	From the <b>Home</b> page, click on the <b>Setup</b> main menu item. If required, input the username and web page password ( <i>see page 375</i> ). The <b>Setup</b> page opens:
	BIX NOC 0401       URL         Home       Documentation       URL         Monitoring       Control       Diagnostics       Maintenance       Setup         Security       Security       Port Mirroring       Vertical of the security       Vertical of the security         Port Mirroring       Diagnostics       Maintenance       Setup         Copyright © 1998-2010, Schneider Automation SAS. All Rights Reserved.       Copyright © 1998-2010, Schneider Automation SAS. All Rights Reserved.
	, , , , ,

Step	Description		
3	On the left side of t and web page acc The <b>Security</b> page	,	
	Monitoring C	control Diagnostics Maintenance Setup	
	SECURITY		
		HTTP access rights	
	Use	ername:	
	Nev	v password:	
	Con	firm password:	
		Save User	
		Data Editor Write Password	
	Data	Editor write password:	
	Nev	v write password:	
	Con	firm write password:	
		Change Write Password	
	Copyright © 200	0-2008, Schneider Automation SAS. All Rights Reserved.	
	L		
4	-	rname and password combination used for web page access, in the <b>nts</b> section of the page, enter values for the following fields:	
	Username:	<ul> <li>To change the username: type in a new username</li> <li>To retain the current username (for example, if you are changing only the password): type in the current username</li> </ul>	
	New password:	<ul> <li>To change the password: type in a new password</li> <li>To keep the current password (for example, if you are changing only the username): type in the current password</li> </ul>	
	Confirm password:	Type in the same password entered in the <b>New password</b> field, above.	
5	Click the Save User button.		
6		sword used for writing data values in the <b>Data Editor</b> , in the <b>Password</b> section of the page, enter values for the following fields:	
	Data Editor write password:	Type in the current password that is required to write data using the <b>Data Editor</b> .	
	New write password:	Type in the new <b>Data Editor</b> password.	
	Confirm write password:	Type in the same password entered in the <b>New write password</b> field, above.	
7	Click the Change	Write Password button.	

# **Configuring Port Mirroring**

#### **Enabling Port Mirroring in Unity Pro**

You can use the port mirroring service to duplicate the traffic entering and exiting any one of the four Ethernet ports (the source port) onto another one of the ports (the destination port), for the purpose of diagnosing the source port.

#### NOTE:

- Verify that the port mirroring service is enabled in Unity Pro (see page 75) before configuring it in the web pages.
- You can designate only non-RSTP enabled ports as the destination port.
- The port mirroring configuration settings are transient, and are cleared when you reboot the Ethernet communication module.

#### **Configuring Port Mirroring in the Web Pages**

To configure port mirroring, follow these steps:

Step	Description
1	In Unity Pro, enable the port mirroring service (see page 75) to globally enable port mirroring.
2	Navigate to and open the web server, <i>(see page 374)</i> using the IP address of the communication module. The <b>Home</b> page opens.
3 From the <b>Home</b> page, click on the <b>Setup</b> main menu item. If required, username and web page password (see page 375). The <b>Setup</b> page of	
	BMX NOC 0401 Home       URL         Monitoring       Control       Diagnostics       Maintenance       Setup         Security       Security         Port Mirroring       Uput       Uput

Step	Description				
4	On the left side of the page, click on the <b>Port Mirroring</b> node. The <b>Port Mirroring</b> page opens:				
	Setup Port Mirroring				
	Ena	able:			
	Sou	irce: port 4			
	Destinat	tion: port 1			
		Save			
5	Configure the fol	lowing fields:			
Enable:		Place a check mark in this field to enable port mirroring. (Default = de-selected.)			
	Source:	Select a port (14). The traffic from this port will be duplicated and sent to the destination port for diagnosis.			
	Destination:	Select a port—other than the source port—to receive the duplicated traffic of the source port. Only ports with RSTP disabled can be selected.			
6	Click the Save b	putton.			

# Section 11.2 Monitoring the Unity Pro Application

#### **Overview**

This section describes how to use the BMX NOC 0401 Ethernet communication module's embedded web pages to monitor the Unity Pro application.

#### What Is in This Section?

This section contains the following topics:

Торіс	Page
Using the Monitoring Page	381
Data Editor (Standard)	382
Working With Data Templates	387
Data Editor (Lite)	391

# Using the Monitoring Page

# **Monitoring Page**

Click on the main menu Monitoring command to display the Monitoring page:



To access a monitoring service, click on either of the following links:

- Data Editor Lite
- Data Editor Standard

# **Data Editor (Standard)**

#### **Overview**

The **Data Editor** is a Java applet that dynamically displays run-time application data. Use the **Data Editor** to create and edit data monitoring tables that provide read/write access to application data and device registers.

**NOTE:** Write access is password protected.

# 

### **Unintended Equipment Operation**

The data editor makes it possible to write to application variables and change application data values.

- Use passwords to strictly limit access to write data functionality.
- Do not use weak passwords, including the default password and other obvious passwords.
- Limit access to trained personnel.

Failure to follow these instructions can result in death, serious injury, or equipment damage.

This topic describes the Data Editor user interface.

#### **Data Editor**

The Data Editor presents the following controls:

	â 🥝 📀	1	Rate 500	IP addre	ss 192.168.1.4
Empty 2	Symbol Address	Data type	Value F	ormat	Status
	Symbol Type Value	•	Address	t	Apply Reset
]					

- 1 Toolbar
- 2 Data template list
- 3 Data template
- 4 Configuration Area

# Toolbar

The Data Editor toolbar presents the following features:

Command or Field	lcon	Description			
New	*	<ul> <li>If a node in the data template list is selected, this command opens the New table dialog for the creation of a new data template. The new data template is inserted below the selected node.</li> <li>If a row in the currently open data template is selected, this command inserts a new row below the selected row.</li> </ul>			
Save		Saves changes made to both the data template list and each data template.			
Сору	₽ <u>₽</u>	<ul> <li>If a node in the data template list is selected, this command copies the selected data template.</li> <li>If an item (or row) in the currently open data template is selected, this command to copies the selected item.</li> </ul>			
Paste		<ul> <li>If the root, or Empty, node is selected in the data template list, this command pastes a previously copied data template into the list.</li> <li>If an empty item (or row) in the currently open data template is selected, this command pastes a previously copied item into the data template item at the selected row.</li> </ul>			
		<b>NOTE:</b> When adding a copied item, or row, to a data template, the paste command will overwrite item data in the selected row. To insert a copied row between existing rows, first use the <b>New</b> command to create an empty row, then paste the copied data into the new row.			
Delete	×	Deletes the selected data template from the list, or the selected item from the data template.			
Change password	۵	Opens the <b>Change password</b> dialog, where you can change the Data Editor Write <i>(see page 376)</i> password.			
		<b>NOTE:</b> The Data Editor Write password can also be changed in the <b>Setup</b> – <b>Security</b> web page.			
Read PLC symbols	٢	Loads the existing Unity Pro symbol—or variable—names into the Lookup Variable dialog. Variables that have been loaded into this dialog can be added to the currently open data template.			
Start animation	0	Starts the dynamic display of value and status for the items contained in the selected data template.			
		<b>NOTE:</b> The Start animation icon is visible only when animation is turned OFF.			

Command or Field	lcon	Description
Stop animation	-	Stops the dynamic display of value and status for the items contained in the selected data template.
		<b>NOTE:</b> The Stop animation icon is visible only when animation is turned ON.
Rate	—	The refresh rate of the dynamic display of data template items, in milliseconds.
IP address	—	The IP address of the Ethernet communication module and its embedded web server.

#### Data Template List

The data template list displays a node for each data template that was either:

- previously saved, or
- created after the Data Editor was opened, but not yet saved

Select a data template in this list to view or edit its contents.

**NOTE:** If you create a new data template, then navigate away from the **Data Editor** before clicking the **Save** button, the new data template will be lost.

#### **Data Template**

Use the data template—when animation is turned ON—to monitor the status and values of items for the template that is currently selected in the data template list.

Each data template item (or row) is defined in the configuration area. A data template item can contain the following fields:

Field	Description				
Symbol	Contains the names of Unity Pro symbols (variables).				
Address	Contains direct addresses and the addresses of Unity Pro symbols (variables). Any direct address can be viewed by entering its reference in this field. Valid direct addresses include:				
	%Mi	same as for 0X coils			
	%li	same as 1x for discreet inputs			
	%IWi	same as 3x for input registers			
	%MWi, %MDi, %MFi	same as 4x for holding registers			
	<ul> <li>NOTE:</li> <li>A single bit of any word address (for example, %MWi, %IWi) can be specified by appending ".j" to the address, where "j" is a bit index in the range of 0 (LSB) to 15 (MSB). For example, bit 4 of the value at %MW101 would be specified as %MW101.4.</li> <li>A direct address can include an index specification that allows it to be treated as an array variable. Indexed addressing can be used with a %Mi, %MWi, %MDi, or %MFi address by appending "[j]" to the address of the beginning of the array, where "j" is an unsigned integer value. For example, the third value of an array of float values starting at %MF201 would be specified as %MF201[2].</li> </ul>				

Field	Description				
Data type	Contains the data type of the symbol (variable) or direct address. Symbol (variable) data types appear automatically when the symbol (variable) is located. Select direct address data types from a drop-down list. The following data types are valid:				
	INT	16-bit signed integer			
	UINT	16-bit unsigned integer			
	DINT	32-bit signed integer			
	UDINT	32-bit unsigned integer			
	REAL	32-bit IEEE floating point			
	TIME	32-bit unsigned integer (in ms)			
	DATE	Date (32-bit BCD)			
	TOD	Time of day (32-bit BCD)			
	BOOL	1 bit discrete (Boolean)			
Value	When animation has started, this field displays the value of the symbol (variable) or direct address. This field is updated continuously.				
Format	Contains the format type for displaying the value of the symbol (variable) or direct address. The following formats are available:				
	bool	Boolean			
	dec	Decimal			
	hex	Hexadecimal			
	binary	Binary			
	ASCII	bytes displayed as ASCII characters			
	time	day_hr_min_sec_ms			
	date	YYYY-MM-DD or HH:MM:SS			
Status	Contains messages describing the status of communication with the direct address:				
	if communication is normal	The status message reads <b>OK</b>			
	if communication is interrupted	The status field displays a system message describing the interruption			

## **Configuration Area**

Open and close the configuration area by double-clicking on a row in the data template. The configuration area will display the configuration settings for the selected row. Use the up and down arrows on your keyboard to move between rows in the data template and display their settings in the configuration area.

Use the configuration area—when data template animation is turned OFF—to:

- create a new data template (see page 387)
- display the items contained in an existing data template (see page 388)
- add a direct address (see page 389) to a data template

Use the configuration area—when data template animation is turned ON—to write data to read/write application variables.

Refer to the topic Working With Data Templates for more information on how to use the controls in the configuration area.

# **Working With Data Templates**

#### **Creating a Data Template**

To display and access application data, first create a data template.

To create a new data template, follow these steps:

Step	Description
1	Confirm that <b>Data Editor</b> animation is OFF. If necessary, click the <b>Stop animation</b> toolbar button.
2	Click the <b>New</b> table <b>*</b> toolbar button. The <b>New table</b> dialog opens:
	New table
	Table name Type Modbus Ok Cancel
3	In the Table name field, type in the name of the new data template.
4	Click <b>Ok</b> . The new data template appears as a node in the data template list.

**NOTE:** Save the new data template before performing any other task in the **Data Editor**. Moving to another page—or creating a new data template in the current page—before saving your work deletes the new data template.

## Saving a Data Template

After you save a new data template, you can re-use it to view or modify its contents.

### NOTE:

- Be careful when you modify and save a data template. The last saved modification overwrites the pre-existing data template, even if the data template was originally created by someone other than yourself.
- If a data template is open for viewing by someone else, your edits to that data template will be seen only when that person next accesses the **Data Editor**.

To save a new data template, follow these steps:

Step	Description				
1	Click the <b>Save</b> 🔛 toolbar button. The <b>Save application</b> dialog opens:				
	Save application				
	Password OK Cancel				
2	In the Password field, type in the Web Page (HTTP) Access password.				
	NOTE: The default password is USER.				
3	Click <b>Ok</b> . The new data template is saved.				

# **Displaying an Existing Data Template**

When you open a saved data template, you can use it to:

- edit its contents by inserting a direct address
- monitor the value and status of data items
- write data values to a read/write variables

The data template list, located on the left side of the **Data Editor**, displays the saved data templates. Select a data template node from the list to display that template's data items in the spreadsheet on the right:

r 🖬 🖻 🗙 👌 🥥 💽			Rate 500	D IP add	dress 192.168.1.4		
Empty	Symbol	Address	Data type	Value	Format	Status	
Table 1		%MW1	INT		DECIMAL		-
		%MW121	INT		DECIMAL		III
Table_2							
							_
							-
						1	

# Inserting a Direct Address Into a Data Template

You can add Unity Pro direct address items—also called located registers—into a data template. After a direct address item is added, you can view or modify its value.

To add a direct address item to a data template, follow these steps:

Step	Description
1	In the data template spreadsheet, double-click on an empty row. The <b>Data Editor</b> configuration area opens.
2	In the Address field of the configuration area, type in the item's direct address.
3	In the configuration area, click <b>Apply</b> . The selected row is updated.
4	Save your edits.

## Modifying Data Values Using a Data Template

You can use the **Data Editor** to write data values to a direct address item, and send the new value to the controller.

For example, suppose that you have programmed a pushbutton object to jog a motor when the button is depressed and to stop jogging when the button is released. If communications are lost while the button is depressed, the motor will continue to jog even when the button is released. Graphic objects are not designed to be used to control situations like this, unless other interlock methods are installed in the system.

**NOTE:** You can only modify the value of data items that are defined as read/write in the Unity Pro application.

Step	Description		
1	In the data template spreadsheet, double-click on the item you want to write data to. The <b>Data Editor</b> configuration area opens, displaying the fields for the selected item.		
2	In the Value field, type in the desired data value.		
3	Click Apply. The Enter password dialog opens:		
	Enter password Password OK Cancel		
4	In the <b>Password</b> field, type in the Write Data password.		
	NOTE: The default password is USER.		
5	Click <b>OK</b> . The new value is sent to the controller.		

To use the Data Editor to edit data, follow these steps:

# Data Editor (Lite)

### **Overview**

**Data Editor Lite** is a version of the **Data Editor** that is smaller in size and therefore faster to download, especially for use via a dial-up connection.

Data Editor Lite presents the same interface as the Data Editor, with the exception that its toolbar does not include the Read PLC Symbols function:

		F	Rate 500	IP address 19	2.168.1.4
Empty	Symbol Address	Data type	Value Fo	rmat	Status
					<u> </u>
					•
		1			
1	Symbol		. Address		
	Туре	•	Format		-
	Value		Read only 📝		
					Apply Reset
					1

#### Variables

Data Editor Lite accepts the following IEC variables:

Address	Туре	Display
%MW IEC internal word	INT	DECIMAL
%MD IEC double word	DINT	DECIMAL
%M IEC internal bits	BOOL	BOOLEAN

**NOTE:** You cannot access the **Lookup Variable** dialog and insert symbols into a data template using **Data Editor Lite**. You can insert only direct addresses.

# **Re-Using Data Editor Templates**

Data Editor Lite can reuse the same templates created with the Data Editor. However, Data Editor templates can use a wider range of variable types than Data Editor Lite. When Data Editor Lite encounters a variable it cannot manage, it displays Not Supported as the data type. In this case, the variable cannot be edited using Data Editor Lite.

# Section 11.3 Diagnostics

## **Overview**

This section describes the diagnostic services provided by the BMX NOC 0401 Ethernet communication module.

## What Is in This Section?

This section contains the following topics:

Торіс	Page
Using the Diagnostics Page	394
Status Summary	395
Rack Viewer	398
Processor Load	400
Scanner Status	403
Messaging	405
QoS Configuration	407
Port Statistics	409
Redundancy	412
Email Diagnostics	413
Network Time Service Diagnostics	416
Properties	419

# **Using the Diagnostics Page**

## **Diagnostics Page**

Click on the main menu **Diagnostics** command to display the **Diagnostics** page:



To access a monitoring service, click on either of the following links:

- Status Summary (see page 395)
- Rack Viewer (see page 398)
- Ethernet:
  - Processor Load (see page 400)
  - Scanner Status (see page 403)
  - Messaging (see page 405)
  - QoS Configuration (see page 407)
- Switch
  - Port Statistics (see page 409)
  - Redundancy (see page 412)
- Network Time Service (see page 416)
- Email (see page 413)
- Properties (see page 419)

# **Status Summary**

## Introduction

Use the Status Summary page to view the status of:

- the LEDs (see page 324) located on the front of the BMX NOC 0401 Ethernet communication module
- the Ethernet services (see page 75) supported by the communication module
- the communication module in its role as:
  - scanner
  - Modbus TCP server
  - EtherNet/IP messaging server

# **Status Summary Display**

The **Status Summary** page looks like this:

Monitoring	Control	Diagnostics Mair	itenance Setup	
STATUS SUMMARY				
LEDs				
	Label	Status		
	RUN	Ready for Operation		
	ERR	No Fault Detected		
	ETH STS	In Operation		
	MS	In Operation		
	NS	Connections establishe	ed	
		Services		
	Function	Status		
	DHCP Server	Enabled		
	FDR Server	Enabled		
	QoS Tagging	Enabled		
IC	GMP Snooping	Enabled		
A	ccess Control	Enabled		
	Port Mirroring	Enabled		
	RSTP	Enabled		
Netv	vork Time Service	Enabled		
	Email Service	Enabled		
	canner Status	Not Configure	d	

To open this page:

Step	Action
1	Starting at the <b>Home page</b> , click the <b>Diagnostics</b> main menu item. The <b>Diagnostics</b> page opens.
2	On the left side of the <b>Diagnostics</b> page, select <b>Ethernet Status Summary</b> .
3	If necessary, type in the HTTP web access password.
	NOTE: The default password is USER.

# **Status Summary Data**

The **LEDs** section of the page can present the following operational states:

LED	Color	Text Descriptions	
RUN	Green	Ready for operation	
	Gray	Not ready for operation	
ERR	Red	Fault detected	
	Gray	No fault detected	
ETH STS	Green	In operation	
	Red	Duplicate IP	
		Waiting for BootP server response	
		Default IP Address in use	
		IP Address Configuration conflict detected	
MS (module status)	Green	In operation	
	Red	Not configured	
		Fault detected	
		Recoverable fault detected	
NS (network status)	Green	Connections established	
	Red	No EtherNet/IP connections	
		Connection error detected	
		Duplicate IP address	

Function	Color	Text Descriptions
DHCP Server	—	Enabled
FDR Server		Disabled
QoS Tagging		
IGMP Snooping		
Access Control		
Port Mirroring		
RSTP		
Network Time Service	—	Enabled
Email Service		Disabled
Scanner Status	Green	Working properly
	Red	At least one connection is bad
	Gray	Not configured

The **Services** section of the page can present the following functional conditions:

## **Rack Viewer**

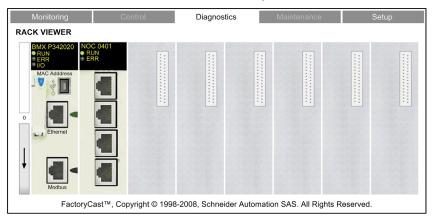
#### Introduction

Use the **Rack Viewer** to access web pages that describe the identity, placement, configuration and operation of modules in the M340 rack.

To view information describing a specific module—including the BMX NOC 0401 Ethernet communication module—click on the image of that module in the **Rack Viewer**.

## **Rack Display**

The Rack Viewer looks like this, when it is first opened:



Step	Action
1	Starting at the <b>Home page</b> , click the <b>Diagnostics</b> main menu item. The <b>Diagnostics</b> page opens.
2	On the left side of the <b>Diagnostics</b> page, select <b>Rack Viewer</b> .
3	If necessary, type in the HTTP web access password. NOTE: The default password is USER.

## Rack Viewer Displaying the BMX NOC 0401

When you click on the BMX NOC 0401 in the rack display, the following web page opens:

Leds:	Rack:		0		Produc	t Range:	M340	
RUN	Slot:		1		Trade 1	•	Comm	unication
ERR		e State:	Ok		Produc		Ethern	
		nce Present:		101	Referer	nce Configured:	BMX N	IOC 0401
	Versio	n:	1.0					
Parameters								
IP Address:	192.168.1	.4	Net mask:	255.255.2	255.0	Gateway:	0.0.0	0.0
Name:			MAC Address:	0.80.f4.1.	fb.bc			
Services		Status			Counte	r		
Port 502:	True	Generic fau	ilts:	False	Refused	d port 502 conne	ctions:	0
IO Scanner:	True	Ethernet in	terface disabled:	False	Receive	ed messages (/se	ec):	25
Global data:	True	Duplicate I	P Address:	False	Filter m	essages (/sec):		10
Emails:	True	Configurati	on mismatch:	False	Droppe	d messages (/see	c):	0
Server FDR:	True	Ethernet lin	k disconnected:	False	Max rec	eived messages	(/sec):	2893
		Obtaining I	P address:	False	Max Filt	ter messages (/se	эс):	10112
		Self-test fai	ult:	False	Max dro	opped messages	(/sec):	46132
		Application	faults:	False	Nb of M	lulticast (/sec):		9
					Nb of B	roadcast (/sec):		2893
								Reset
			Ba	ck 🧹				
				UK				

Click on the blue **Back** arrow to return to the rack display.

## **Processor Load**

#### Introduction

Use the **Processor Load** web page to display dynamically generated data for the BMX NOC 0401 communication module's bandwidth usage.

#### **Processor Load Display**

The Processor Load page looks like this:

Monitoring	DAD	Control Diagnostics	Maintena	ance Setup
		Processor Load	ł	
		Module Load		
	Processor	Utilization	38	%
		Communication L	oad	
Function		Statistics		Units
		EtherNet/IP Sent (writes)	31	Packets per second
	Scanner	EtherNet/IP Received (read)	33	Packets per second
		Modbus TCP Requests	17	Packets per second
	[	Modbus TCP Responses	16	Packets per second
I/O				
	Adapter	EtherNet/IP Sent (writes)	0	Packets per second
	, ladptor	EtherNet/IP Received (read)	0	Packets per second
		Module Capacity	12000	Packets per second
	ŀ	Module Utilization	0.8	%
	Client	EtherNet/IP activity	0	Messages per second
	Client	Modbus TCP activity	0	Messages per second
lessaging				•
	Server	EtherNet/IP activity	0	Messages per second
	Server	Modbus TCP activity	0	Messages per second
	Copyria	ht © 2000-2009, Schneider Automatio	on SAS. All Rights	s Reserved.

**NOTE:** The background color for the **Processor Utilization** and **Module Utilization** values varies, depending upon the percentage of utilization. If utilization is:

- 90% to 100%—background color is RED
- 80% to 89.99%—background color is YELLOW
- 0% to 79.99%—background color is GRAY

Step	Action
1	Starting at the <b>Home page</b> , click the <b>Diagnostics</b> main menu item. The <b>Diagnostics</b> page opens.
2	On the left side of the <b>Diagnostics</b> page, select <b>Ethernet</b> → <b>Processor Load</b> .
3	If necessary, type in the HTTP web access password. <b>NOTE:</b> The default password is <b>USER</b> .

## **Processor Load Parameters**

The **Processor Load** page displays the following parameters for the communication module:

Parameter	Description
Module Load:	
Processor Utilization	The percent of Ethernet communication module processor capacity used by the present level of communication activity. The background color of the value changes, depending on the percentage utilization.
I/O Scanner:	
EtherNet/IP Sent (writes)	The number of EtherNet/IP packets the module has sent, since the last reset, in packets/second.
EtherNet/IP Received (read)	The number of EtherNet/IP packets the module has received, since the last reset, in packets/second.
Modbus TCP Requests	The number of Modbus TCP requests the module has sent, since the last reset, in packets/second.
Modbus TCP Responses	The number of Modbus TCP responses the module has received, since the last reset, in packets/second.
I/O Adapter:	
EtherNet/IP Sent (writes)	The number of EtherNet/IP packets the module has sent—in the role of a local slave—since the last reset, in packets/second.
EtherNet/IP Received (read)	The number of EtherNet/IP packets the module has received—in the role of a local slave—since the last reset, in packets/second.
I/O - Module	
Module Capacity	The maximum number of packets that the module can process, in packets per second.
Module Utilization	The percentage of communication module capacity being used by the application. The background color of the value changes, depending on the percentage utilization.
Messaging - Client:	
EtherNet/IP activity	The number of I/O messages sent by the module—using the EtherNet/IP protocol— since last reset, in packets per second.
Modbus TCP activity	The number of I/O messages sent by the module—using the Modbus TCP protocol— since last reset, in packets per second.
Messaging - Server:	
EtherNet/IP activity	The number of I/O messages received by the module—using the EtherNet/IP protocol—since last reset, in packets per second.
Modbus TCP activity	The number of I/O messages received by the module—using the Modbus TCP protocol—since last reset, in packets per second.

## **Scanner Status**

#### Introduction

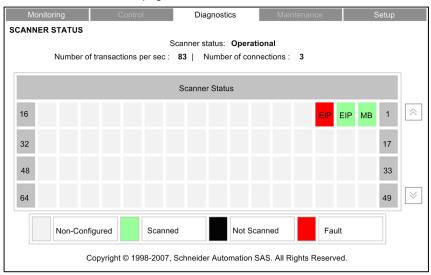
The **Scanner Status** web page displays read-only data describing the current state of the BMX NOC 0401 Ethernet communication module in its role as I/O scanner.

#### **Scanner Status Display**

The top of the page displays the following general diagnostic information about the scanner:

- I/O scanning status
  - A value of **Operational** indicates that the values in the **Scanner Status** grid are reporting the state of scanned devices.
  - A value of **Stopped** indicates the local system is not scanning. In this case, any data that appears in the **Scanner Status** grid is meaningless.
- Number of transactions per second
- Number of connections

The Scanner Status web page looks like this:



In the **Scanner Status** grid, the colors that appear in each block indicate the following states for specific remote devices:

- · GREEN indicates that a device is being scanned
- BLACK indicates that I/O scanning of the specific device has been intentionally disabled
- GRAY indicates an device that is not configured
- RED indicates a suspect device

**NOTE:** A green **Scanner Status** indicator in the grid can remain green for a remote scanned device after the Ethernet cable is detached from that device. This situation can occur if the health timeout value for that device is set to 0.

To avoid this result—and to help promote the accurate reporting of I/O scanning health—configure an operational health timeout value in the range 1...65535 (in 1 ms increments).

The grid also indicates the protocol used to communicate with the remote device:

- MB: indicates a Modbus TCP connection
- EIP: indicates an EtherNet/IP connection

Step	Action
1	Starting at the <b>Home page</b> , click the <b>Diagnostics</b> main menu item. The <b>Diagnostics</b> page opens.
2	On the left side of the <b>Diagnostics</b> page, select <b>Ethernet</b> $\rightarrow$ <b>Scanner Status</b> .
3	If necessary, type in the HTTP web access password. <b>NOTE:</b> The default password is <b>USER</b> .

## Messaging

### Introduction

The **Messaging** page provides current information on the open TCP connections on port 502.

### Messaging Display

The top of the page displays the number of messages sent and received by local port 502.

The Messaging page looks like this:

Mc	onitoring	Control		Diagnostics	Maint	enance	Setup	
IESSA	GING DIAGNOS	ГІС						
	Number of	Messages ser	nt : 94275	Number	of Messages	s received :	95274	
Conn.	Remote address	Remote port	Local port	Туре	Mess. Sent	Mess. Recei	ived Error Sent	
1	192.168.1.222	2568	502	Modbus TCP	3955	3954	0	
2	192.168.1.6	1217	502	EtherNet/IP	2345	2344	0	14
3	192.168.1.7	1222	502	Modbus TCP	1357	1356	0	-
								- [~
	Cop	yright © 1998	-2007, Schn	eider Automatior	n SAS. All Rig	hts Reserve	d.	_

The display grid provides the following information about each active connection:

- Conn.: the connection number-1 to 64
- Remote address: the IP address of the remote device
   NOTE: If the remote device includes an embedded web server, click on the Remote address to open that server and view the remote device's web pages.
- Remote port: the TCP port for the connection on the remote device
- Local port: the TCP port for the connection on the Ethernet communication module
- Type: the connection type—EtherNet/IP or Modbus TCP
- Mess. Sent: the number of messages transmitted over this connection
- Mess. Received: the number of messages received by this connection
- Error Sent: the number of events detected on this connection

## NOTE:

- Following a request to close a connection, the PLC may hold the connection open in its memory for a few minutes, during which the display will reflect the open connection.
- The **Number of Messages received** is not reset after a port 502 connection is closed. Therefore, the count indicates the total number of messages that have been received since the module was started

Step	Action
1	Starting at the <b>Home page</b> , click the <b>Diagnostics</b> main menu item. The <b>Diagnostics</b> page opens.
2	On the left side of the <b>Diagnostics</b> page, select <b>Ethernet</b> $\rightarrow$ <b>Messaging</b> .
3	If necessary, type in the HTTP web access password.
	NOTE: The default password is USER.

## **QoS Configuration**

#### Introduction

The BMX NOC 0401 Ethernet communication module supports the OSI layer 3 Quality of Service (QoS) standard defined in RFC-2475. When the QoS is enabled, the module adds a *differentiated services code point* (DSCP) tag to each Ethernet packet it transmits, thereby indicating the priority of that packet.

The QoS Configuration page displays both the:

- status of the QoS Ethernet packet tagging service-enabled or disabled, and
- the QoS service configuration settings

**NOTE:** The QoS service is enabled in the Services page (see Quantum, 140 NOC 771 01 *Ethernet Communication Module, User Manual*), and the configuration settings are input in the QoS page (see Quantum, 140 NOC 771 01 *Ethernet Communication Module, User Manual*), of the Unity Pro Ethernet Configuration Tool.

#### **QoS Configuration Display**

The QoS Configuration page looks like this:

Monitoring	Control	Diagnostics	Maintenance	Setup			
QoS CONFIGURAT	ΓΙΟΝ						
		QoS Configuratio	n				
		Status: Enabl	led				
		EtherNet/IP					
	DSCP Va	lue for IO Data Urgent	Priority Messages	55			
	DSCP Value	e for IO Data Schedule	Priority Messages	47			
	DSCP	Value for IO Data High	Priority Messages	43			
	DSCP	Value for IO Data Low	Priority Messages	31			
		DSCP Value for	r Explicit Message	27			
	Modbus TCP						
		DSCP Valu	e for IO Messages	47			
		DSCP Value for	r Explicit Message	27			
		Network Time Serv	ice				
		DSCP Value for Net	work Time Service	59			
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This page is read-only.

Step	Action
1	Starting at the <b>Home page</b> , click the <b>Diagnostics</b> main menu item. The <b>Diagnostics</b> page opens.
2	On the left side of the Diagnostics page, select Ethernet $\rightarrow$ QoS Configuration.
3	If necessary, type in the HTTP web access password.
	NOTE: The default password is USER.

## **Port Statistics**

#### Introduction

Use the **Port Statistics** page to display the following data for the BMX NOC 0401 Ethernet communication module:

- static IP addressing configuration data for the module, and
- dynamically generated data describing operations of the module's internal port, and each of the module's external Ethernet ports (ports 1, 2, 3 and 4)

## **Port Statistics Display**

The Port Statistics page looks like this:

		Ethernet configu	ration		
Host	name:	Subnet	Mask: 255.255.255	.0	
MAC Ad	dress: bc fb 01 f4	4 80 00 Ga	teway: 0.0.0.0		
IP Ad	dress: 192.168.1.	4			
		Port Statistic	s		
	Internal port	port 1	port 2	port 3	port 4
Interface label:	Internal port	Port 1	Port 2	Port 3	Port 4
Speed (Operational):	N/A	100Mbps	100Mbps	10Mbps	10Mbps
Duplex (Operational):	N/A	TP-Full Link	TP-Full Link	TP-Half Link	TP-Half Link
Frames transmit OK:	0	0	0	0	0
Frames received OK:	181596	126354	73220	0	0
Collisions:	0	0	0	0	0
Excessive collisions:	0	0	0	0	0
Late collisions:	0	0	0	0	0
CRC errors:	0	0	0	0	0
Number Bytes Received:	15568790	5047683	704	0	0
Number Inbound Packets Error:	220	19185	73220	0	0
Number Inbound Packets Discard:	0	0	0	0	0
Number Bytes Sent:	203	203	203	203	203
Number Outbound Packets Error:	100	100	100	10	10
Number Outbound Packets Discard:	3	3	3	3	3

Click on the **Reset counters** button to reset the counting statistics to zero.

To open this page:

Step	Action
1	Starting at the <b>Home page</b> , click the <b>Diagnostics</b> main menu item. The <b>Diagnostics</b> page opens.
2	On the left side of the Diagnostics page, select Ethernet $\rightarrow$ Switch $\rightarrow$ Port Statistics.
3	If necessary, type in the HTTP web access password.
	NOTE: The default password is USER.

## **Port Statistics Descriptions**

The Port Statistics page displays the following parameters for each communication module port:

Parameter	Description
Ethernet Configuration data:	
Hostname	The name assigned to the communication module
MAC Address	The factory assigned Media Access Control (MAC) address, consisting of 6 hexidecimal octet values
IP Address	The Internet Protocol (IP) address (see page 67) that has been assigned to the communication module
Subnet Mask	The subnet mask (see page 67) that has been assigned to the communication module
Gateway	The IP address of the remote device (see page 67), if any, that serves as a gateway to the communication module
Port Statistics:	
Interface Label	Un-Initialized or Initialized
Speed (Operational)	Baud rate: 0, 10, 100 Mbps
Duplex (Operational)	Twisted Pair— Full Link, Twisted Pair—Half Link
Frames transmit OK:	The number of frames that have been successfully transmitted
Frames received OK:	The number of frames that have been successfully received
Collisions:	The number of times a collision between two successfully transmitted packets was detected on the link
Excessive collisions:	The number of times the transmitter has not been successful after 16 attempts to transmit a frame, due to repeated collisions
CRC errors:	The number of times a CRC (FCS) error was detected on an incoming frame
Number Bytes Received:	Number of inbound bytes received on the interface
Number Inbound Packets Error:	The number of inbound packets that contain detected errors (not included in discards)

Parameter	Description
Number Inbound Packets Discard:	The number of inbound packets received on the interface, but discarded
Number Bytes Sent:	The number of outbound bytes transmitted on the interface
Number Outbound Packets Error:	The number of outbound packets that contain detected errors (not included in discards)
Number Outbound Packets Discard:	The number of outbound packets discarded while attempting to send them

## Redundancy

#### Introduction

Use the **Redundancy** page to enable and disable the Rapid Spanning Tree Protocol (RSTP) for switch ports 3 and 4.

**NOTE:** Because only switch ports 3 and 4 support RSTP redundancy, use ports 3 and 4 to connect the BMX NOC 0401 Ethernet communication module to the wider network, and ports 1 and 2 for connections to local devices.

The RSTP service creates a loop-free logical network path for Ethernet devices that are part of a topology that includes redundant physical paths, and automatically restores network communication—by activating redundant links—in the event the network experiences a service interruption.

### **Redundancy Display**

The Redundancy page looks like this:

Monitoring	Control	Diagnostics	Maintenance	Setup
REDUNDANCY				
		Redundancy		
	<b>RSTP State por</b>	t 3: Disabled		
	RSTP State por	t 4: Disabled		
с	opyright © 2000-2009, \$	Schneider Automation	SAS. All Rights Reserved	1.

Step	Action
1	Starting at the <b>Home page</b> , click the <b>Diagnostics</b> main menu item. The <b>Diagnostics</b> page opens.
2	On the left side of the <b>Diagnostics</b> page, select <b>Ethernet</b> $\rightarrow$ <b>Switch</b> $\rightarrow$ <b>Redundancy</b> .
3	If necessary, type in the HTTP web access password.
	NOTE: The default password is USER.

## **Email Diagnostics**

#### **Diagnosing SMTP Transmissions**

Use the **SMTP Diagnostics** web page to display dynamically generated data describing the BMX NOC 0401 Ethernet communication module Email transmissions.

**NOTE:** The Email service is enabled in the **Services** page, and the configuration settings are input in the **SMTP Configuration** page of the module DTM.

The SMTP Diagnostics web page looks like this:

Monitoring Control		Diagnostics	Maintenance	Setup
EMAIL DIAGNOSTICS				
Email Service				
Status Operatonal				
		Email Server		
Statu	s 🗸		IP Address 192 .	168 . 1 . 10
	Informa	ation of Last Email Heade	r Used	
Sender Address	Operator1@cc	mpany.com		
Recipient Address	merle@mainot	fice.com		
Subject	Pump #1 pum	ping mud, Merle, shut her d	own	
		Email Service Statistics		
Number of Emails Sent:			2	
Number of Responses from Ema	il Server:		25	
Number of Errors:			0	
Last Error:			16#0	
Time elapses since last e-mail su	ccessfully sent (	secs):	23	
Number of times link to the serve	r down:		0	
L		Reset Counters		
с	opyright © 1998-	2012, Schneider Electric. A	II Rights Reserved.	

Click the Reset Counter button to reset to 0 the Email Service Statistics.

Step	Action
1	Starting at the <b>Home page</b> , click the <b>Diagnostics</b> main menu item. The <b>Diagnostics</b> page opens.
2	On the left side of the <b>Diagnostics</b> page, select <b>Ethernet →SMTP Diagnostics</b> .
3	If necessary, type in the HTTP web access password.
	NOTE: The default password is USER.

## **Email diagnostic Parameters**

Electronic mail notification service parameters include the following:

Parameter	Description			
Email Service:				
Status	<ul><li>The status of this service in the Ethernet communication module:</li><li>Operational</li><li>Service Disabled</li></ul>			
Email Server:				
Status	<ul> <li>The connection status between Ethernet communication module and the SMTP server:</li> <li>check mark = connected</li> <li>no check mark = not connected</li> </ul>			
	<b>NOTE:</b> Status is checked at start-up and at least every 30 minutes after start-up.			
IP Address	IP address of the SMTP server			
Information of Last Email Head	er Used:			
Sender Address:	Content of the From field in the last used Email header			
Recipient Address:	Content of the To field in the last used Email header			
Subject:	Content of the Subject field in the last used Email header			
Email Service Statistics:				
Number of Emails Sent	Total number of Emails sent and successfully acknowledged by the SMTP server.			
Number of Responses from Email Server	Total number of responses received from the SMTP server			
Number of Errors	<ul> <li>Total number of Emails that either:</li> <li>could not be sent</li> <li>were sent but were not successfully acknowledged by the SMTP server</li> </ul>			
Last Error	Hexadecimal code describing the reason for the last unsuccessful Email transmission (see page 437). The value "0" indicates no unsuccessful transmissions.			
Time elapses since last Email successfully sent (sec)	Counts the number of seconds since the last Email was successfully sent.			
Number of times link to the server down	Number of times the SMTP server could not be reached. (Link checked every 30 minutes.)			

## **Network Time Service Diagnostics**

#### **Diagnosing the Network Time Service**

Use the **Network Time Service Diagnostic** web page to display dynamically generated data describing the operation of the network time protocol (NTP) service that you configured in the Network Time Service page (*see page 103*) in Unity Pro.

**NOTE:** The Email service is enabled in the **Services** page, and the configuration settings are input in the **Network Time Service Configuration** page of the module DTM.

The NTP Diagnostics web page looks like t his:

Monitoring	Control	Di	agnostics	Maintenar	ıce	Setup
NETWORK TIME SERVI	CE DIAGNOSTICS					
Network <sup>-</sup>	Time Service					
Status Opera	tional					
		Date a	nd Time Status			
Date: 21-0	Dct-2011	Time:	14:22:13	DST	Status:	ON
Time Zone: UTC	-5:00					
		N	TP Server			
Status	IP Ad	dress	192 . 168 . 1 .	. 1	Туре	e: Primary
	Ne	twork Tin	ne Service Statis	tics		
Number of Red	quests: 0		N	umber of Errors:	0	
Number of Resp	onses: 0			Last Error:	16#0	
		Re	set Counters			
	Copyright © 1998-	2012, Sch	neider Electric. Al	II Rights Reserve	d.	

Click the **Reset Counter** button to reset to 0 the **Network Time Service Statistics**.

Step	Action
1	Starting at the <b>Home page</b> , click the <b>Diagnostics</b> main menu item. The <b>Diagnostics</b> page opens.
2	On the left side of the <b>Diagnostics</b> page, select <b>Ethernet</b> — <b>NTP Diagnostics</b> .
3	If necessary, type in the HTTP web access password.
	NOTE: The default password is USER.

## Network Time Service Diagnostic Parameters

Parameter	Description		
Network Time Service:			
Status	Operational status of the service in the module: • Operational • Service Disabled		
Date and Time Status:			
Date:	System date		
Time:	System time		
	<b>NOTE:</b> Red text indicates the network time server is not available.		
DST Status	<ul> <li>The actual working status of the automatic daylight savings service:</li> <li>ON = automatic adjustment of daylight savings is enabled and the current date and time reflect the daylight savings time adjustment</li> <li>OFF = automatic adjustment of daylight savings is disabled; or automatic adjustment of daylight savings is enabled, but the current date and time may not reflect the daylight savings time adjustment</li> </ul>		
Time Zone	Time zone plus or minus Universal Time, Coordinated (UTC)		
NTP Server:			
Status	<ul> <li>Connection status of the NTP server:</li> <li>check mark = the NTP server is reachable</li> <li>no check mark = the NTP server is not reachable</li> </ul>		
IP Address	The IP address of the NTP server		
Туре	The NTP server currently active: • Primary • Secondary		
Network Time Service St	atistics:		
Number of Requests:	Total number of client requests sent to the NTP server		
Number of Responses:	Total number of server responses sent from the NTP server		
Number of Errors:	Total number of unanswered NTP requests		

Time synchronization service parameters are in the table:

Parameter	Description
Last Error	<ul> <li>Last detected error code received from the NTP client:</li> <li>0: good NTP configuration</li> <li>1: late NTP server response (can be caused by excessive network traffic or server overload)</li> <li>2: NTP not configured</li> <li>3: invalid NTP parameter setting</li> <li>4: NTP component disabled</li> <li>7: unrecoverable NTP transmission</li> <li>9: invalid NTP server IP address</li> <li>15: invalid syntax in the custom time zone rules file</li> </ul>

## **Properties**

#### Introduction

The **Properties** web page displays read-only data describing the particular BMX NOC 0401 Ethernet communication module installed in your system.

## **Properties Display**

The **Properties** page looks like this:

Monitoring	Control	Diagnostics	Maintenance	Setup
PROPERTIES				
		Properties		_
	Device type:	12		
	Product code:	2052		
	Product name:	BMX NOC 0401		
	Revision:	1.01		
	Serial number:	134347887		
	Status:	100		
	Vendor name:	243		
	Copyright © 2000-:	2009, Schneider Automation	SAS. All Rights Reserved	d.

Step	Action
1	Starting at the <b>Home page</b> , click the <b>Diagnostics</b> main menu item. The <b>Diagnostics</b> page opens.
2	On the left side of the <b>Diagnostics</b> page, select <b>Properties</b> .
3	If necessary, type in the HTTP web access password. NOTE: The default password is USER.

# **Appendices**



## What Is in This Appendix?

The appendix contains the following chapters:

Chapter	Chapter Name	Page
A	Detected Error Codes	423
В	CIP General Status Codes	431
С	Modbus Exception Response Codes	435
D	Email Detected Error Response Codes	437

## Appendix A Detected Error Codes

#### **Overview**

This chapter contains a list of codes that describe the status of Ethernet communication module messages.

## What Is in This Chapter?

This chapter contains the following topics:

Торіс	Page
EtherNet/IP Implicit or Explicit Messaging Detected Error Codes	424
Explicit Messaging: Communication and Operation Reports	427

## EtherNet/IP Implicit or Explicit Messaging Detected Error Codes

#### Introduction

If a DATA\_EXCH function block does not execute an EtherNet/IP explicit message, Unity Pro returns a hexadecimal detected error code. The code can describe an EtherNet/IP detected error.

#### **EtherNet/IP Detected Error Codes**

EtherNet/IP hexadecimal detected error codes include:

Detected Error Code	Description		
16#800D	Timeout on the explicit message request		
16#8012	Bad device		
16#8015	<ul> <li>Either:</li> <li>Nor resources to handle the message, or</li> <li>Internal detected error: no buffer available, no link available, impossible to send to the TCP task</li> </ul>		
16#8018	Either: • Another explicit message for this device is in progress, or • TCP connection or encapsulation session in progress		
16#8030	Timeout on the Forward_Open request		
	wing 16#81xx detected errors are Forward_Open response detected errors that originate at tet and are received via the CIP connection.		
16#8100	Connection in use or duplicate Forward_Open		
16#8103	Transport class and trigger combination not supported		
16#8106	Ownership conflict		
16#8107	Target connection not found		
16#8108	Invalid network connection parameter		
16#8109	Invalid connection size		
16#8110	Target for connection not configured		
16#8111	RPI not supported		
16#8113	Out of connections		
16#8114	Vendor ID or product code mismatch		
16#8115	Product type mismatch		
16#8116	Revision mismatch		
16#8117	Invalid produced or consumed application path		
16#8118	Invalid or inconsistent configuration application path		
16#8119	Non-Listen Only connection not opened		

Detected Error Code	Description		
16#811A	Target object out of connections		
16#811B	RPI is smaller than the production inhibit time		
16#8123	Connection timed out		
16#8124	Unconnected request timed out		
16#8125	Parameter detected error in unconnected request and service		
16#8126	Message too large for unconnected_send service		
16#8127	Unconnected acknowledge without reply		
16#8131	No buffer memory available		
16#8132	Network bandwidth not available for data		
16#8133	No consumed connection ID filter available		
16#8134	Not configured to send scheduled priority data		
16#8135	Schedule signature mismatch		
16#8136	Schedule signature validation not possible		
16#8141	Port not available		
16#8142	Link address not valid		
16#8145	Invalid segment in connection path		
16#8146	Detected error in Forward_Close service connection path		
16#8147	Scheduling not specified		
16#8148	Link address to self invalid		
16#8149	Secondary resources unavailable		
16#814A	Rack connection already established		
16#814B	Module connection already established		
16#814C	Miscellaneous		
16#814D	Redundant connection mismatch		
16#814E	No more user-configurable link consumer resources: the configured number of resources for a producing application has reached the limit		
16#814F	No more user-configurable link consumer resources: there are no consumers configured for a producing application to use		
16#8160	Vendor specific		
16#8170	No target application data available		
16#8171	No originator application data available		
16#8173	Not configured for off-subnet multicast		
16#81A0	Detected error in data assignment		
16#81B0	Optional object state detected error		

Detected Error Code	Description	
16#81C0	Optional device state detected error	
Note: All 16#82xx detected errors are register session response detected errors.		
16#8200	Target device does not have sufficient resources	
16#8208	Target device does not recognize message encapsulation header	
16#820F	Reserved or unknown detected error from target	

## **Explicit Messaging: Communication and Operation Reports**

#### **Overview**

Communication and operation reports are part of the management parameters.

**NOTE:** It is recommended that communication function reports be tested at the end of their execution and before the next activation. On cold start-up, confirm that all communication function management parameters are checked and reset to 0.

It may be helpful to use the %S21 to examine the first cycle after a cold or warm start. For more information, refer to Unity Pro online help for %S21.

#### **Communication Report**

This report is common to every explicit messaging function. It is significant when the value of the activity bit switches from 1 to 0. The reports with a value between 16#01 and 16#FE concern errors detected by the processor that executed the function.

Value	Communication report (least significant byte)		
16#00	Correct exchange		
16#01	Exchange stop on timeout		
16#02	Exchange stop on user request (CANCEL)		
16#03	Incorrect address format		
16#04	Incorrect destination address		
16#05	Incorrect management parameter format		
16#06	Incorrect specific parameters		
16#07	Error detected in sending to the destination		
16#08	Reserved		
16#09	Insufficient receive buffer size		
16#0A	Insufficient send buffer size		
16#0B	No system resources: the number of simultaneous communication EFs exceeds the maximum that can be managed by the processor		
16#0C	Incorrect exchange number		
16#0D	No telegram received		
16#0E	Incorrect length		
16#0F	Telegram service not configured		
16#10	Network module missing		
16#11	Request missing		
16#12	Application server already active		
16#13	UNI-TE V2 transaction number incorrect		

The different values of this report are indicated in the following table:

Value	Communication report (least significant byte)	
16#FF	Message refused	

**NOTE:** The function can detect a parameter error before activating the exchange. In this case the activity bit remains at 0, and the report is initialized with values corresponding to the detected error.

## **Operation Report**

This report byte is specific to each function, and specifies the result of the operation on the remote application:

Value	Operation report (most significant byte)		
16#05	Length mismatch (CIP)		
16#07	Bad IP address		
16#08	Application error		
16#09	Network is down		
16#0A	Connection reset by peer		
16#0C	Communication function not active		
16#0D	<ul> <li>Modbus TCP: transaction timed out</li> <li>EtherNet/IP: request timeout</li> </ul>		
16#0F	No route to remote host		
16#13	Connection refused		
16#15	<ul> <li>Modbus TCP: no resources</li> <li>EtherNet/IP: no resources to handle the message; or an internal detected error; or no buffer available; or no link available; or cannot send message</li> </ul>		
16#16	Remote address not allowed		
16#18	<ul> <li>Modbus TCP: concurrent connections or transactions limit reached</li> <li>EtherNet/IP: TCP connection or encapsulation session in progress</li> </ul>		
16#19	Connection timed out		
16#22	Modbus TCP: invalid response		
16#23	Modbus TCP: invalid device ID response		
16#30	<ul> <li>Modbus TCP: remote host is down</li> <li>EtherNet/IP: connection open timed out</li> </ul>		
16#8016#87: Forw	ard_Open response detected errors:		
16#80	Internal detected error		
16#81	Configuration detected error: the length of the explicit message, or the RPI rate, needs to be adjusted		
16#82	Device detected error: target device does not support this service		
16#83	Device resource detected error: no resource is available to open the connection		
16#84	System resource evebt: unable to reach the device		

Value	Operation report (most significant byte)		
16#85	Data sheet detected error: incorrect EDS file		
16#86	Invalid connection size		
16#9016#9F: Regi	16#9016#9F: Register session response detected errors:		
16#90	Target device does not have sufficient resources		
16#98	Target device does not recognize message encapsulation header		
16#9F	Unknown detected error from target		

## **Appendix B** CIP General Status Codes

## **CIP General Status Codes**

**NOTE:** Taken by permission from *The CIP Networks Library, Volume 1*, <u>Common Industrial</u> <u>Protocol (CIP™)</u>, Edition 3.6, April 2009.

The following table lists the status codes that may be present in the general status code field of a detected error response message. Note that the extended code field is available for use in further describing any general status code. Extended status codes are unique to each general status code within each object. Each object manages the extended status values and value ranges (including vendor specific). All extended status values are reserved unless otherwise indicated within the object definition.

General Status Code (in hex)	Status Name	Description of Status
00	Success	Service was successfully performed by the object specified.
01	Connection unsuccessful	A connection related service was unsuccessful along the connection path.
02	Resource unavailable	Resources needed for the object to perform the requested service were unavailable.
03	Invalid parameter value	See status code 0x20, which is the preferred value to use for this condition.
04	Path segment error	The path segment identifier or the segment syntax was not understood by the processing node. Path processing stops when a path segment error is detected.
05	Path destination unknown	The path is referencing an object class, instance, or structure element that is not known or is not contained in the processing node. Path processing stops when a path destination unknown error is detected.
06	Partial transfer	Only part of the expected data was transferred.
07	Connection lost	The messaging connection was lost.
08	Service not supported	The requested service was not implemented or was not defined for this object class/instance.
09	Invalid attribute value	Invalid attribute data detected.
0A	Attribute list error	An attribute in the Get_Attribute_List or Set_Attribute_List response has a non-zero status.

General Status Code (in hex)	Status Name	Description of Status
0B	Already in requested mode/state	The object is already in the mode/state being requested by the service.
0C	Object state conflict	The object cannot perform the requested service in its current mode/state.
0D	Object already exists	The requested instance of object to be created already exists.
0E	Attribute not settable	A request to modify a non-modifiable attribute was received.
0F	Privilege violation	A permission/privilege check was unsuccessful.
10	Device state conflict	The device's current mode/state prohibits the execution of the requested service.
11	Reply data too large	The data to be transmitted in the response buffer is larger than the allocated response buffer.
12	Fragmentation of a primitive value	The service specified an operation that is going to fragment a primitive data value, i.e., half a REAL data type.
13	Not enough data	The service did not supply enough data to perform the specified operation.
14	Attribute not supported	The attribute specified in the request is not supported.
15	Too much data	The service supplied more data than was expected.
16	Object does not exist	The object specified does not exist in the device.
17	Service fragmentation sequence not in progress	The fragmentation sequence for this service is not currently active for this data.
18	No stored attribute data	The attribute data of this object was not saved prior to the requested service.
19	Store operation unsuccessful	The attribute data of this object was not saved due to an unsuccessful attempt.
1A	Routing unsuccessful, request packet too large	The service request package was too large for transmission on a network in the path to the destination. The routing device was forced to abort the service.
1B	Routing unsuccessful, response packet too large	The service response packet was too large for transmission on a network in the path from the destination. The routing device was forced to abort the service.
1C	Missing attribute list entry data	The service did not supply an attribute in a list of attributes that was needed by the service to perform the requested behavior.
1D	Invalid attribute value list	The service is returning the list of attributes supplied with status information for those attributes that were invalid.
1E	Embedded service error	An embedded service resulted in a detected error.

General Status Code (in hex)	Status Name	Description of Status
1F	Vendor specific error	A vendor specific error has been detected. The additional code field of the error response defines the particular error encountered. Use this general code only when none of the codes presented in this table or within an object class definition accurately reflect the detected error.
20	Invalid parameter	A parameter associated with the request was invalid. This code is used when a parameter does not meet the requirements of this specification and/or the requirements defined in an application object specification.
21	Write-once value or medium already written	An attempt was made to write to a write-once medium (e.g., WORM drive, PROM) that has already been written, or to modify a value that cannot be changed once established.
22	Invalid reply received	An invalid reply is received (e.g., reply service code does not match the request service code, or reply message is shorter than the minimum expected reply size). This status code an serve for other causes of invalid replies.
23	Buffer overflow	The message received is larger than the receiving buffer can handle. The entire message was discarded.
24	Message format error	The format of the received message is not supported by the server.
25	Key failure in path	The key segment that was included as the first segment in the path does not match the destination module. The object specific status indicates which part of the key check was unsuccessful.
26	Path size invalid	The size of the path that was sent with the service request is either not large enough to allow the request to be routed to an object or too much routing data was included.
27	Unexpected attribute in list	An attempt was made to set an attribute that is not able to be set at this time.
28	Invalid member ID	The member ID specified in the request does not exist in the specified class/instance/attribute.
29	Member not settable	A request to modify a non-modifiable member was received.
2A	Group 2 only server — general error This detected error code may only be reported by DeviceNet 2 only servers with 4 Kb or less code space and only in plac service not supported, attribute not support, or attribute not settable.	
2B	Unknown Modbus error	A CIP to Modbus translator received an unknown Modbus exception code.
2C	Attribute not gettable	A request to read a non-readable attribute was received.
2D - CF		Reserved by CIP for future extensions.

General Status Code (in hex)	Status Name	Description of Status
D0 - FF	Reserved for object class and service errors	This range of detected error codes is used to indicate object class specific detected errors. Use this range only when none of the codes presented in this table accurately reflect the error that is detected.

# **Appendix C** Modbus Exception Response Codes

#### **MODBUS Exception Response Codes**

The MODBUS exception response codes include the following:

Status		Response	Description
Hex)	(Dec)		
0x8101	33025	Illegal Function	The function code received in the query is not an allowable action for the server (or slave). This may be because the function code is only applicable to newer devices, and was not implemented in the unit selected. It could also indicate that the server (or slave) is in the wrong state to process a request of this type. This code is also returned when attempting to write to a read-only attribute.
0x8102	33026	Illegal Data Address	The data address received in the query is not an allowable address for the server (or slave). More specifically, the combination of reference number and transfer length is invalid.
0x8103	33027	Illegal Data Value	A value contained in the query data field is not an allowable value for server (or slave). This indicates an invalid request structure. It specifically does NOT mean that a data item submitted for storage in a register has a value outside the expectation of the application program, because the MODBUS protocol does not test the significance of any particular register value.
0x8104	33028	Slave Device Failure	An unrecoverable event occurred while the server (or slave) was attempting to perform the requested action.

Status		Response	Description
Hex)	(Dec)	_	
0x8105	33029	Acknowledge	Specialized use in conjunction with programming commands: The server (or slave) has accepted the request and is processing it, but a long duration of time will be required to do so. This response is returned so that a timeout in the client (or master) will not occur. The client (or master) can next send a Poll Program Complete message to determine if processing is completed.
0x8106	33030	Slave Device Busy	Specialized use in conjunction with programming commands: The server (or slave) is engaged in processing a long–duration program command. The client (or master) should retransmit the message later when the server (or slave) is free.
0x8107	33031	Negative Acknowledge	Specialized use in conjunction with programming commands: The request attempts to initiate a program function that is not supported by the server (slave).
0x8108	33032	Memory Parity Error	Specialized use in conjunction with function codes 20 and 21 and reference type 6, indicating that the extended file area did not pass a consistency check.
0x810A	33034	Gateway Path Unavailable	Specialized use in conjunction with gateways, indicates that the gateway was unable to allocate an internal communication path from the input port to the output port for processing the request. Usually means that the gateway is misconfigured or overloaded.
0x810B	33035	Gateway Target Device Failed to Respond	Specialized use in conjunction with gateways, indicates that no response was obtained from the target device. Usually means that the device is not present on the network.

The preceding MODBUS exception response codes are derived from the *MODBUS Application Protocol Specification V1.1b* as distributed by the Modbus Organization, Inc. at http://www.Modbus-IDA.com.

# Appendix D Email Detected Error Response Codes

#### **Electronic Mail Notification Service Detected Error Response Codes**

#### **SMTP Codes**

The following codes are available only on the Unity Pro DTM and web page diagnostic screens for the electronic mail notification service:

Code (hexadecimal)	Description	
16#5100	Internal error detected	
16#5101	SMTP component not operational	
16#5102	Mail header not configured	
16#5103	Invalid mail header value detected (1, 2, or 3)	
16#5104	Cannot connect to SMTP server	
16#5105	Error detected during transmitting content of email body to SMTP server	
16#5106	Closing SMTP connection with the server returned a detected error message	
16#5107	SMTP HELO request unsuccessful	
16#5108	SMTP MAIL request unsuccessful — SMTP server may require authentication	
16#5109	SMTP RCPT request unsuccessful	
16#510A	No recipient accepted by the SMTP server	
16#510B	SMTP DATA request unsuccessful	
16#510C	Send email request contains an invalid length	
16#510D	Authentication unsuccessful	
16#510E	A reset component request was received while the connection was open	

# Glossary

# D

#### DTM

(device type manager) A DTM is a device driver running on the host PC. It provides a unified structure for accessing device parameters, configuring and operating the devices, and diagnosing events. DTMs can range from a simple Graphical User Interface for setting device parameters to a highly sophisticated application capable of performing complex real-time calculations for diagnosis and maintenance purposes. In the context of a DTM, a device can be a communications module or a remote device on the network.

#### Е

#### **Explicit Messaging**

TCP/IP-based messaging for Modbus TCP and EtherNet/IP. It is used for point-to-point, client/server messages that include both data—typically unscheduled information between a client and a server—and routing information. In EtherNet/IP, Explicit Messaging is considered Class 3 type messaging, and can be connection-based or connectionless.

# R

#### RPI

(requested packet interval) The time period between cyclic data transmissions requested by the Scanner. EtherNet/IP devices will publish data at the rate specified by the RPI assigned to them by the Scanner. Modbus TCP devices will receive message requests from the Scanner at each RPI.

### Т

#### trap

A trap is an event directed by an SNMP agent that indicates either:

- a change has occurred in the status of an agent, or
- an unauthorized SNMP manager device has attempted to get data from, or change data on, an SNMP agent

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